



**Charles-Augustin COULOMB - A geotechnical tribute**  
**Paris, september 25 & 26, 2023**

# Computational Limit Analysis and Extensions

**K. Krabbenhoft**  
**Optum Computational Engineering**

# **Outline**

**Introduction**

**The conventional FE approach**

**The Optum approach**

**Examples**

**Future developments**

# Introduction



## Question:

What is the maximum magnitude of loading that the foundation can sustain?

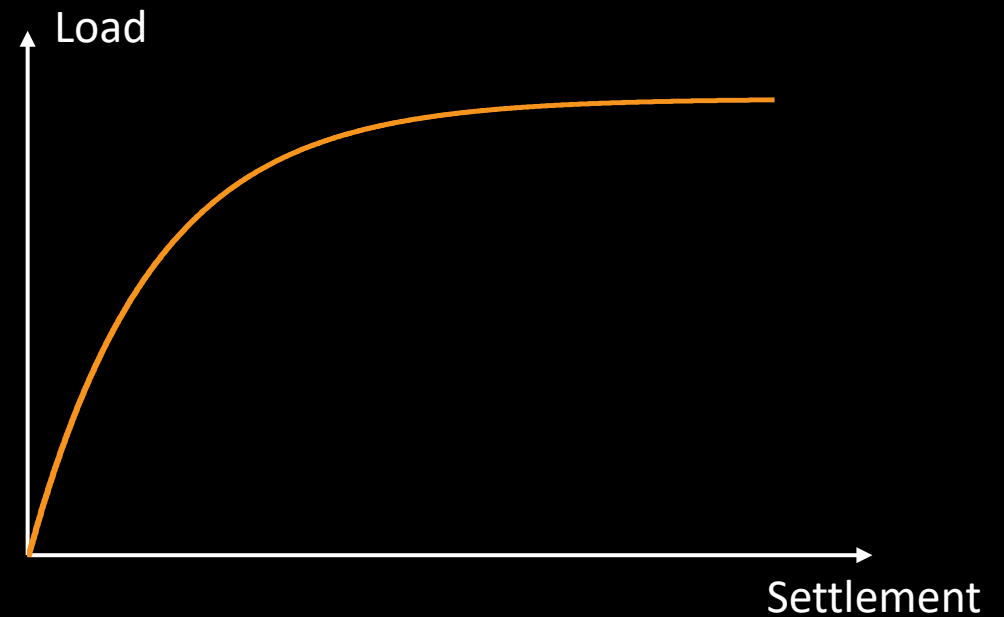


# Introduction



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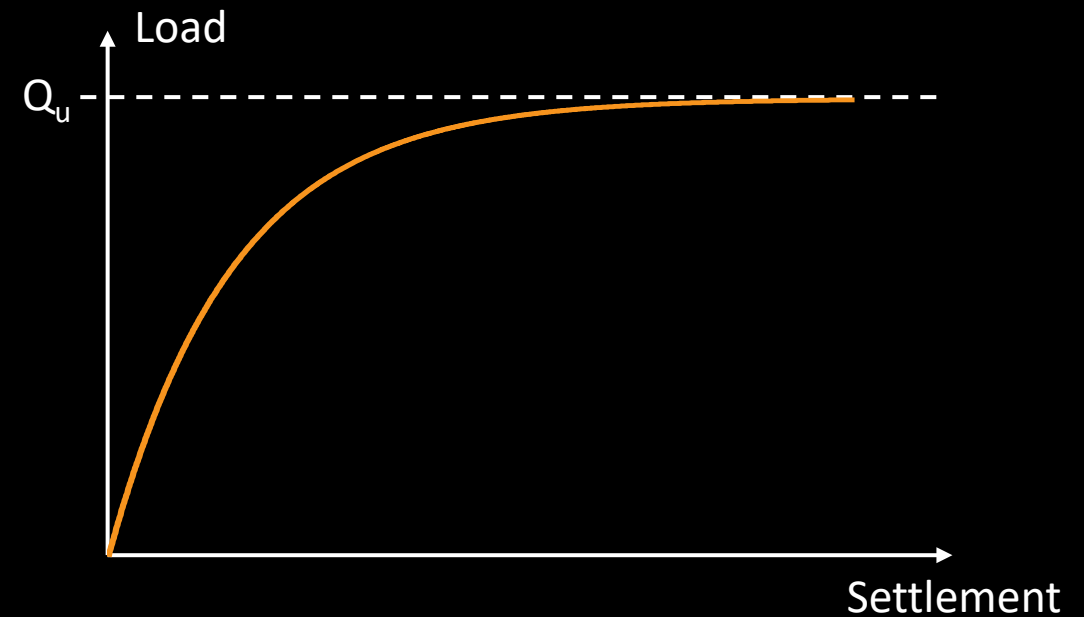


# Introduction



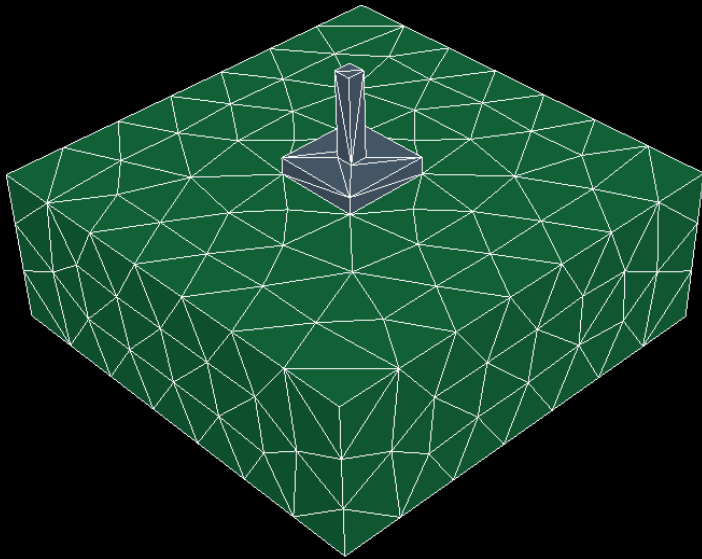
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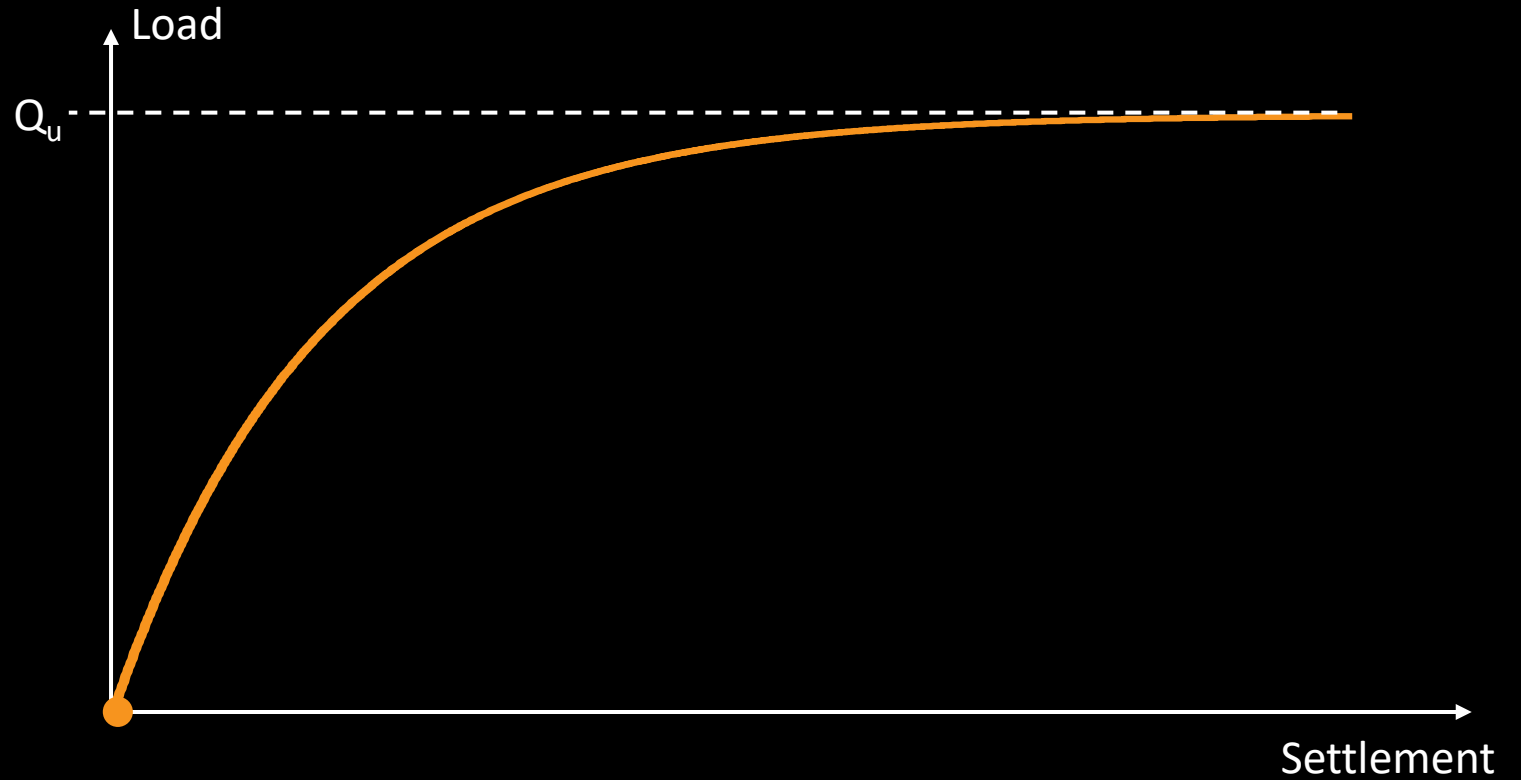




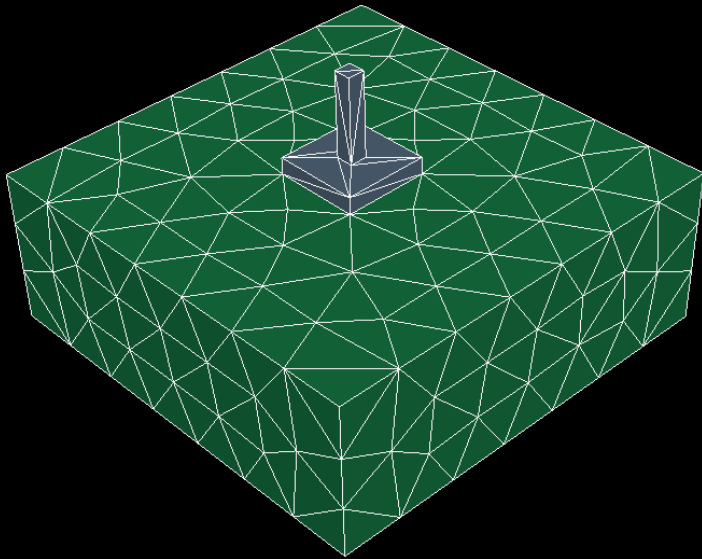
# The conventional FE approach



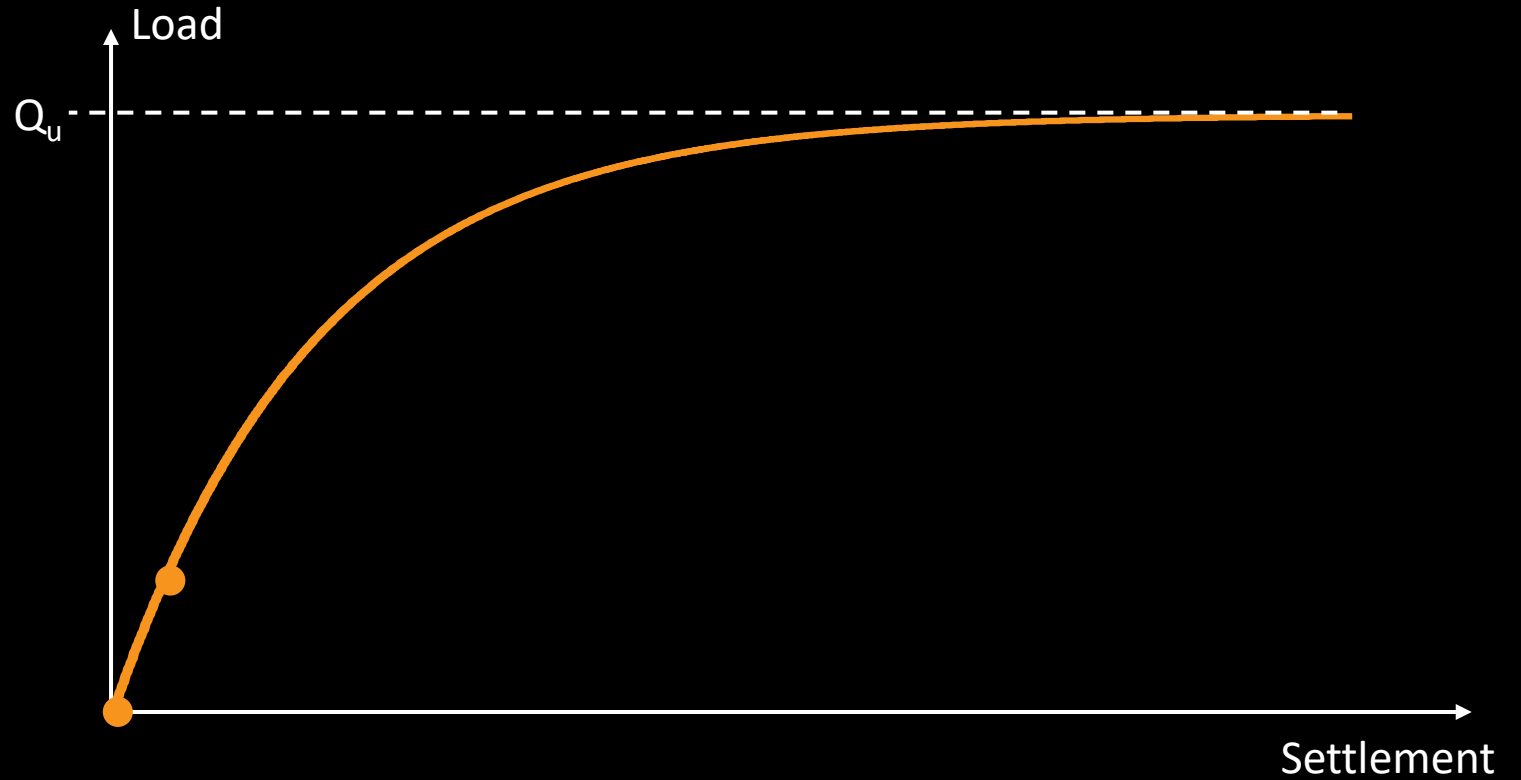
Increase load to failure:



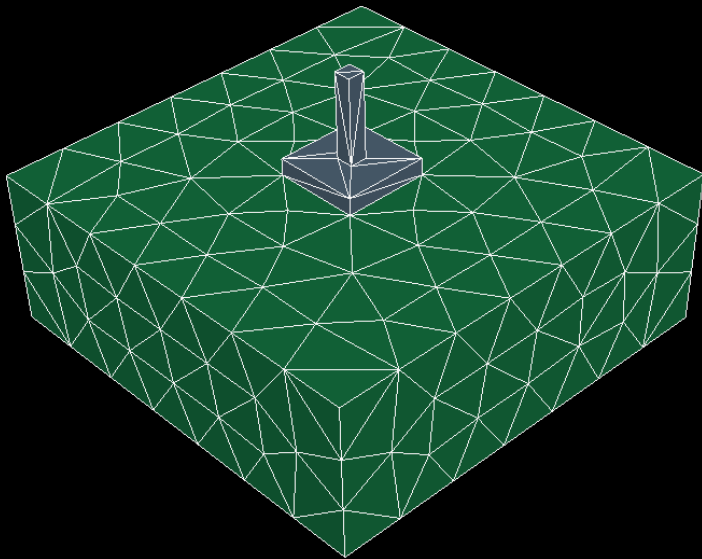
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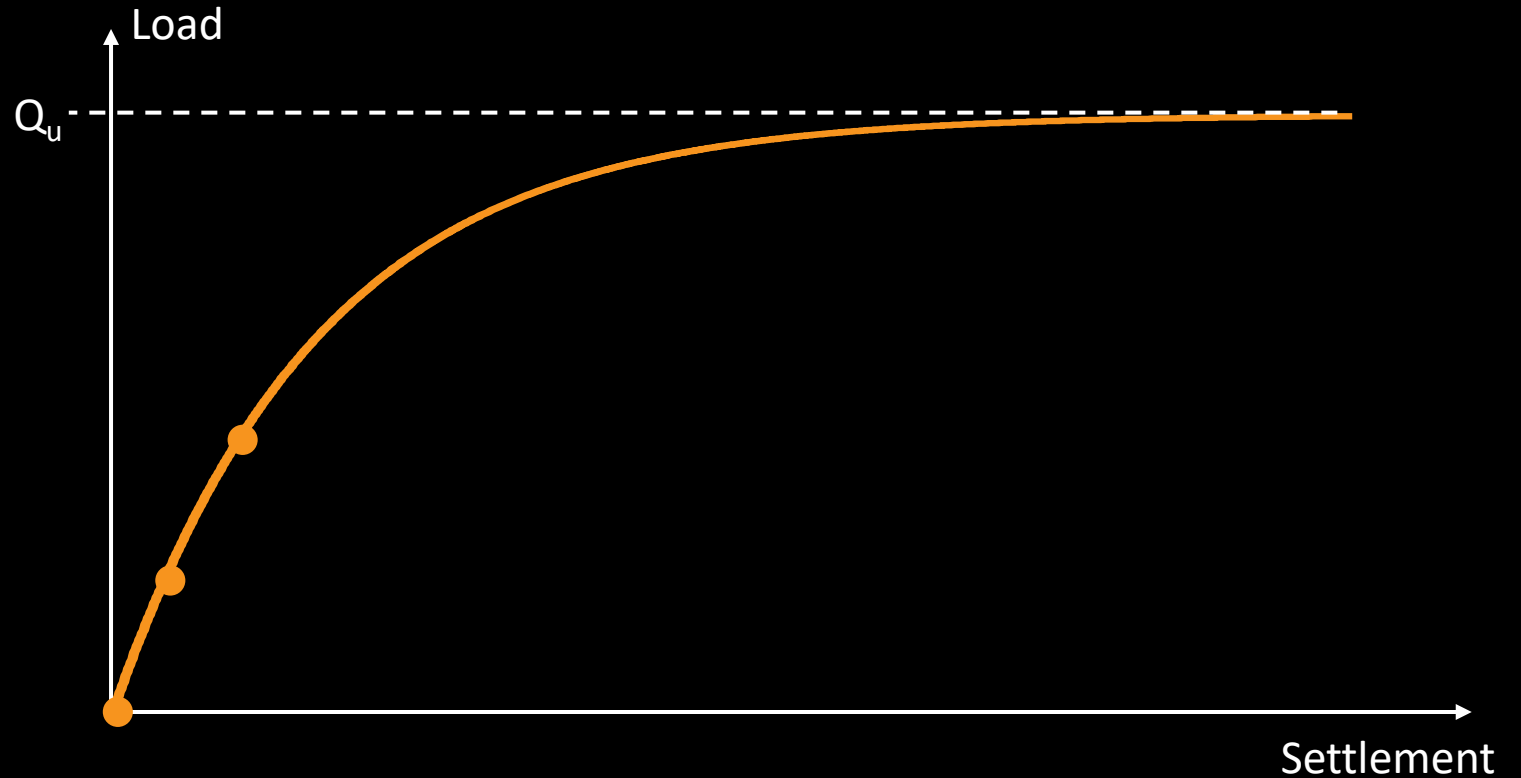
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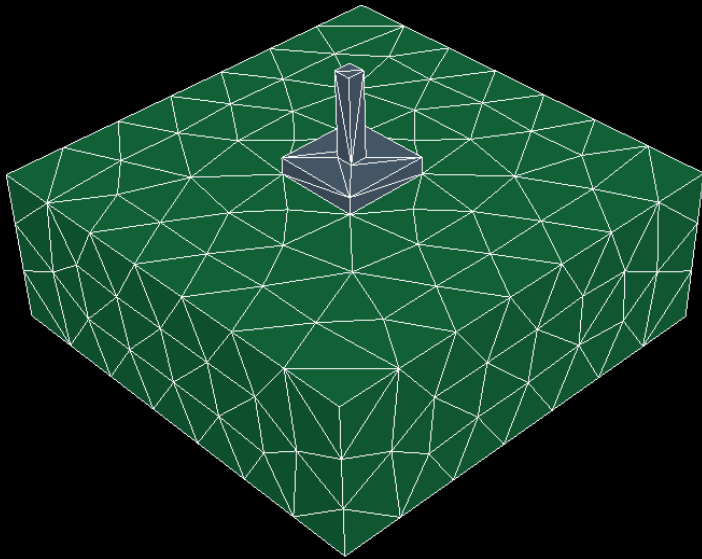


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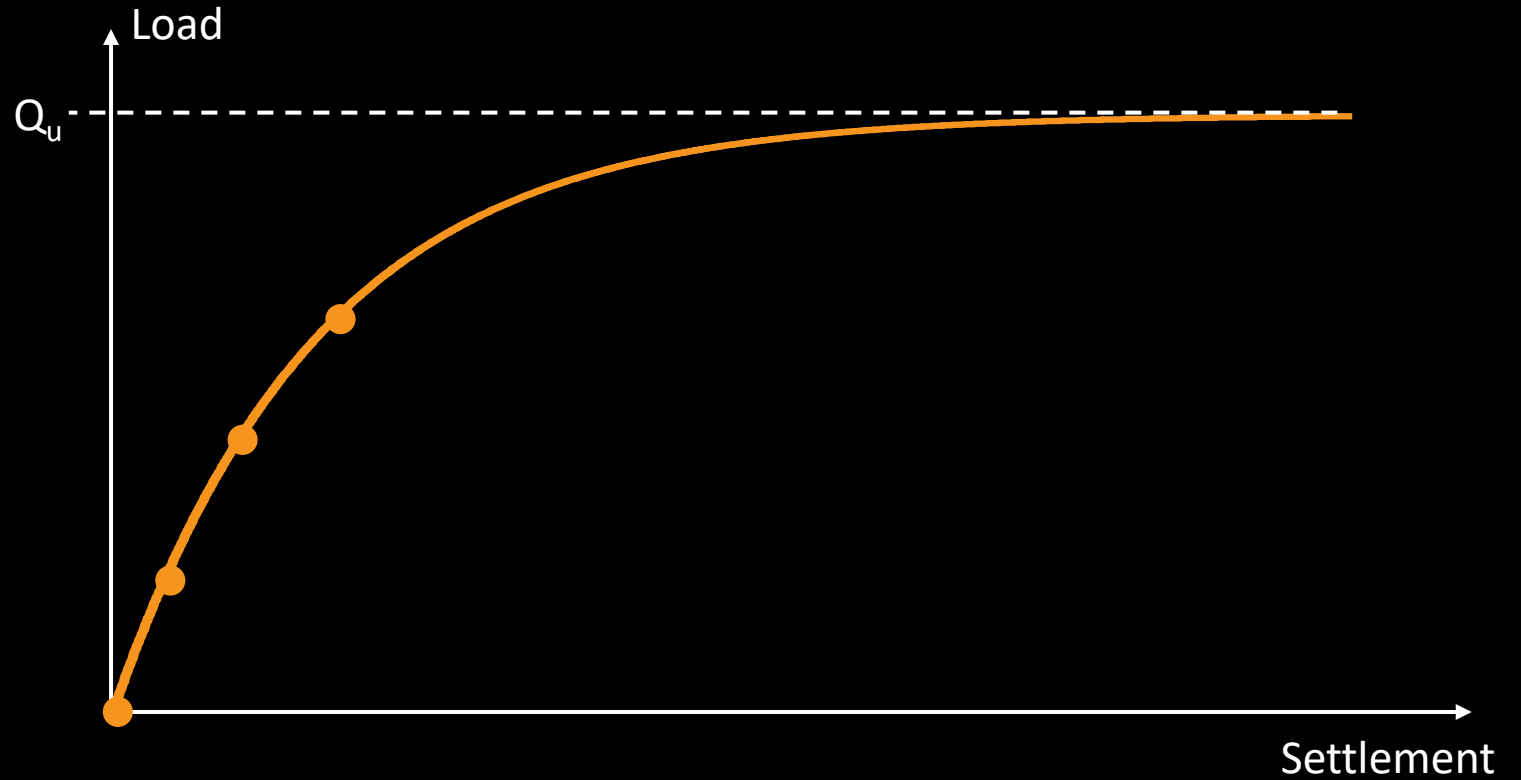




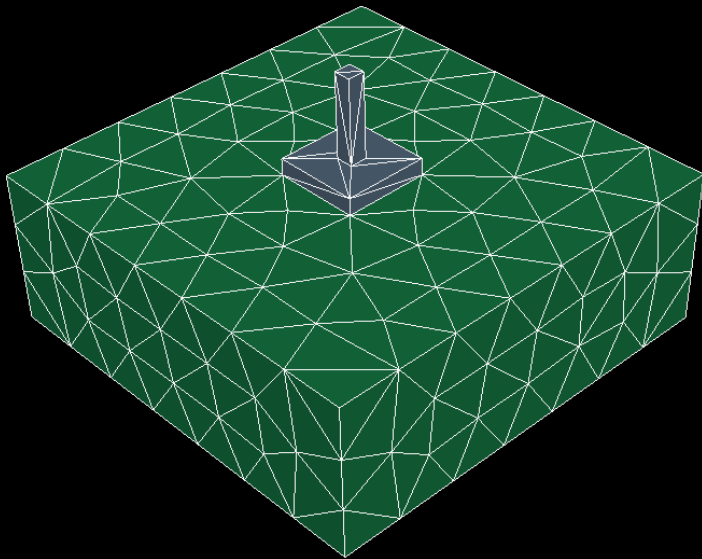
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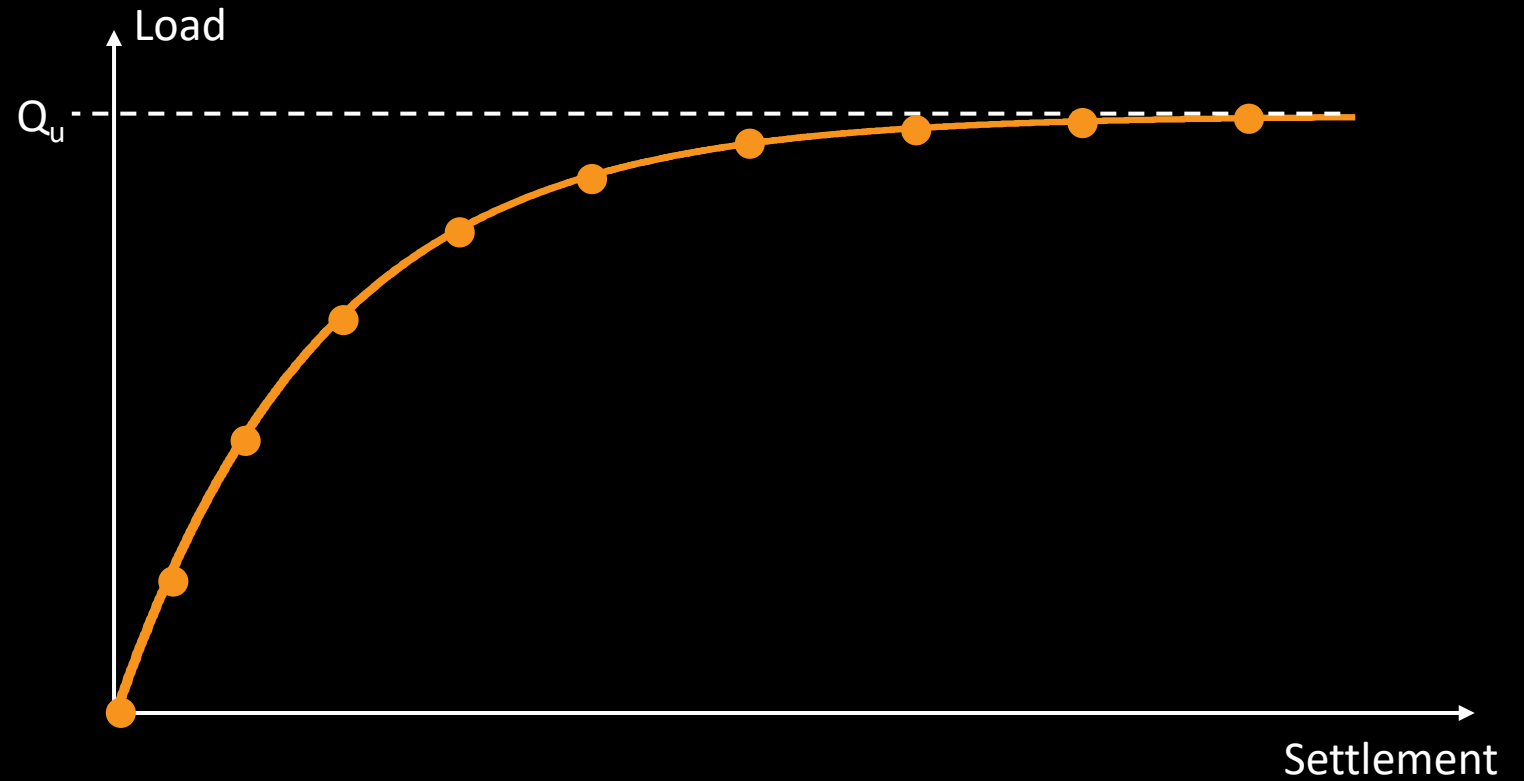
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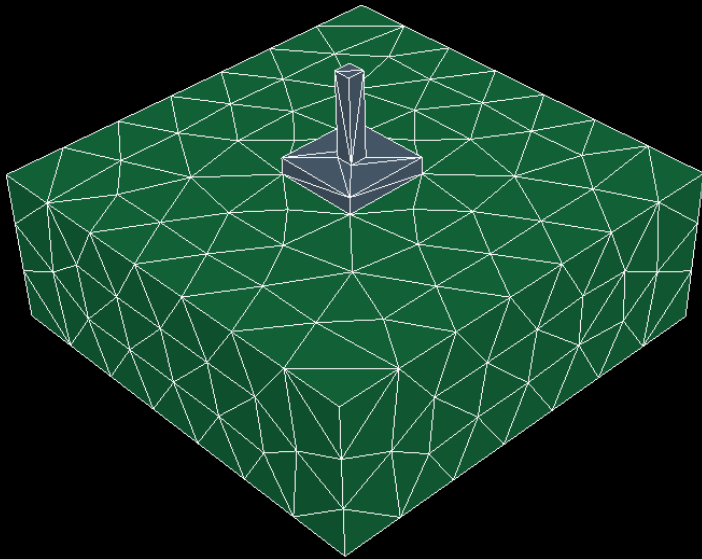
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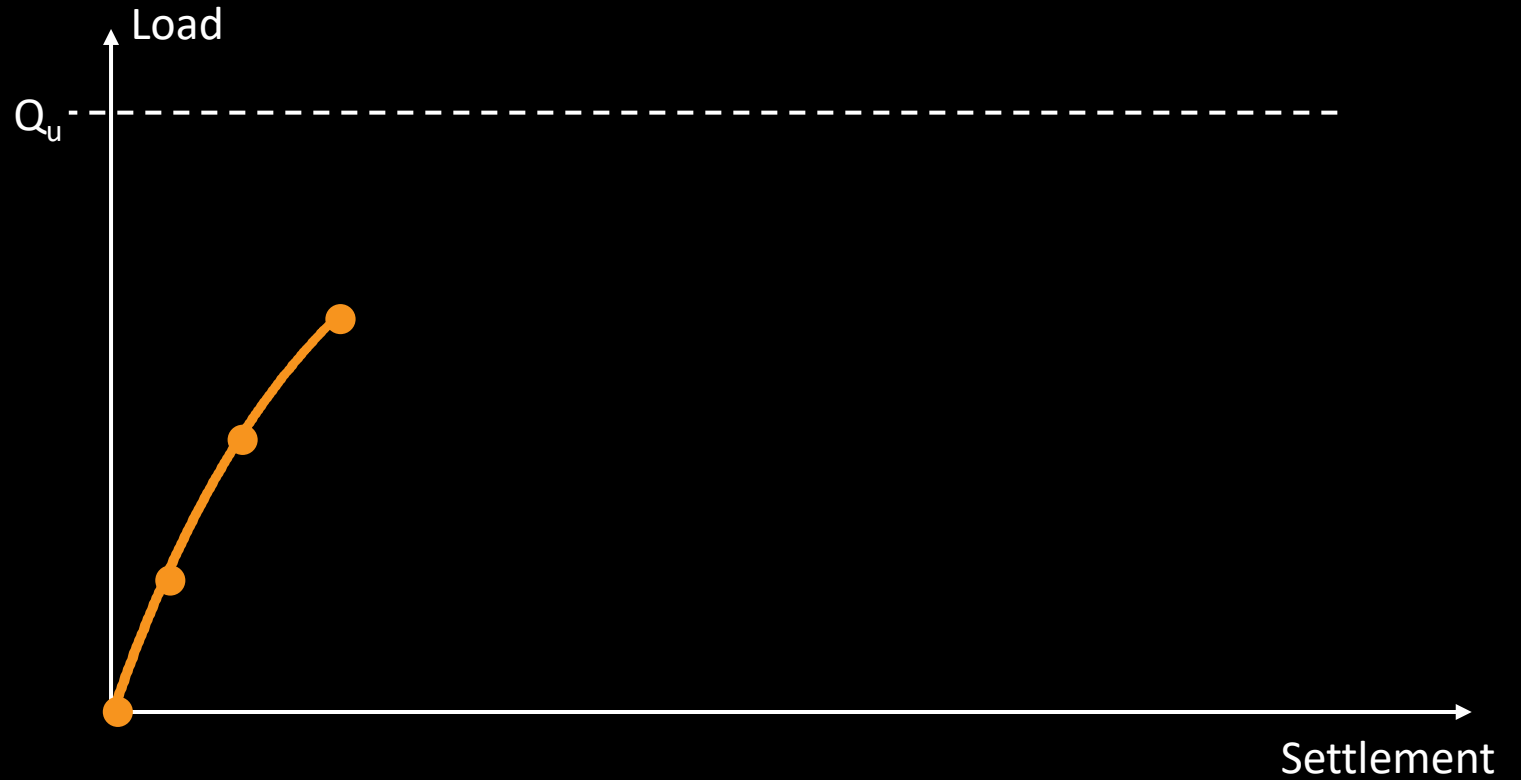
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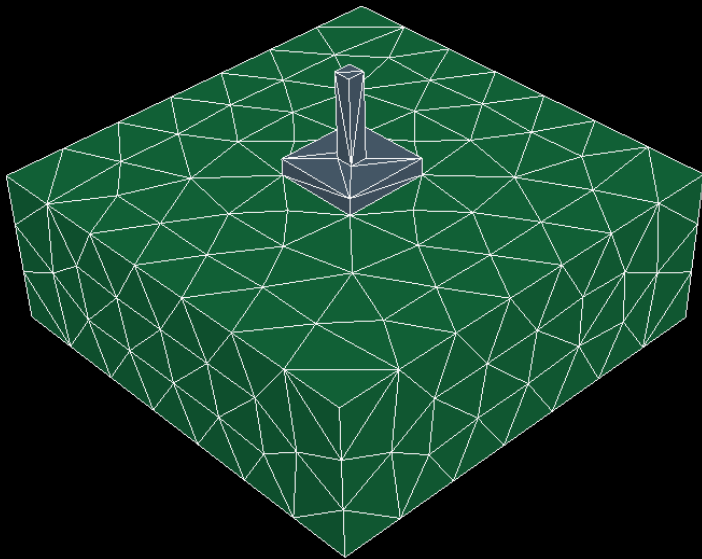


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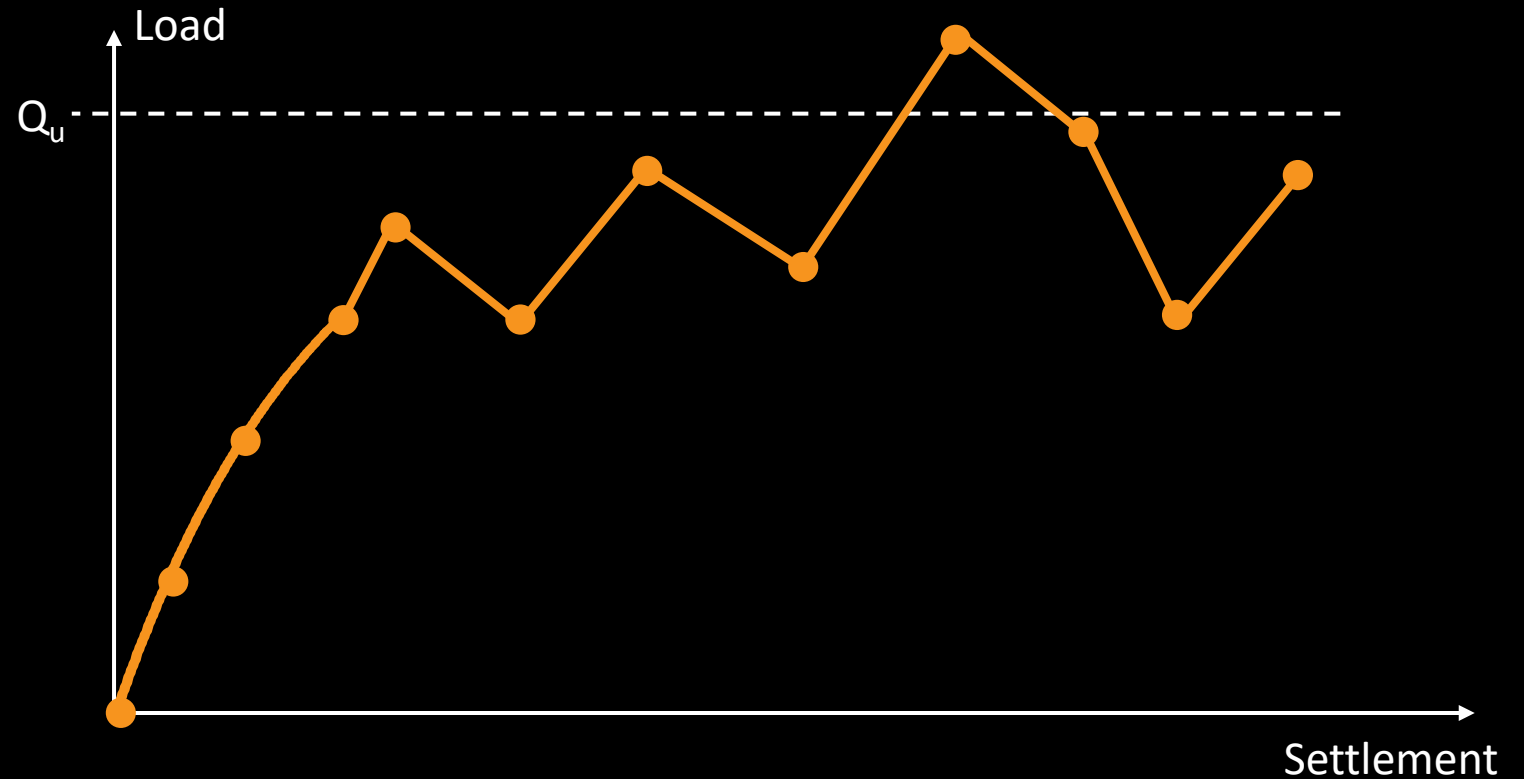




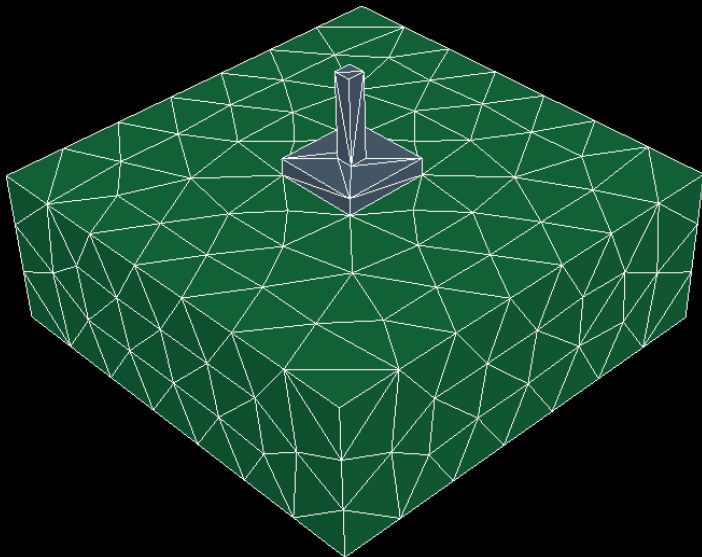
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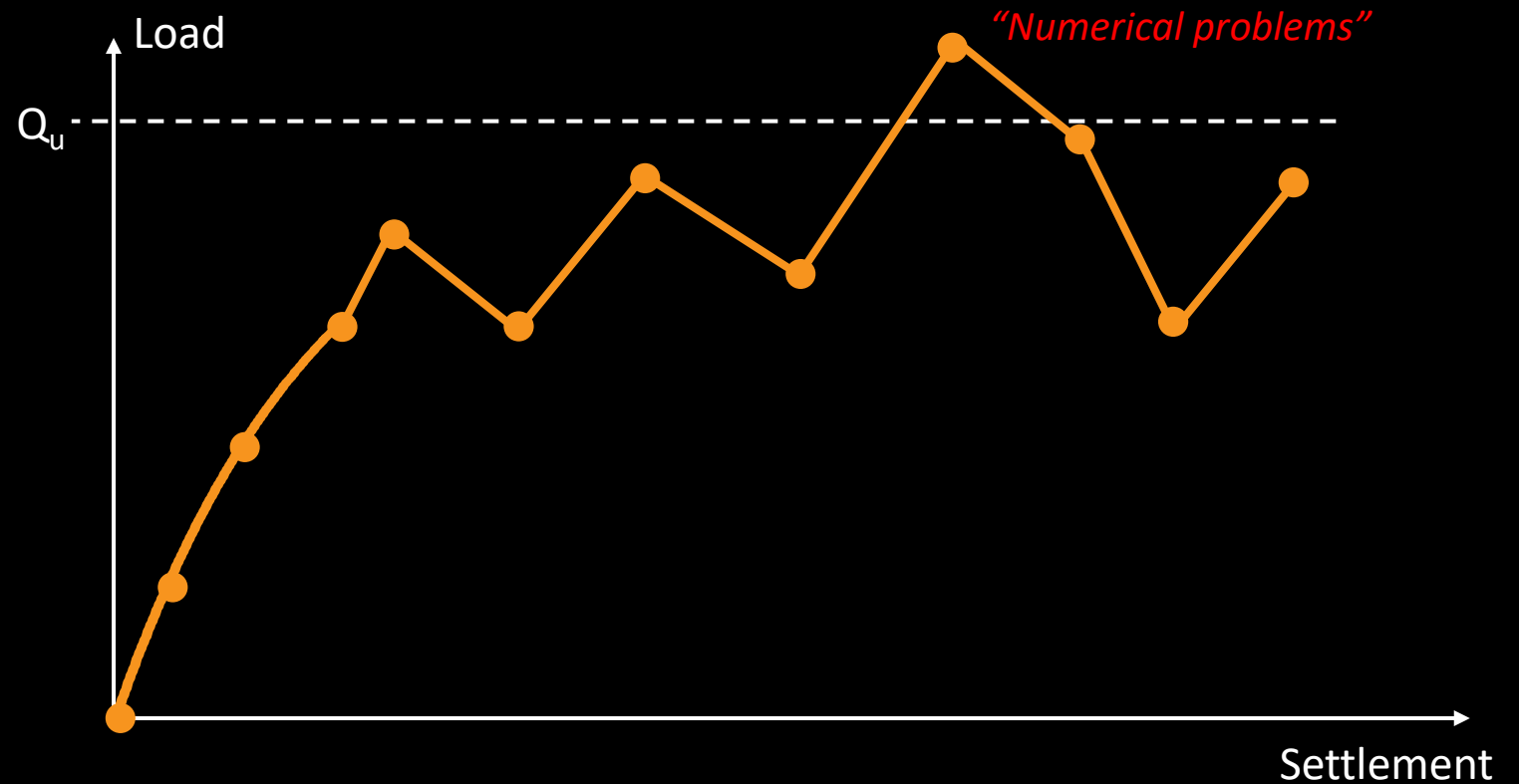
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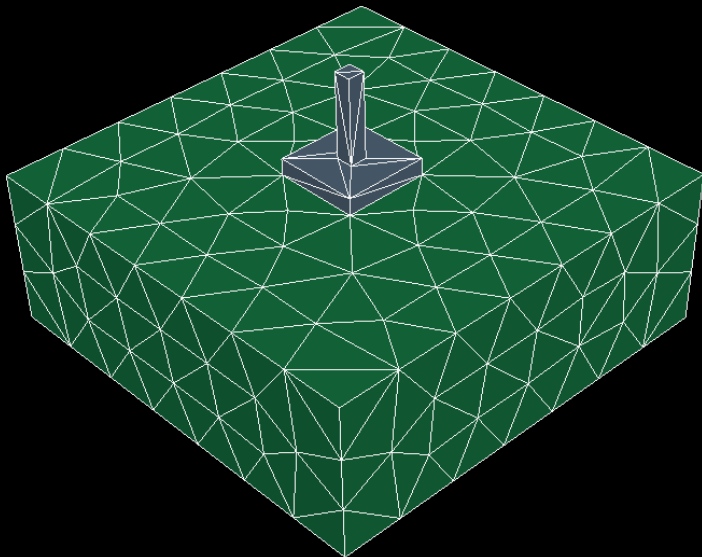


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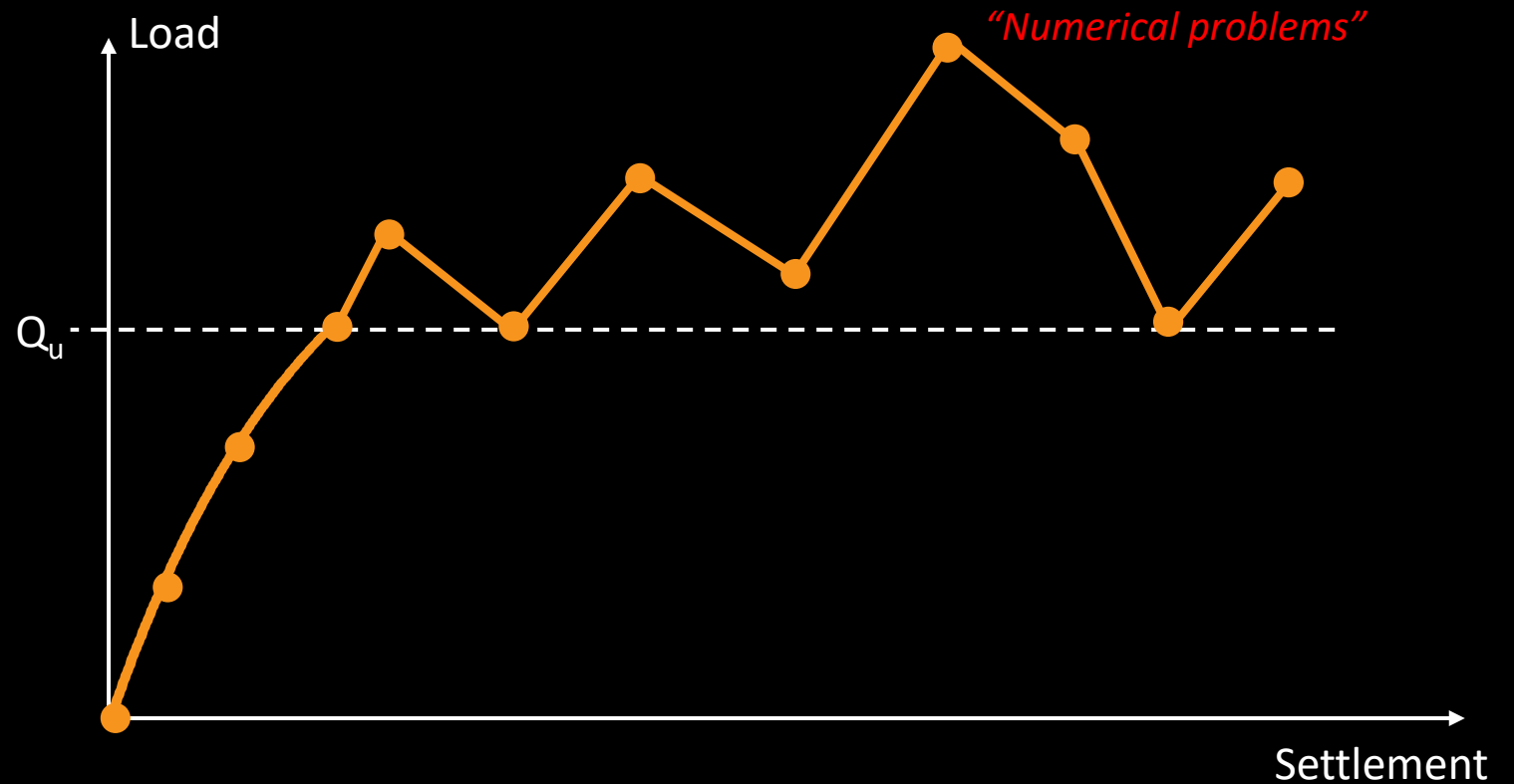


What is the limit load?

# The conventional FE approach



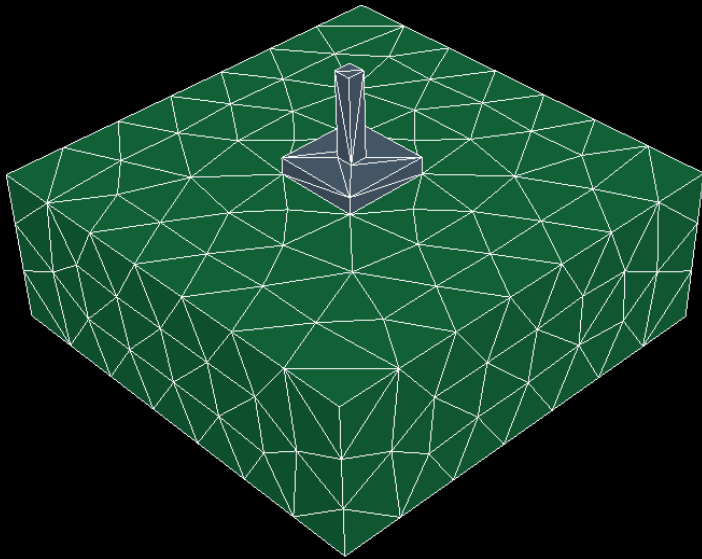
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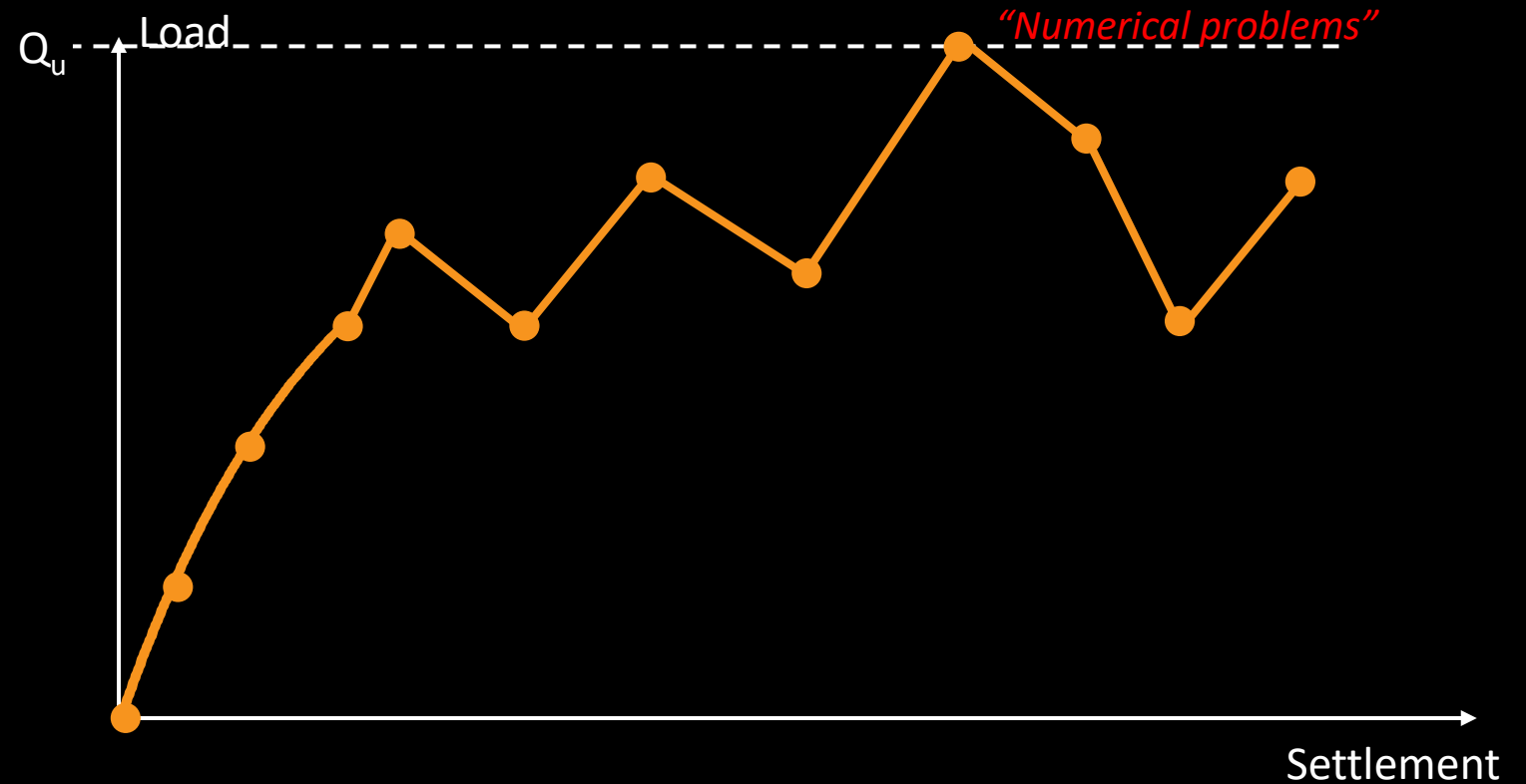
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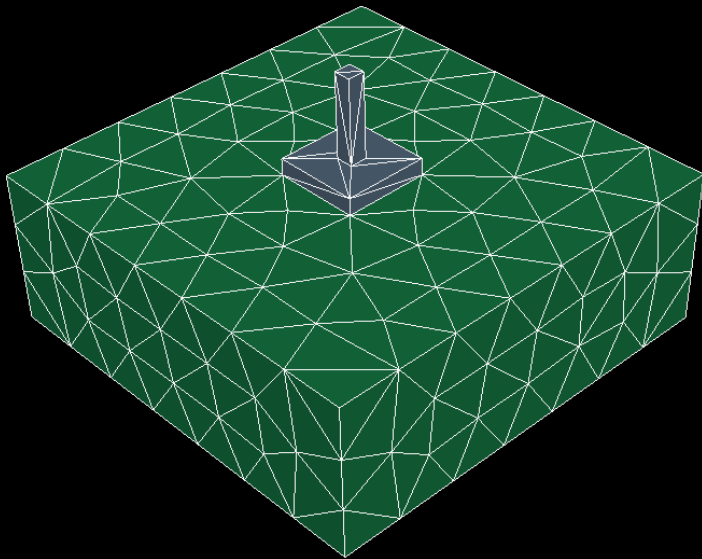


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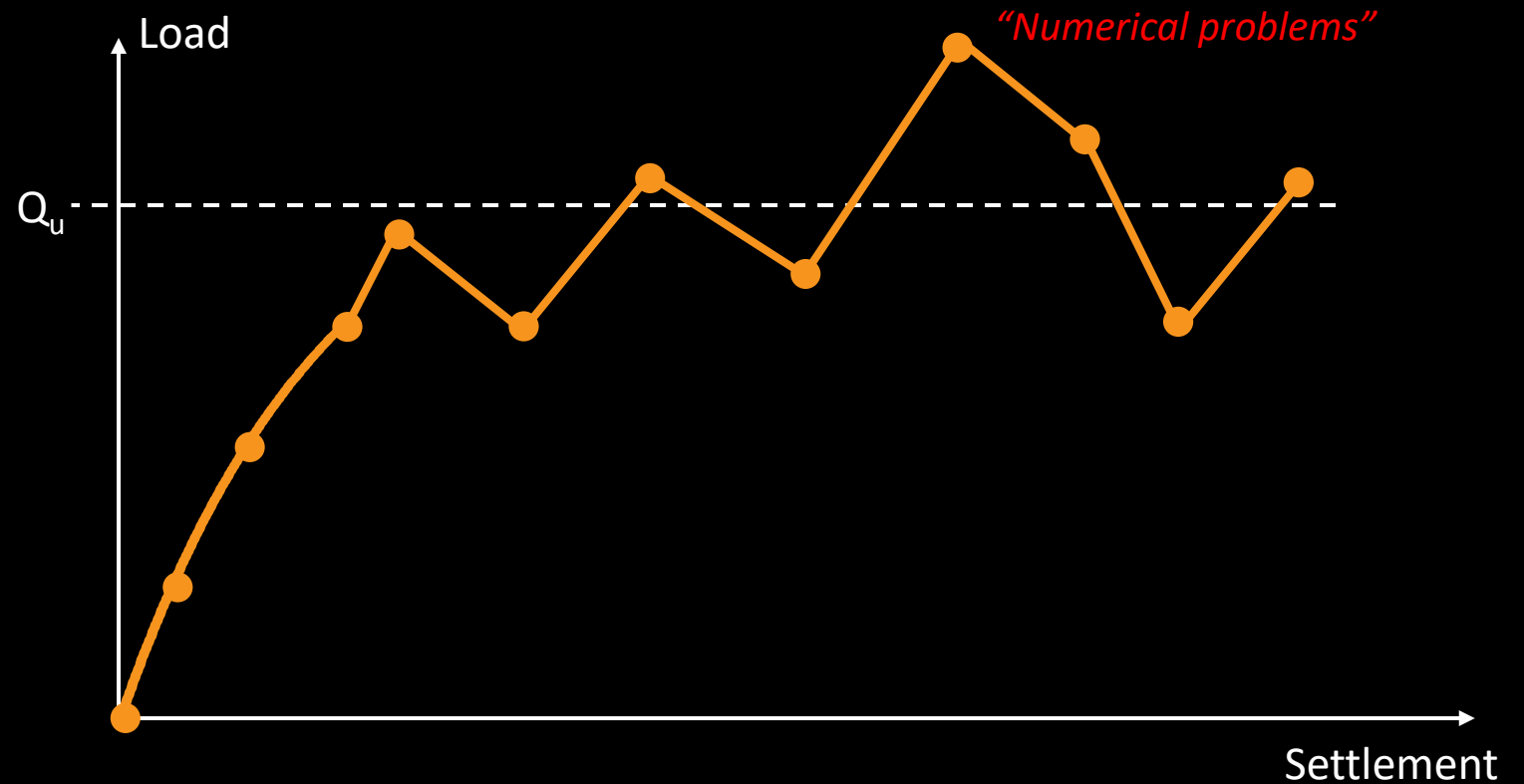


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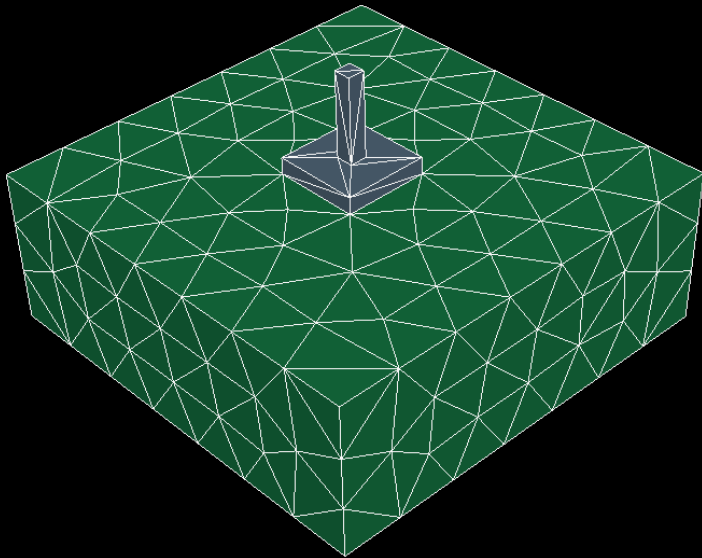


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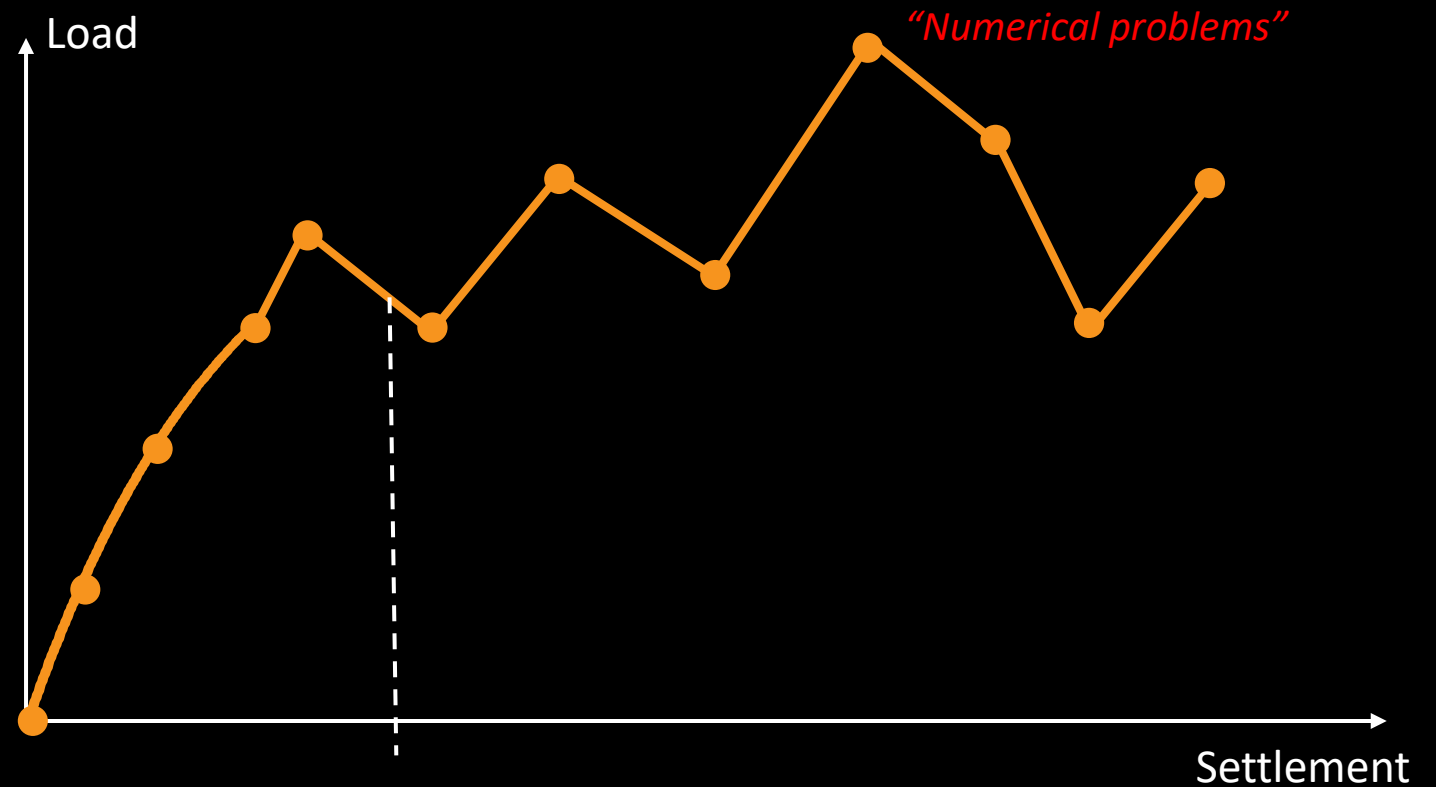


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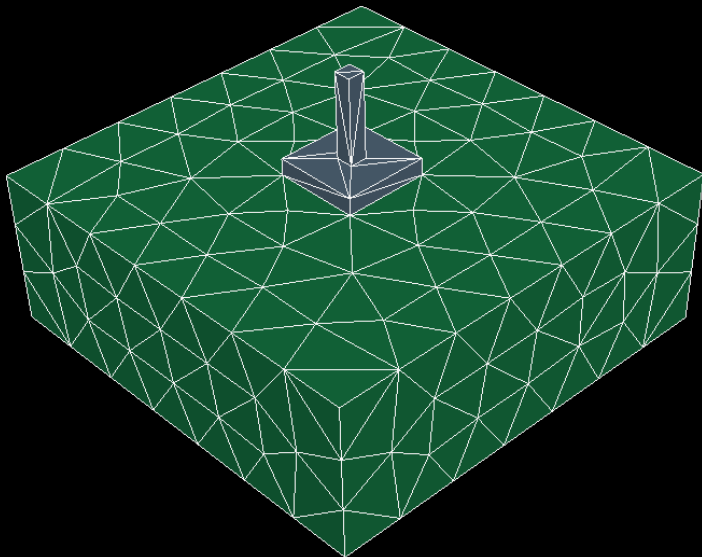
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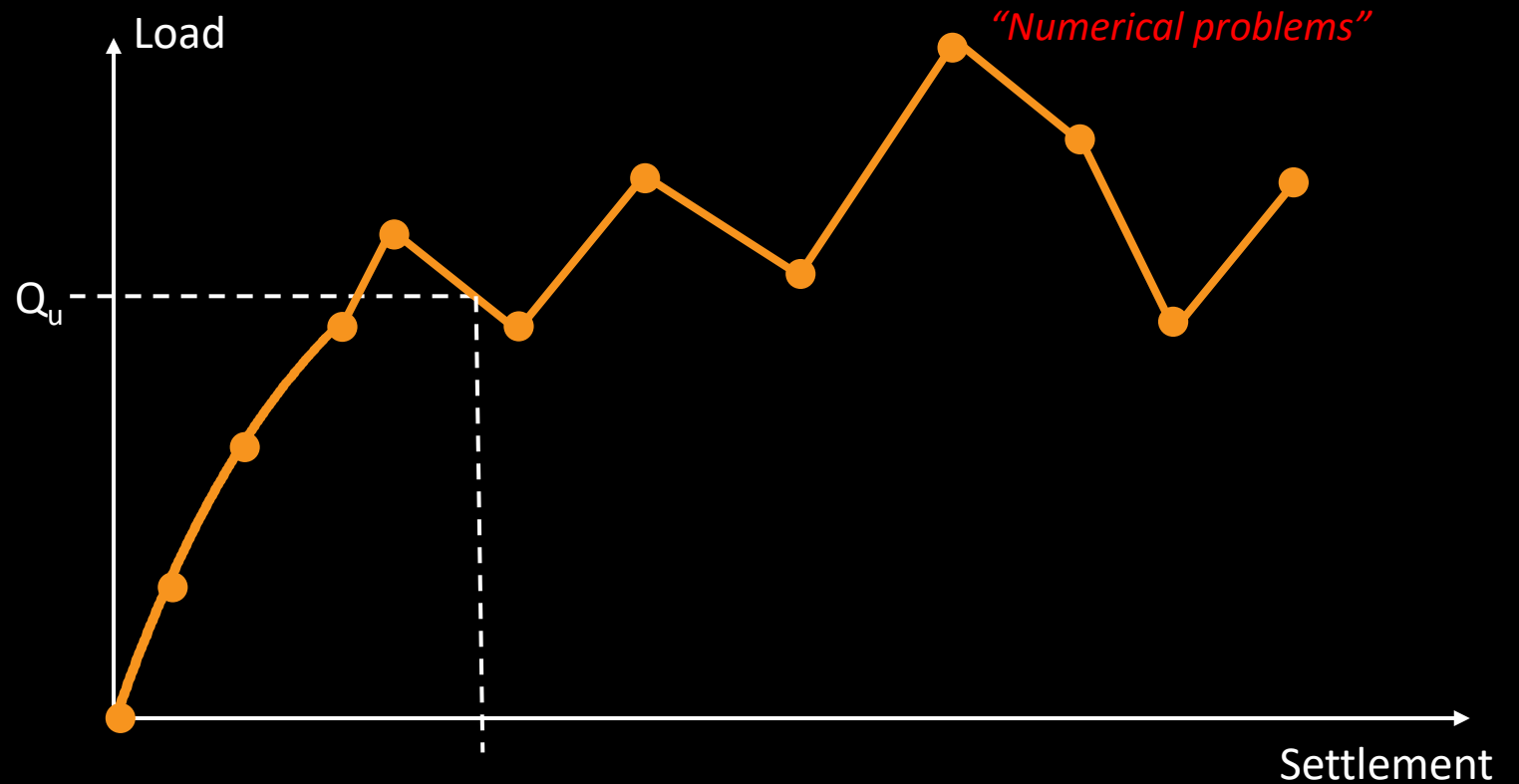
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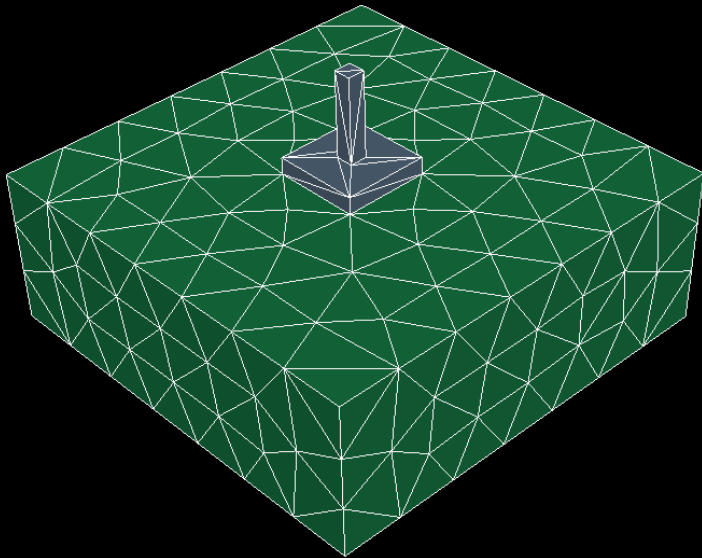


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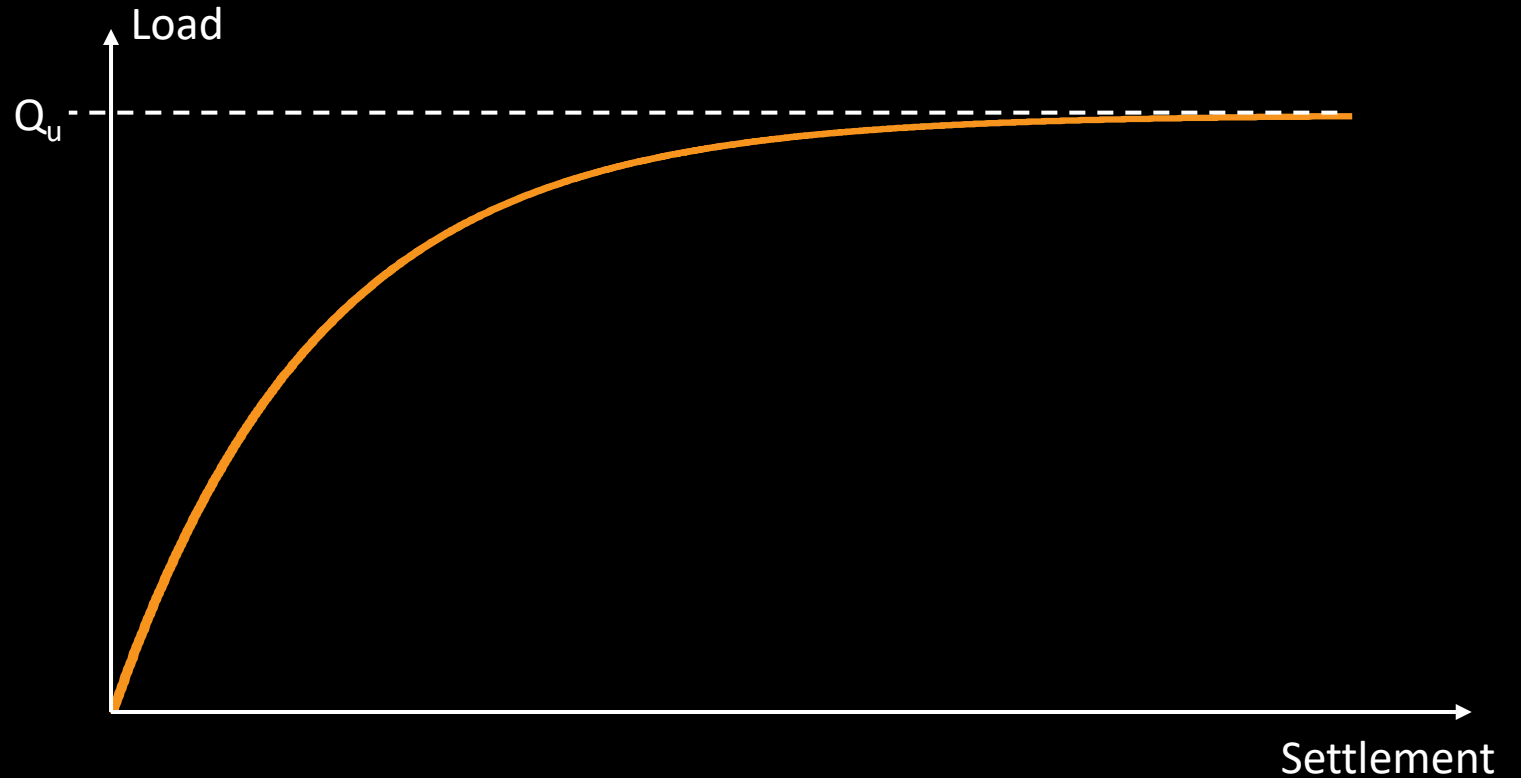


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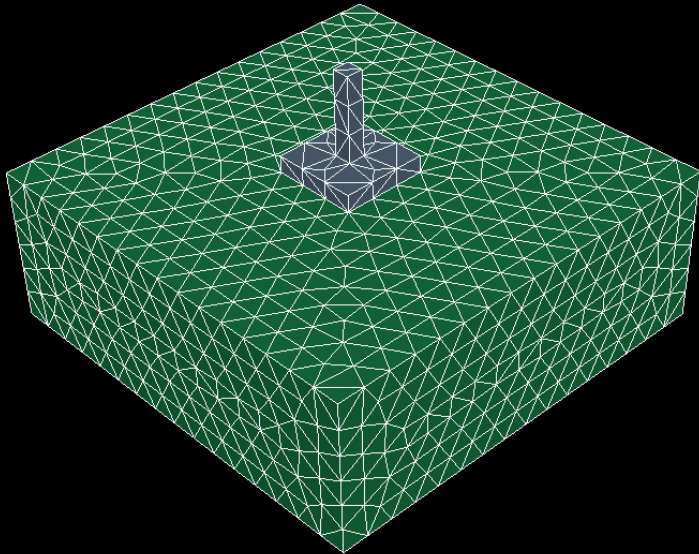


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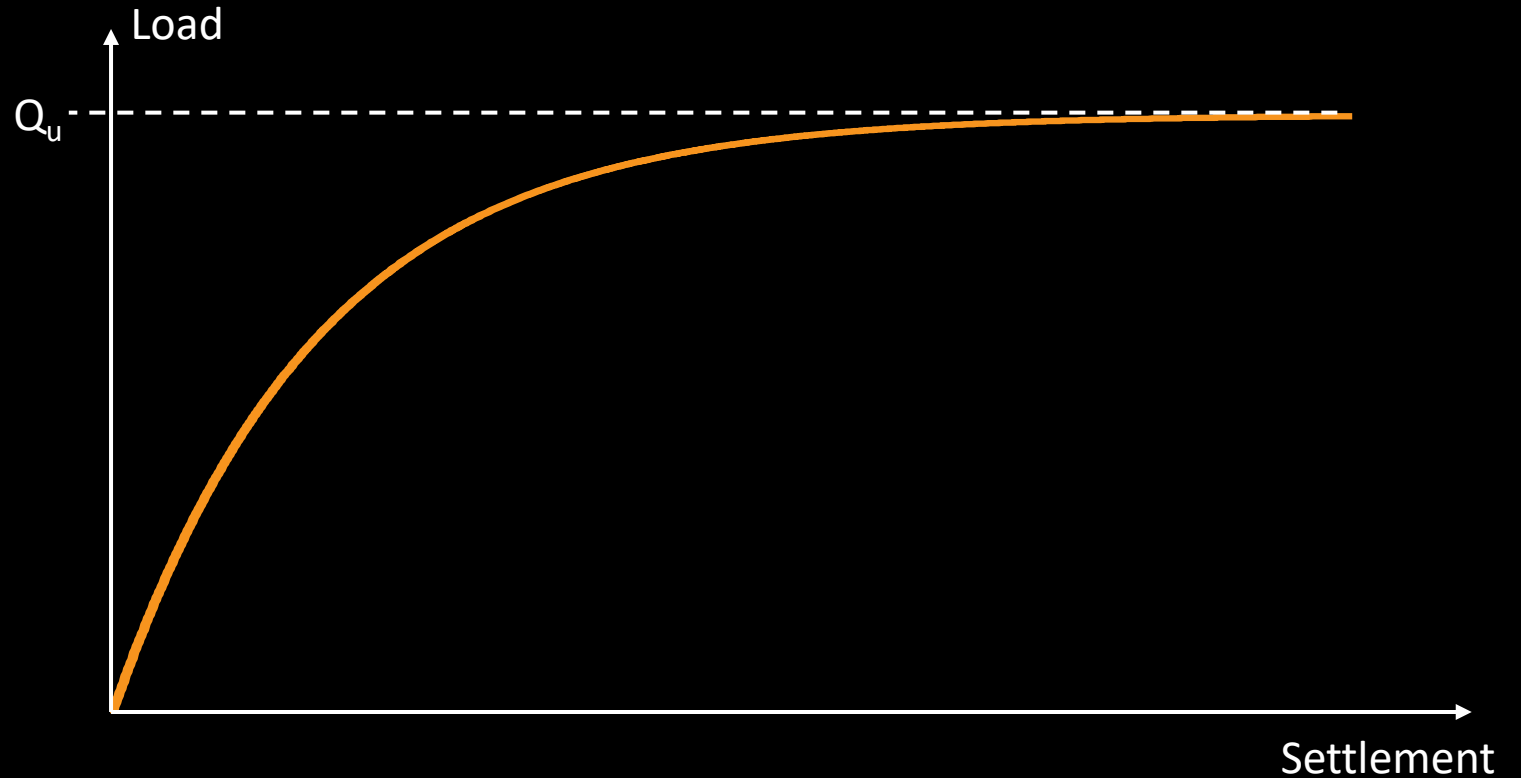


How accurate is the solution?

# The conventional FE approach



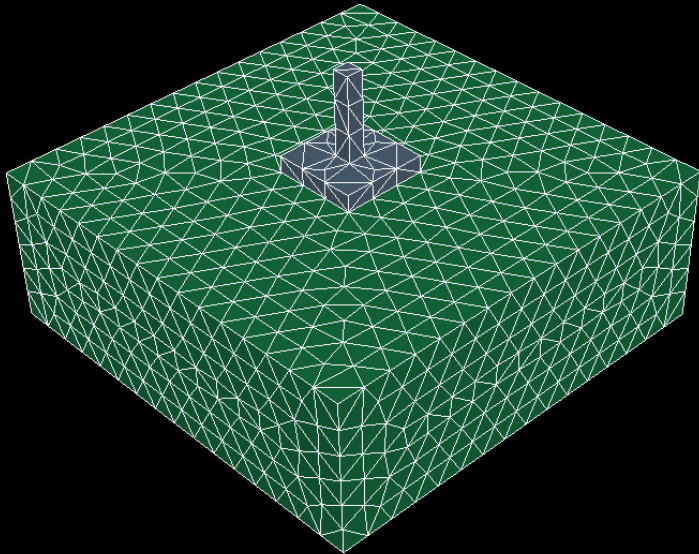
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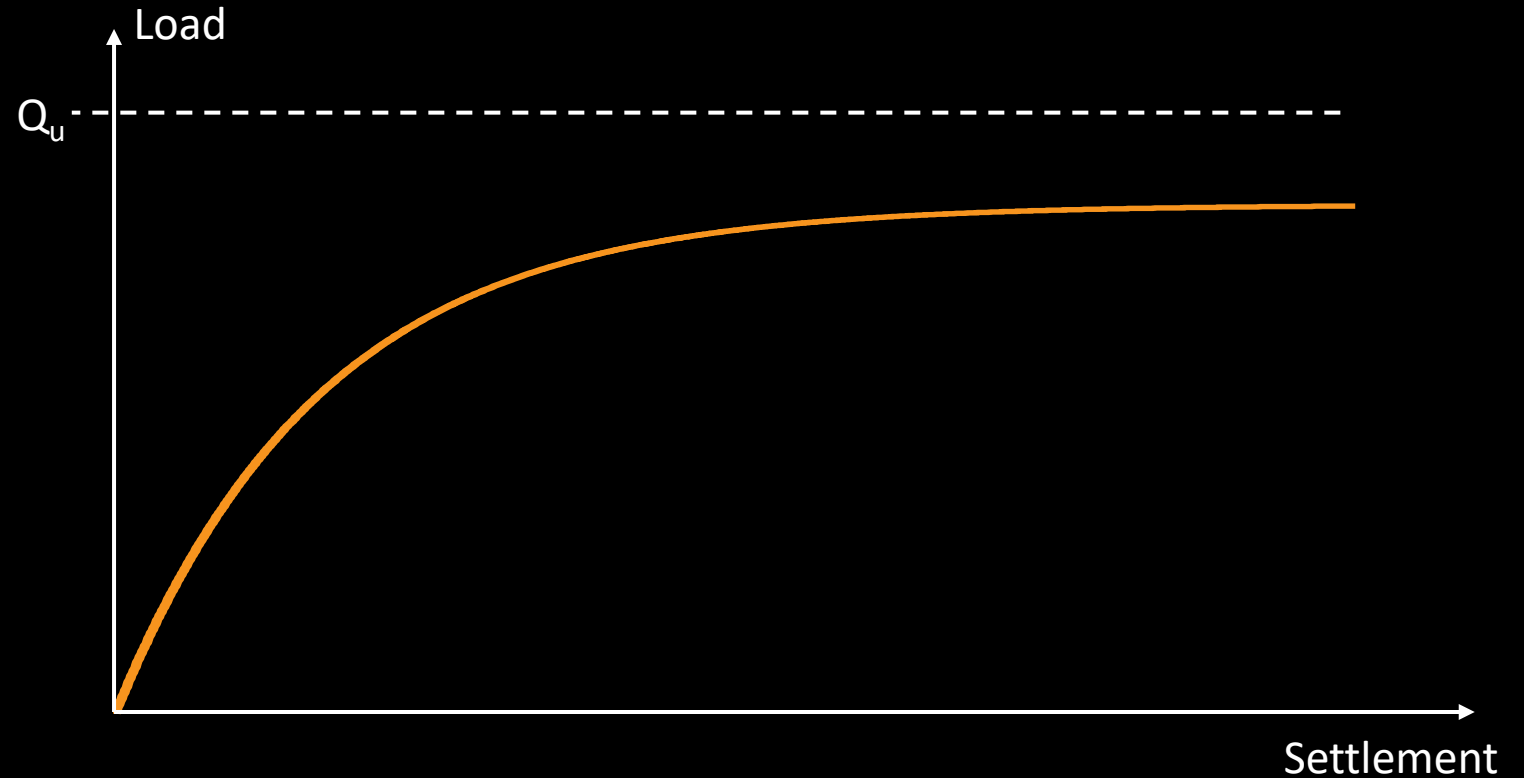
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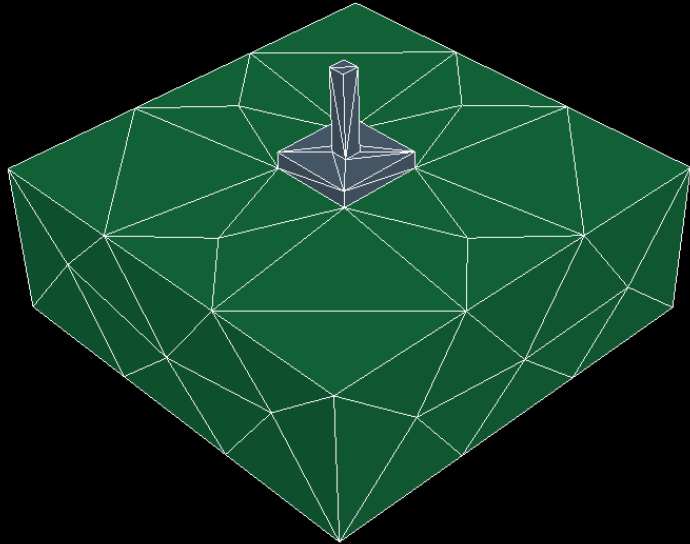


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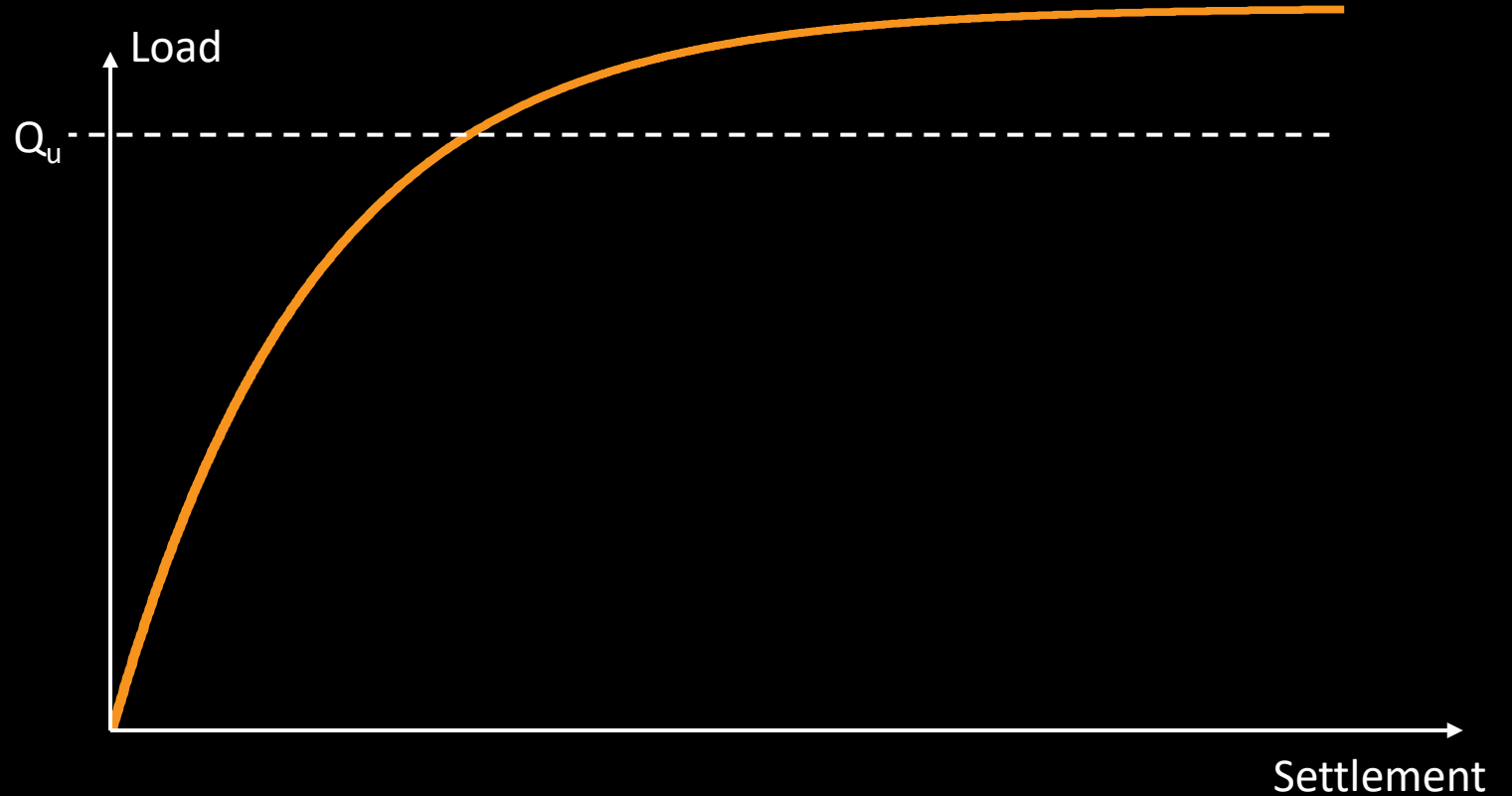


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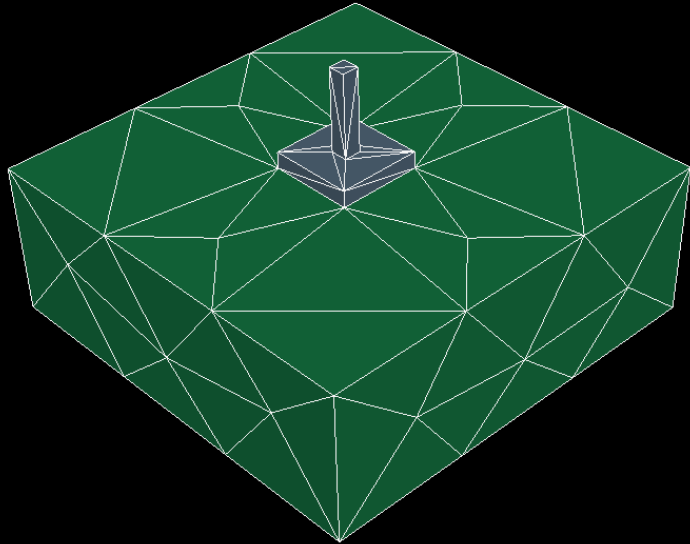


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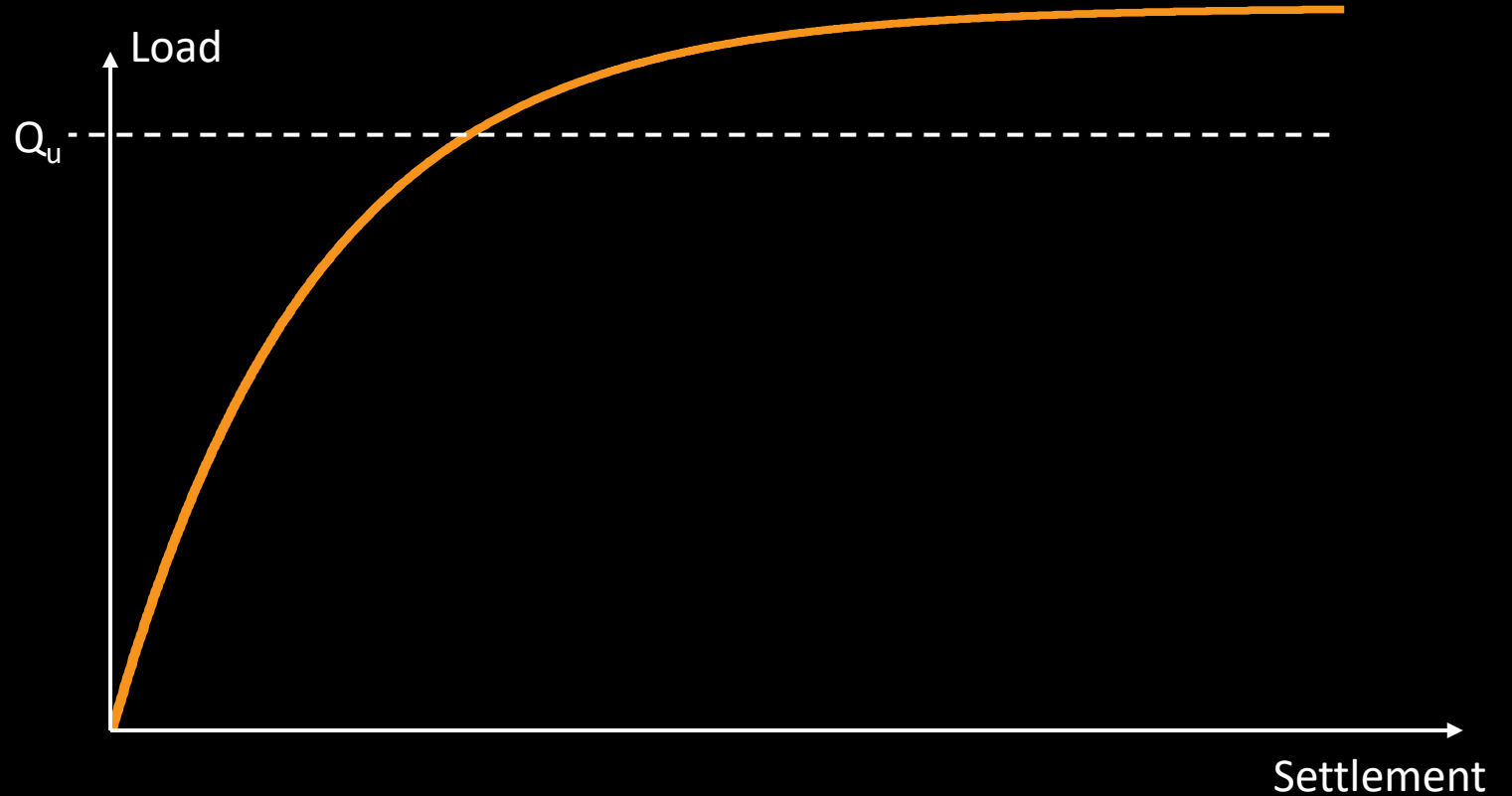


How accurate is the solution?

# The conventional FE approach



Increase load to failure:



Is there a better way?



# The Optum approach



## *E S S A I*

*Sur une application des règles de Maximis & Minimis  
à quelques Problèmes de Statique, relatifs à  
l'Architecture.*

Par M. COULOMB, Ingénieur du Roi.

### *I N T R O D U C T I O N.*

C E Mémoire est destiné à déterminer, autant que le mélange du Calcul & de la Physique peuvent le permettre, l'influence du frottement & de la cohésion, dans quelques problèmes de Statique. Voici une légère analyse des différens objets qu'il contient.

Coulomb (1736-1806)

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Euler (1707-1783)

*Since the fabric of the universe is most perfect and the work of a most wise Creator, nothing whatsoever takes place in the universe in which some relation of maximum or minimum does not appear.*



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Coulomb (1736-1806)

## Variational principles – examples:

- + Fermat's principle (implying Snell's law of refraction)
- + Classical mechanics (Maupertuis, Lagrange, Hamilton)
- + Principle of least action (classical and quantum mechanics)
- + Hilbert's action principle (yielding Einstein's field equations)
- + Mechanics of solids – elastostatics (e.g. Hellinger-Reissner), dynamics, plasticity and much more



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# The Optum approach

## Rigid plasticity (limit analysis)

Equilibrium:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

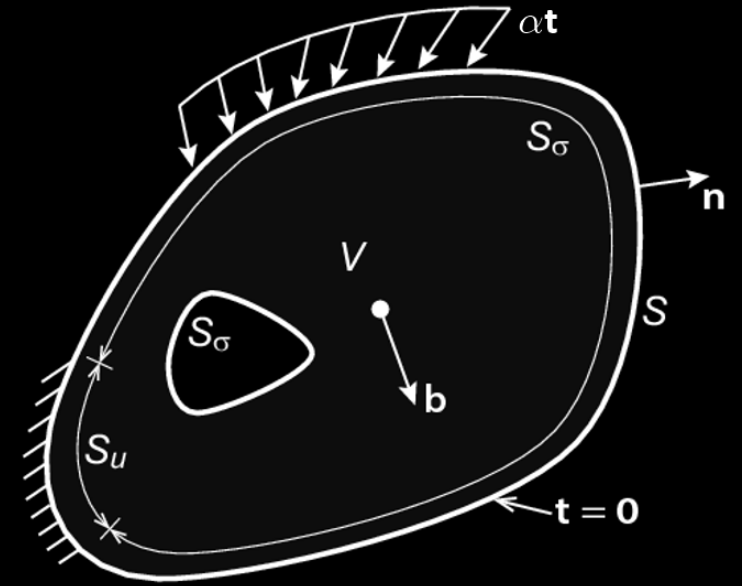
Static BC:  $\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t}$  on  $S_\sigma$

Strain-disp:  $\dot{\boldsymbol{\varepsilon}}^p = \nabla \dot{\mathbf{u}}$

Yield condition:  $F(\boldsymbol{\sigma}) \leq 0$

Flow rule:  $\dot{\boldsymbol{\varepsilon}}^p = \dot{\lambda} \frac{\partial F}{\partial \boldsymbol{\sigma}}$

Complementarity:  $\dot{\lambda} \geq 0, \quad \dot{\lambda} F(\boldsymbol{\sigma}) = 0$



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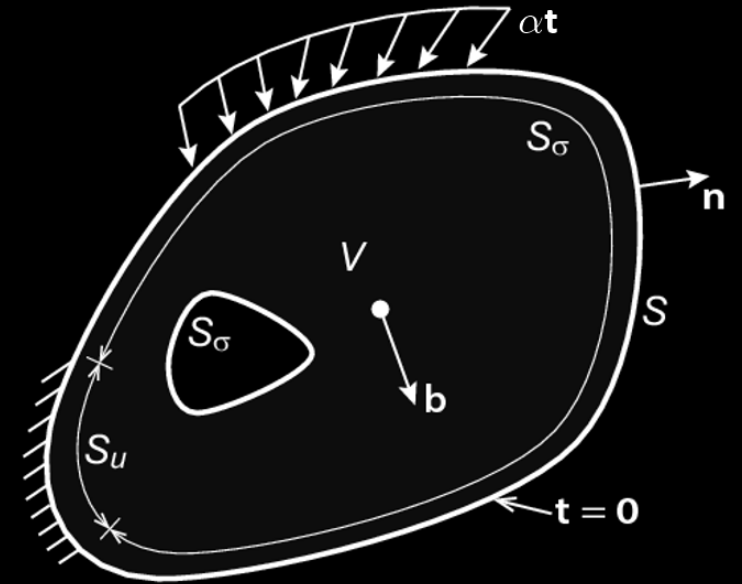
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## Variational principle (lower bound):

maximize  $\alpha$

subject to  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

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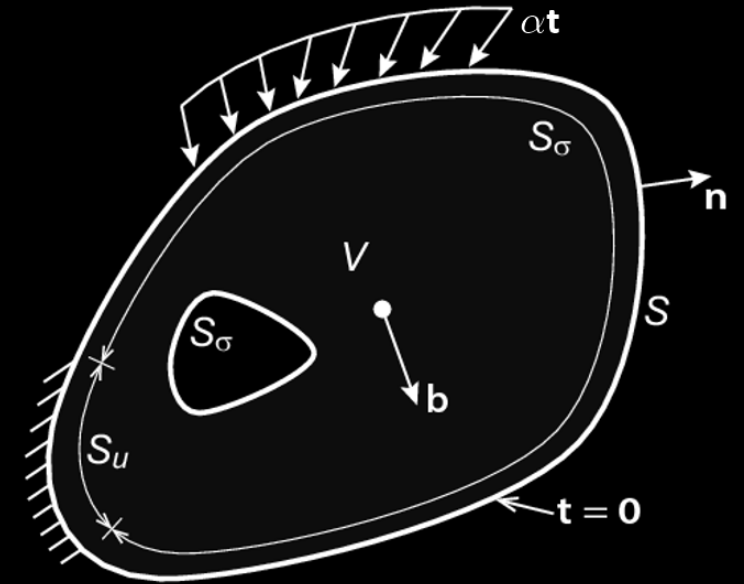
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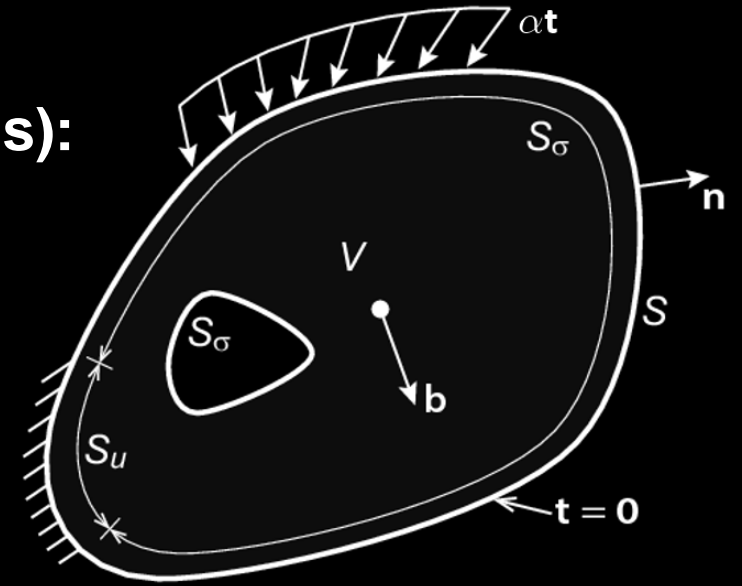
$$F(\boldsymbol{\sigma}) \leq 0$$

**The variational principle (optimization problem) is in every way equivalent to the governing equations**

# The Optum approach

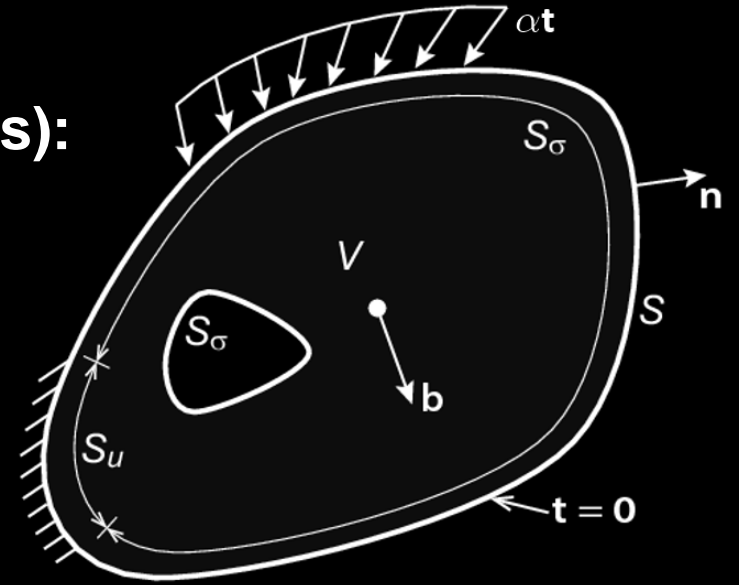
Variational principle (equivalent to governing equations):

$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & && \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$



# The Optum approach

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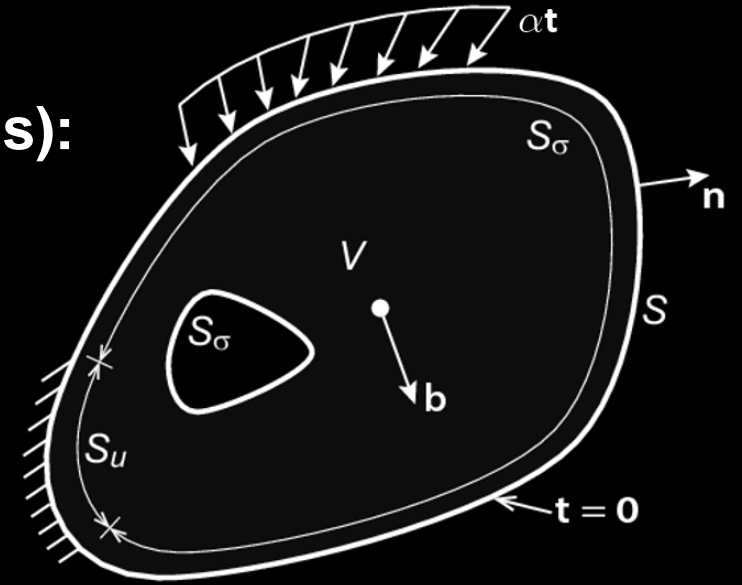
## Simple analogy: Hooke's law



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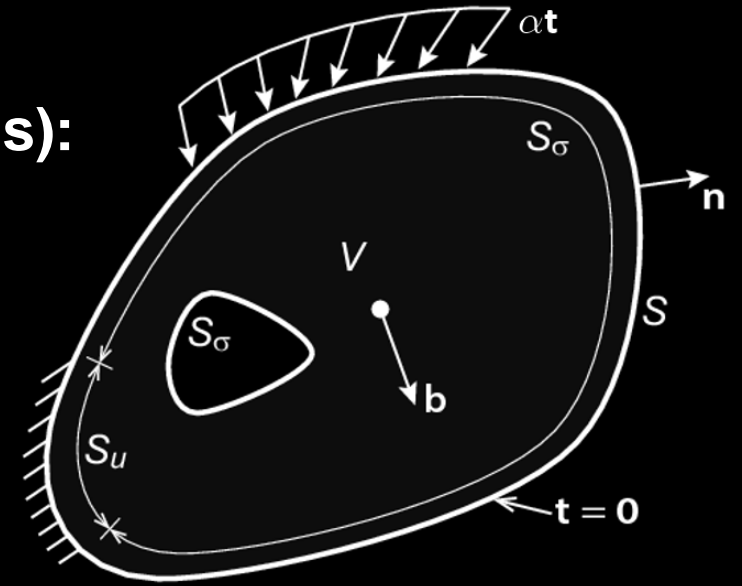
*Either:*

$$F = kx$$

# The Optum approach

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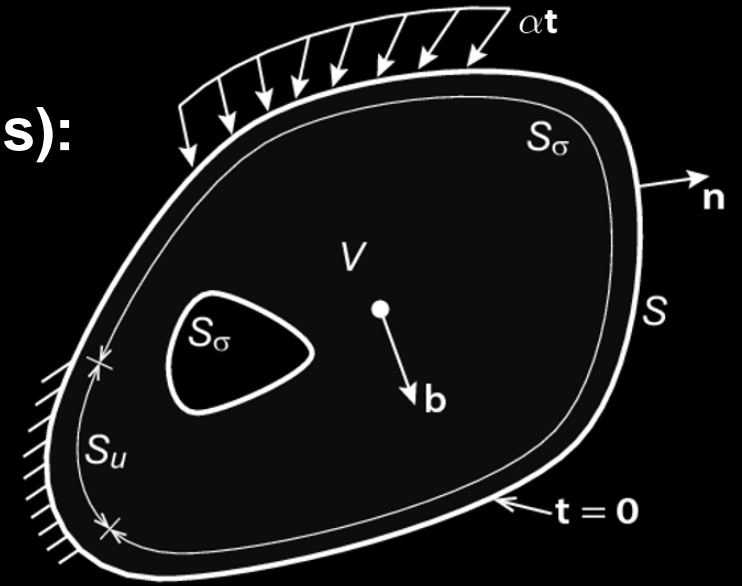
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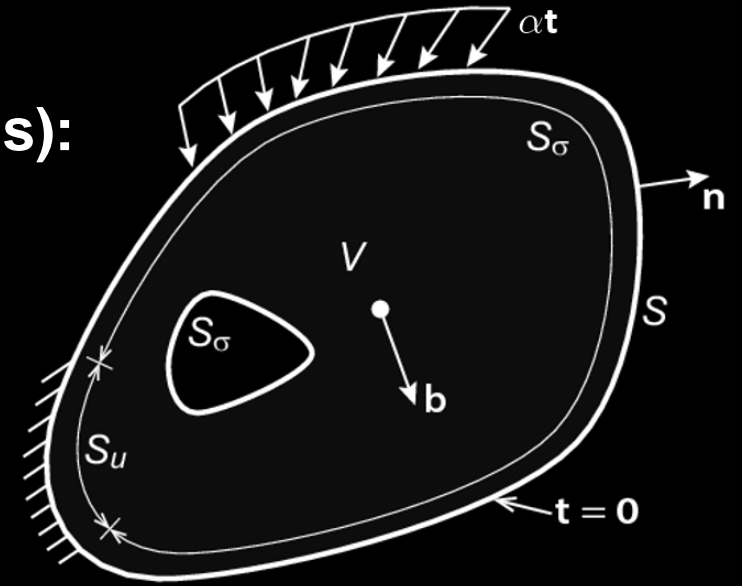
$$\text{minimize} \quad \frac{1}{2}kx^2 - Fx \quad \rightarrow \quad \frac{d}{dx} \left( \frac{1}{2}kx^2 - Fx \right) = 0$$



# The Optum approach

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Simple analogy: Hooke's law

*Either:*

$$F = kx$$

*or:*

$$\text{minimize } \frac{1}{2}kx^2 - Fx \rightarrow \frac{d}{dx} \left( \frac{1}{2}kx^2 - Fx \right) = 0 \Rightarrow kx - F = 0$$

# The Optum approach

## Rigid plasticity (limit analysis)

Equilibrium:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

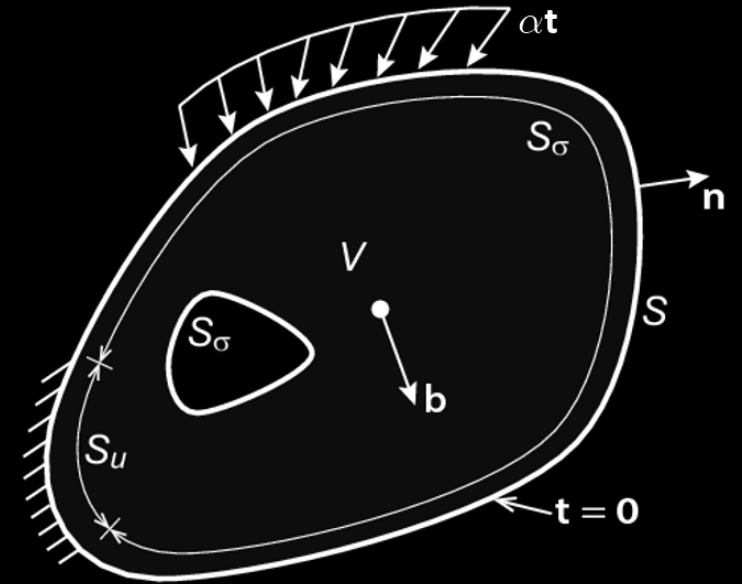
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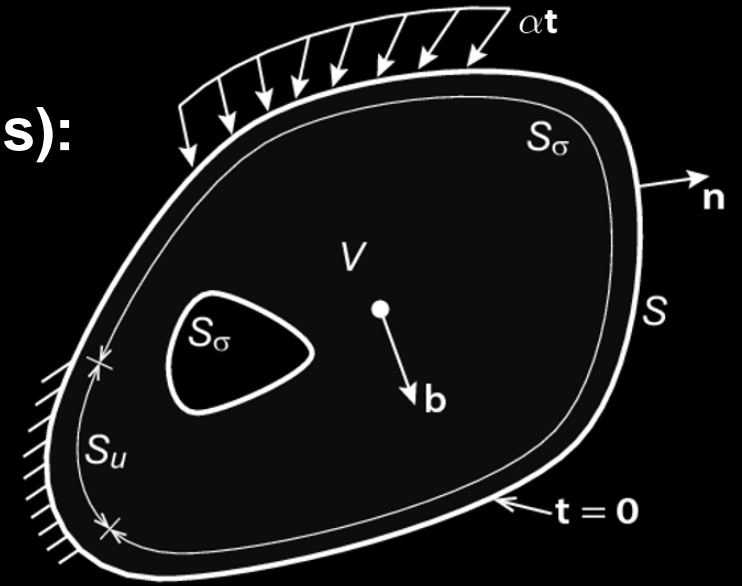
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Variational principle (equivalent to governing equations):

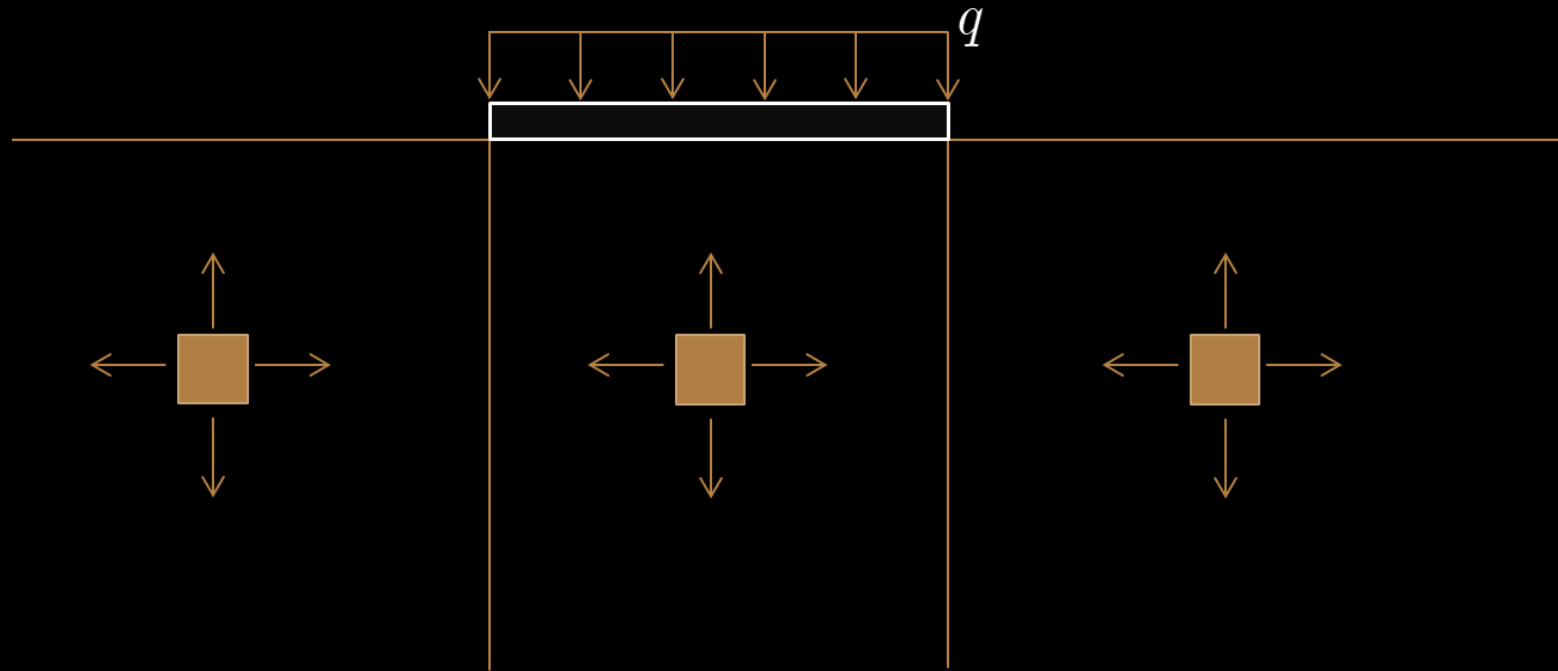
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However: partial solutions (solutions that satisfy the constraints but are not optimal) will be lower bounds (less than the optimal  $\alpha$ )

# The Optum approach

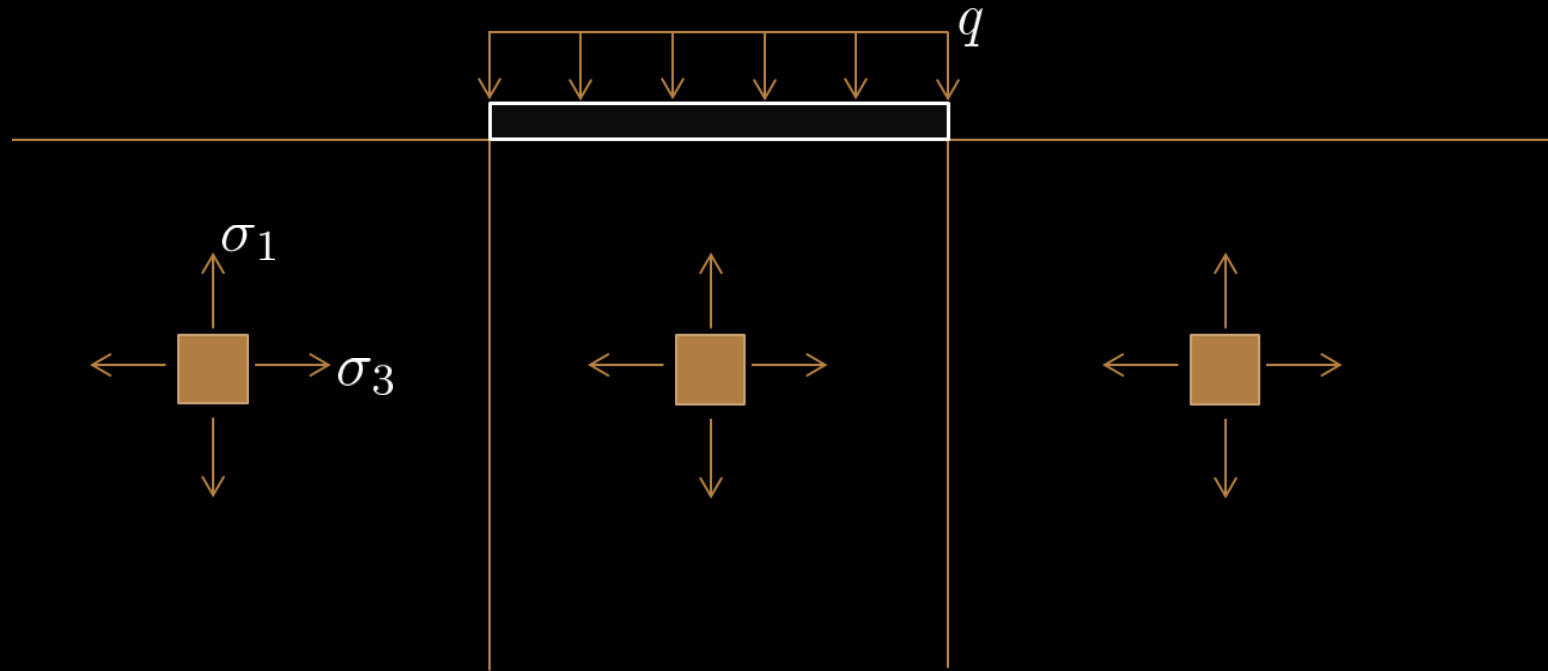
Example: footing on weightless Tresca soil





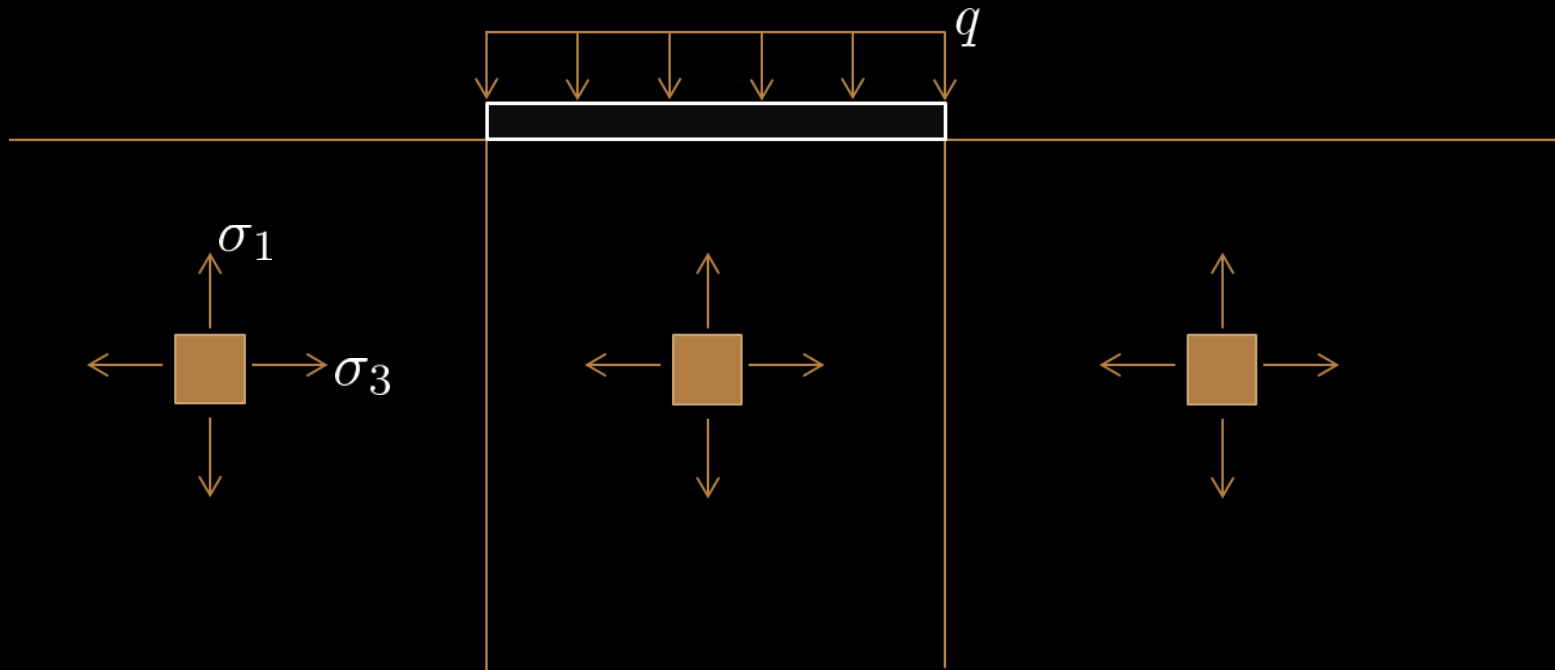
# The Optum approach

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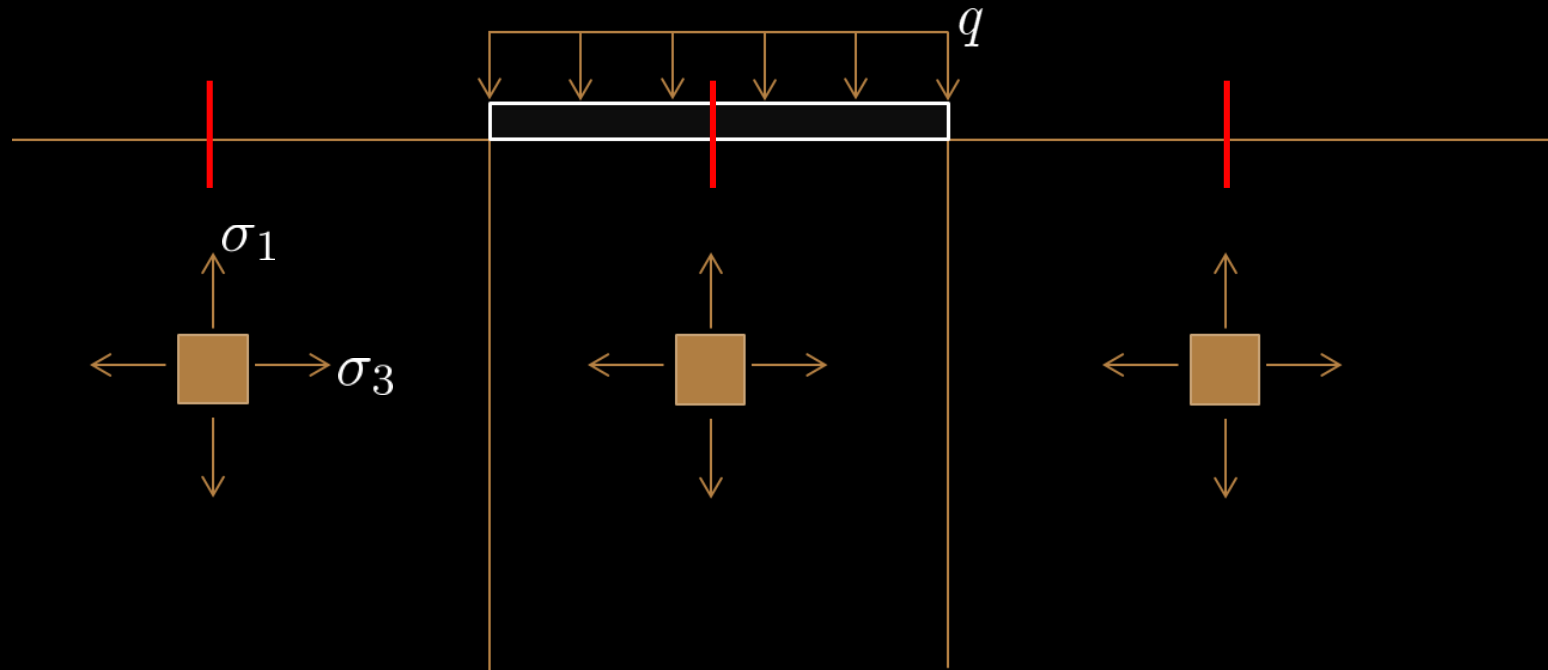


maximize  
subject to

$q$   
Global equilibrium (satisfied)  
Static BCs  
Interface equilibrium  
 $|\sigma_1 - \sigma_3| \leq 2s_u$

# The Optum approach

Example: footing on weightless Tresca soil



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Global equilibrium (satisfied)

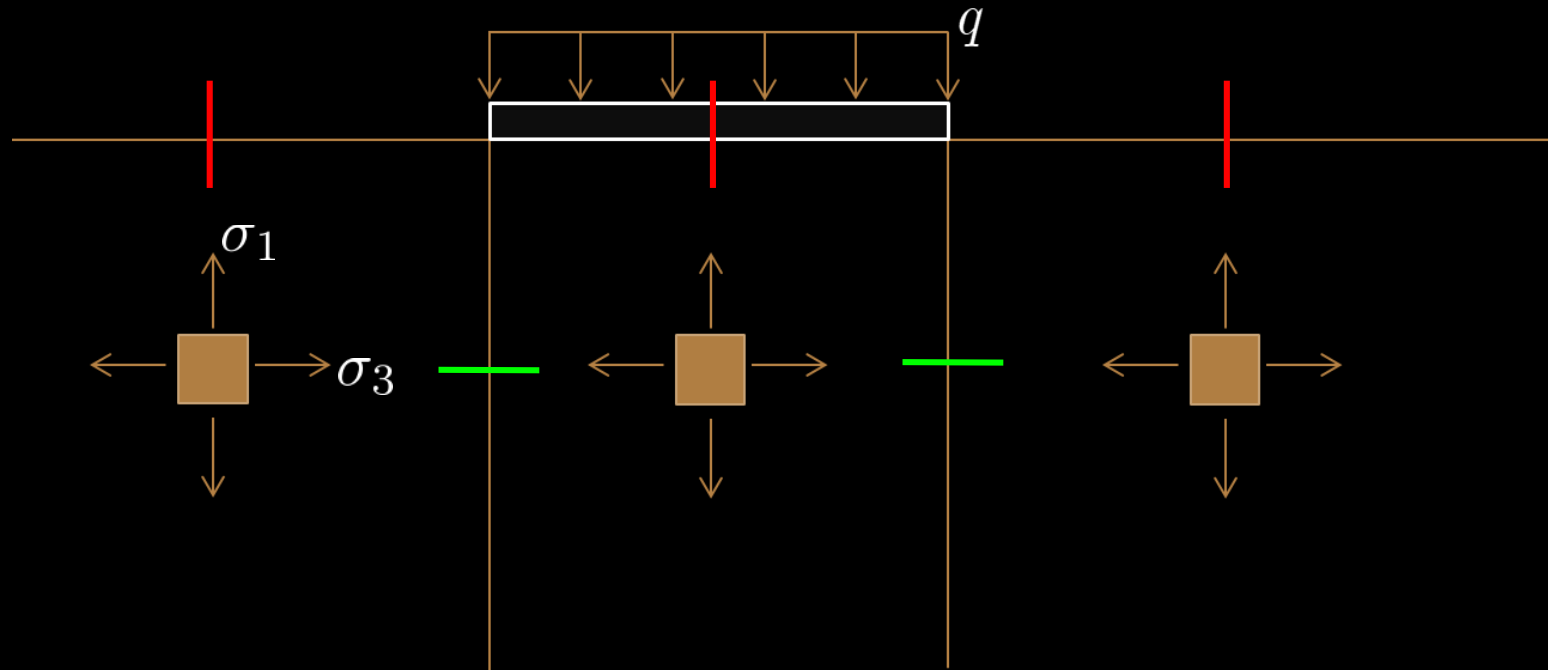
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$

Global equilibrium (satisfied)

Static BCs

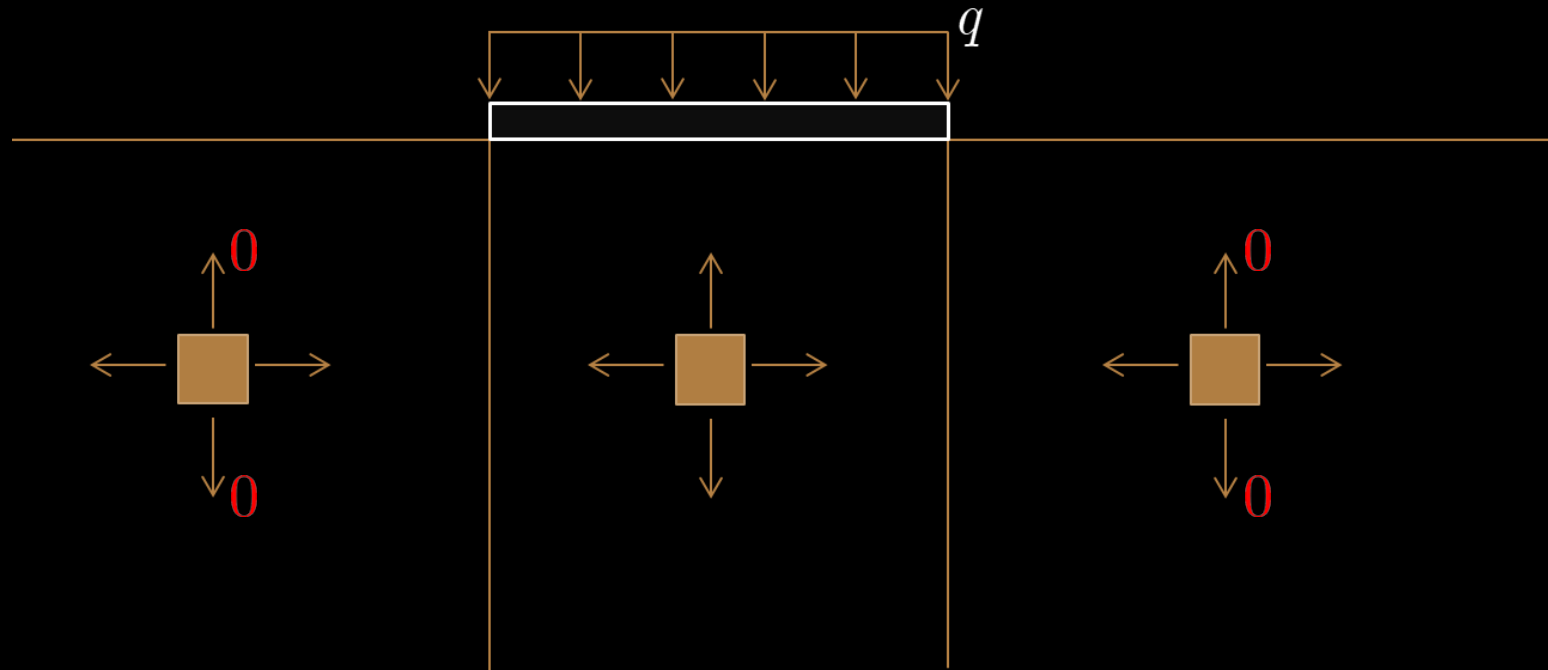
Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$

Global equilibrium (satisfied)

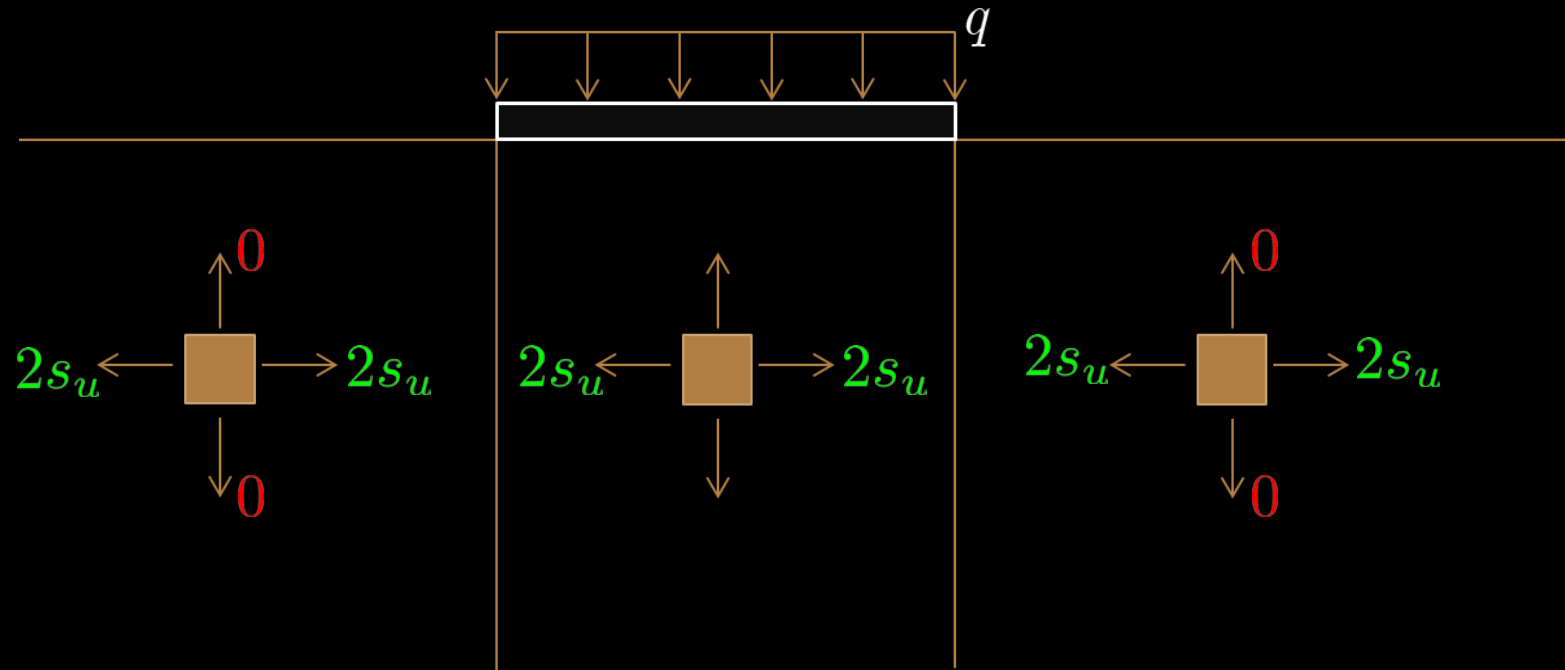
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$

Global equilibrium (satisfied)

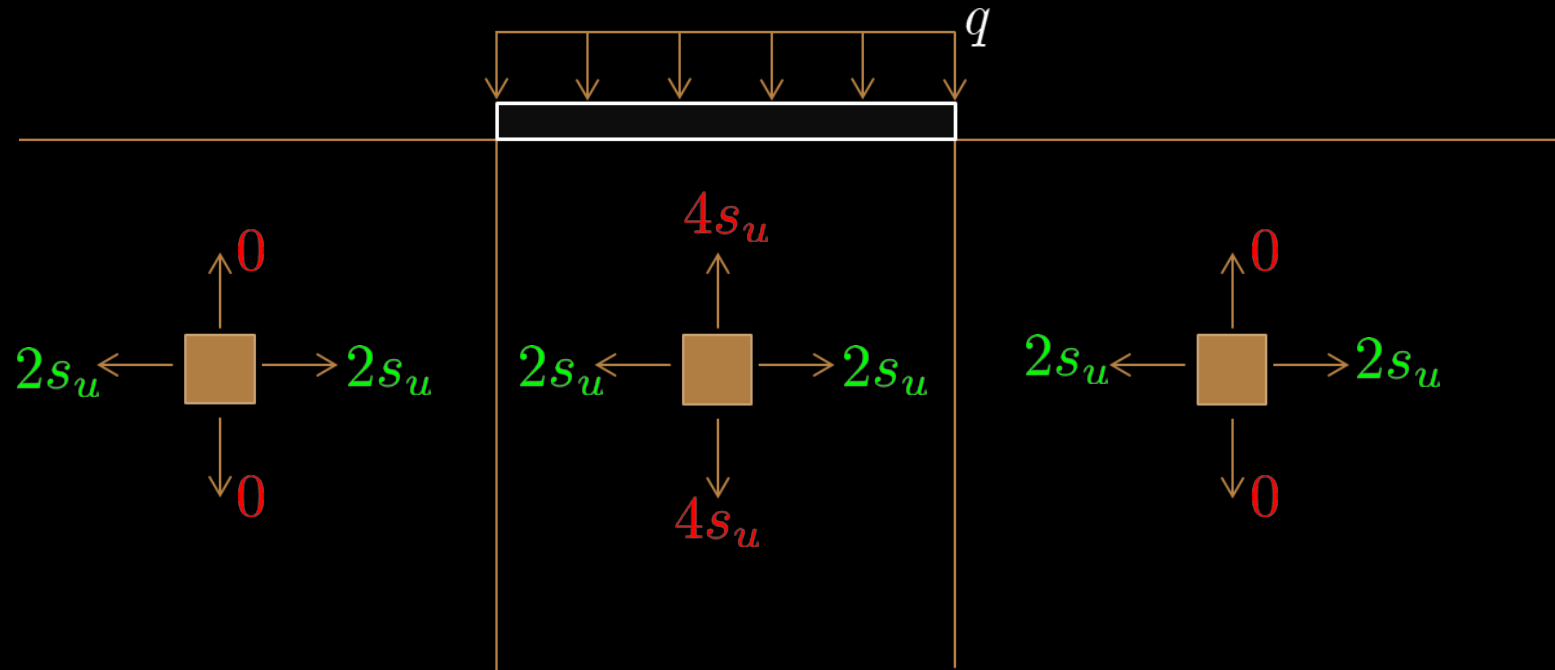
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$   
Global equilibrium (satisfied)

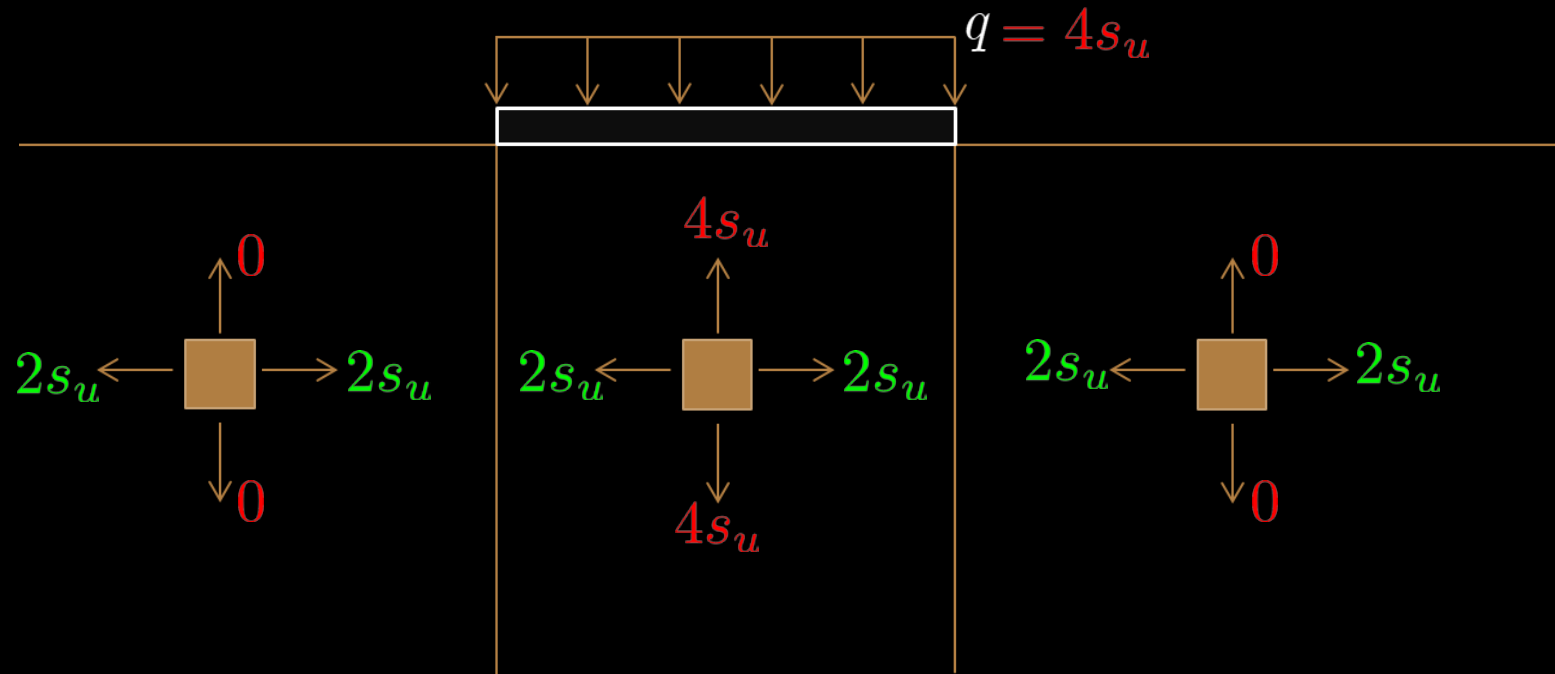
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$   
Global equilibrium (satisfied)

Static BCs

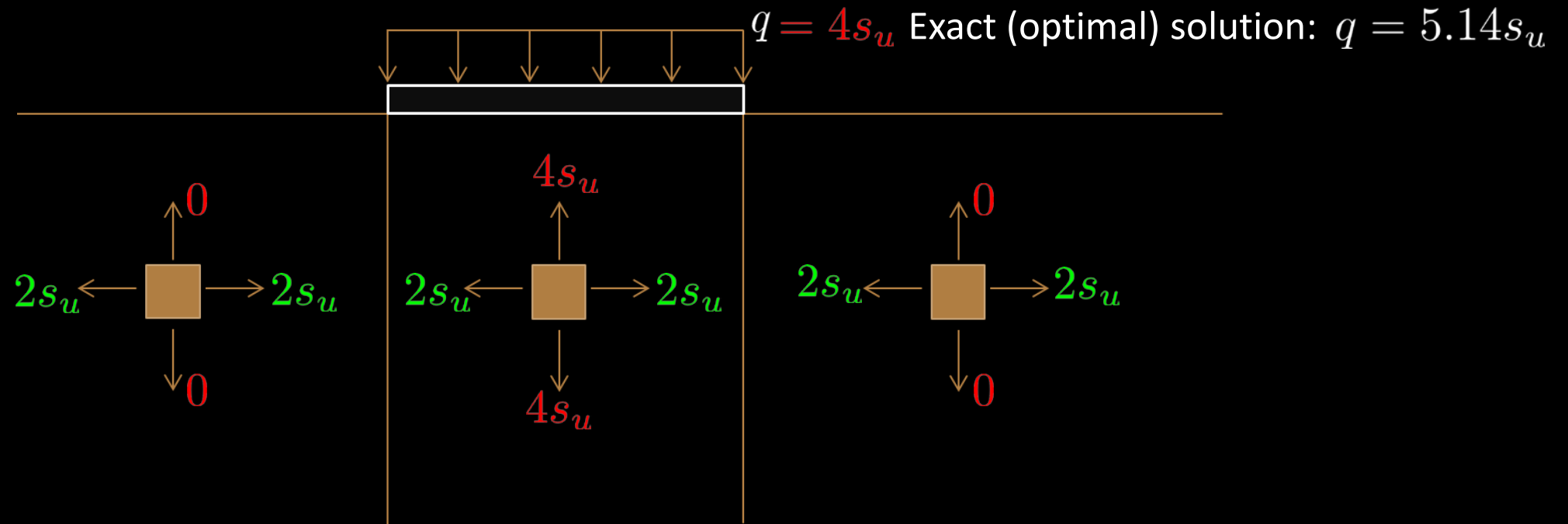
Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$   
Global equilibrium (satisfied)

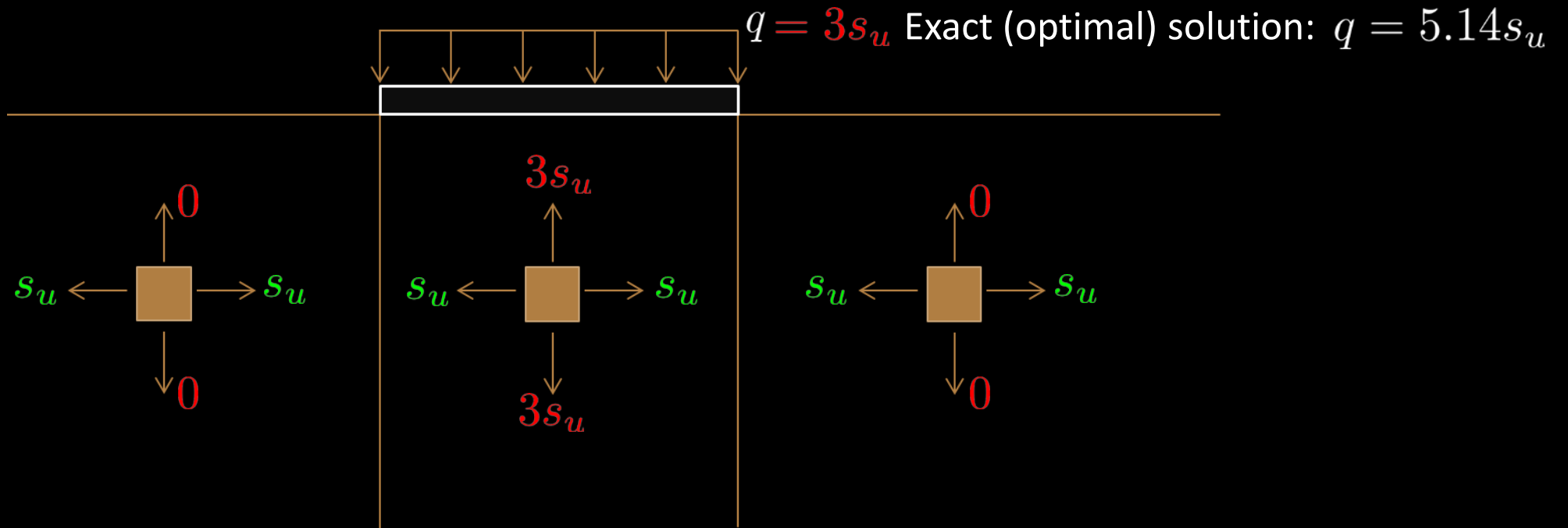
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$   
Global equilibrium (satisfied)

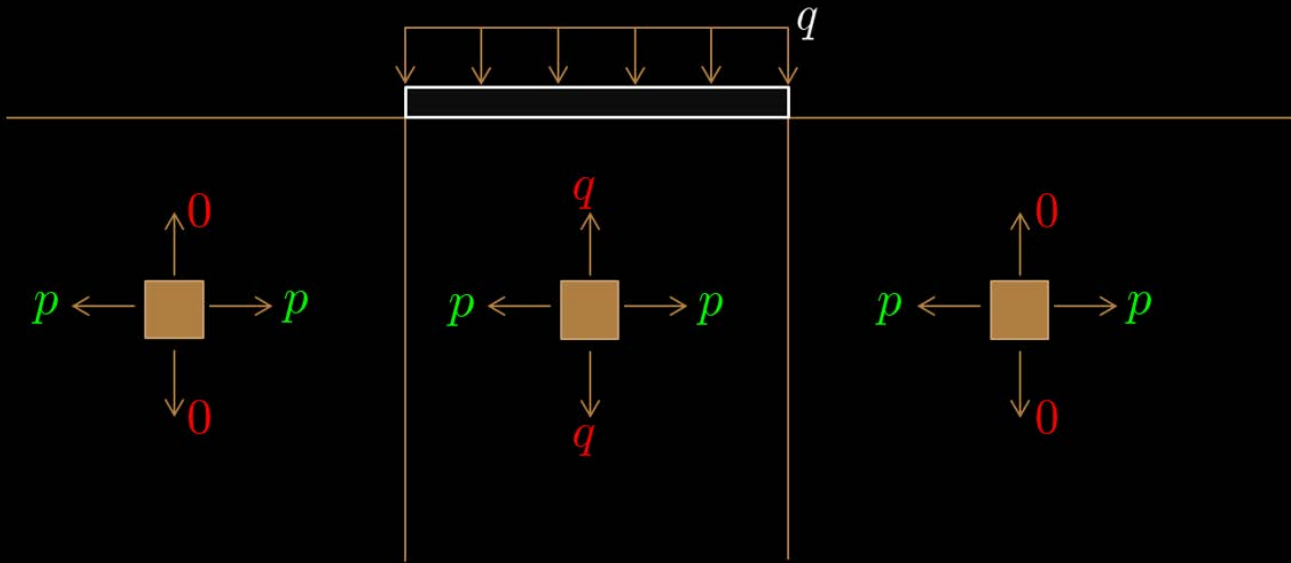
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

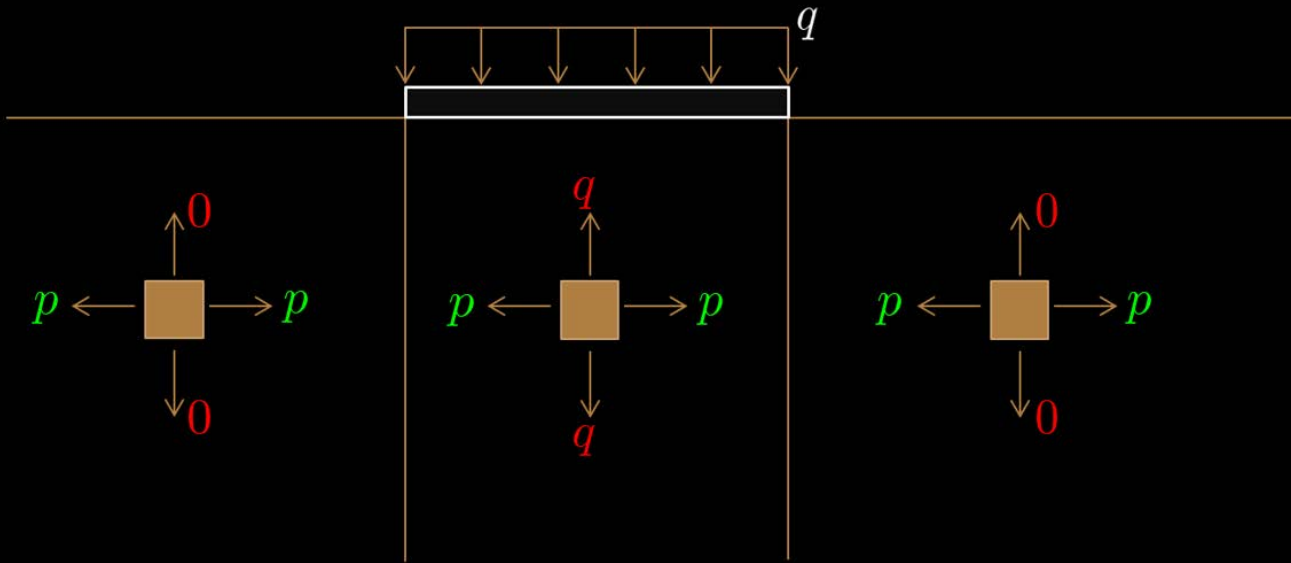
# The Optum approach

Example: footing on weightless Tresca soil



# The Optum approach

Example: footing on weightless Tresca soil

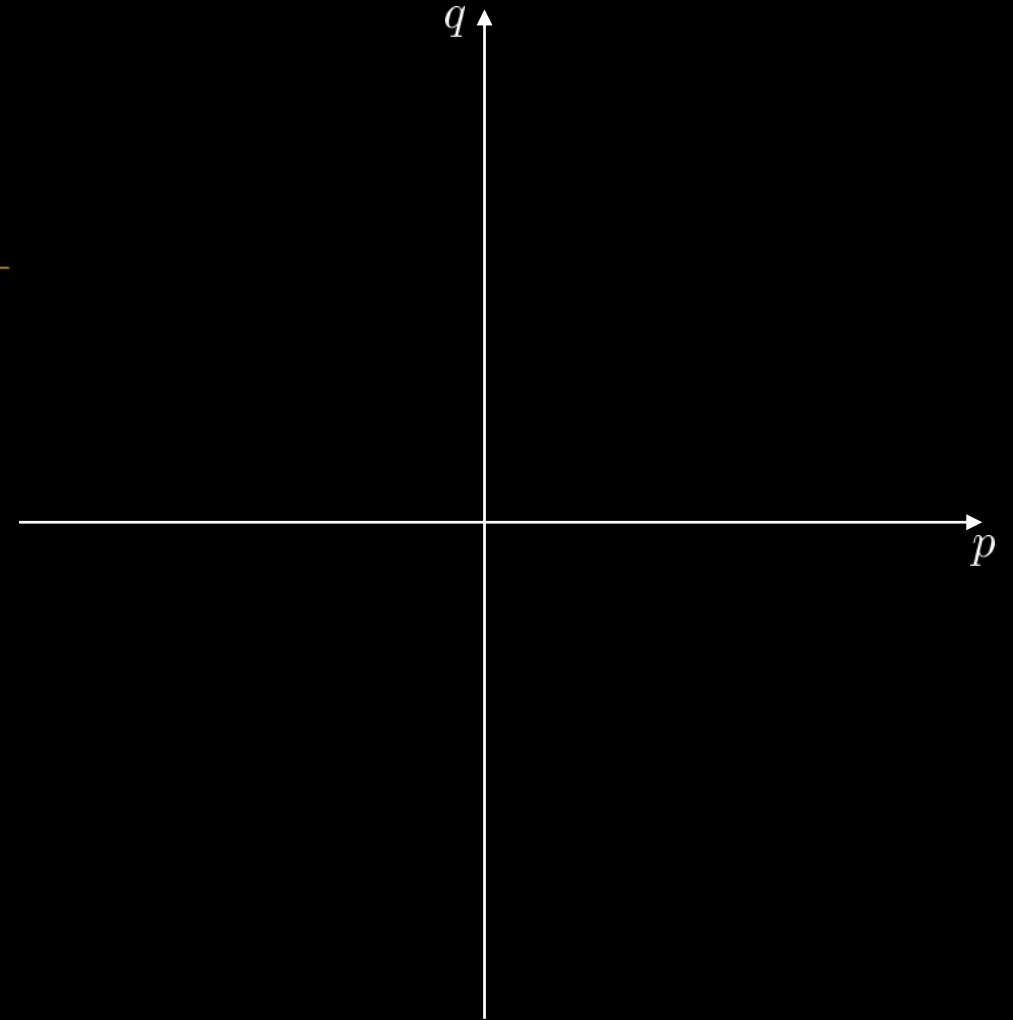
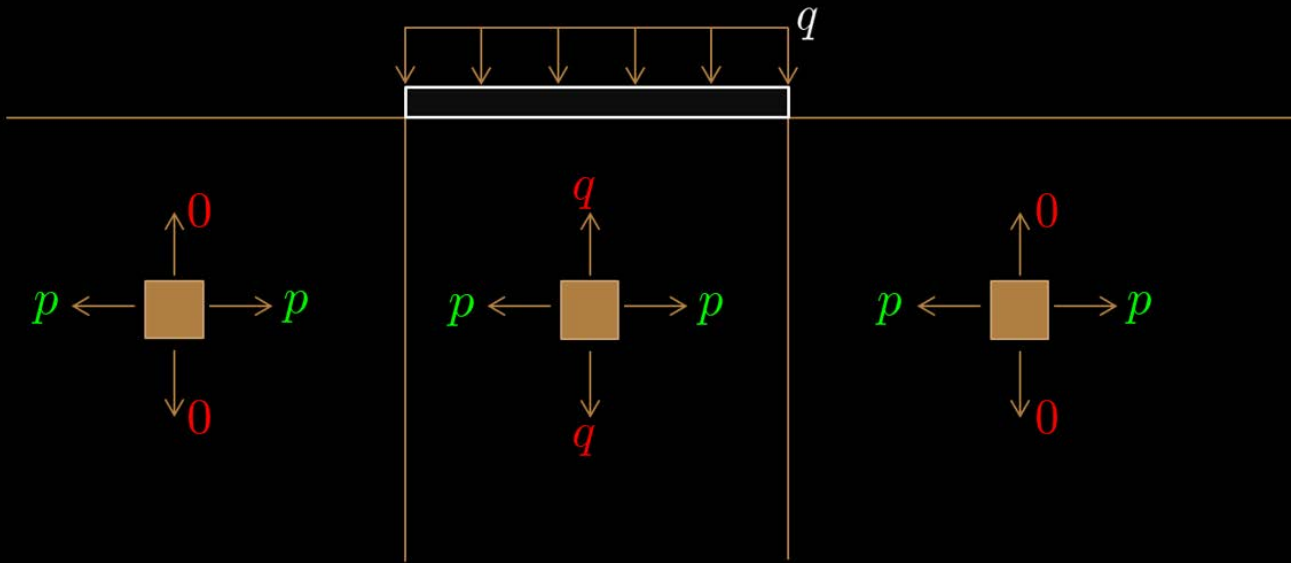


maximize  $q$   
subject to  $|p| \leq 2s_u$   
 $|q - p| \leq 2s_u$



# The Optum approach

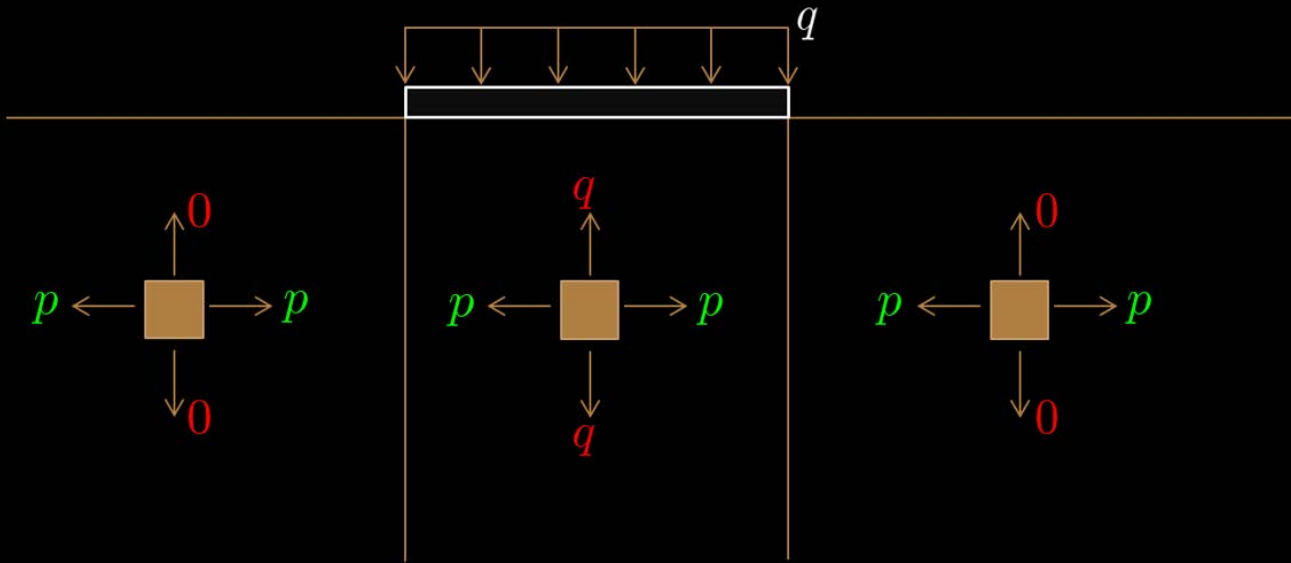
Example: footing on weightless Tresca soil



maximize  $q$   
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# The Optum approach

Example: footing on weightless Tresca soil

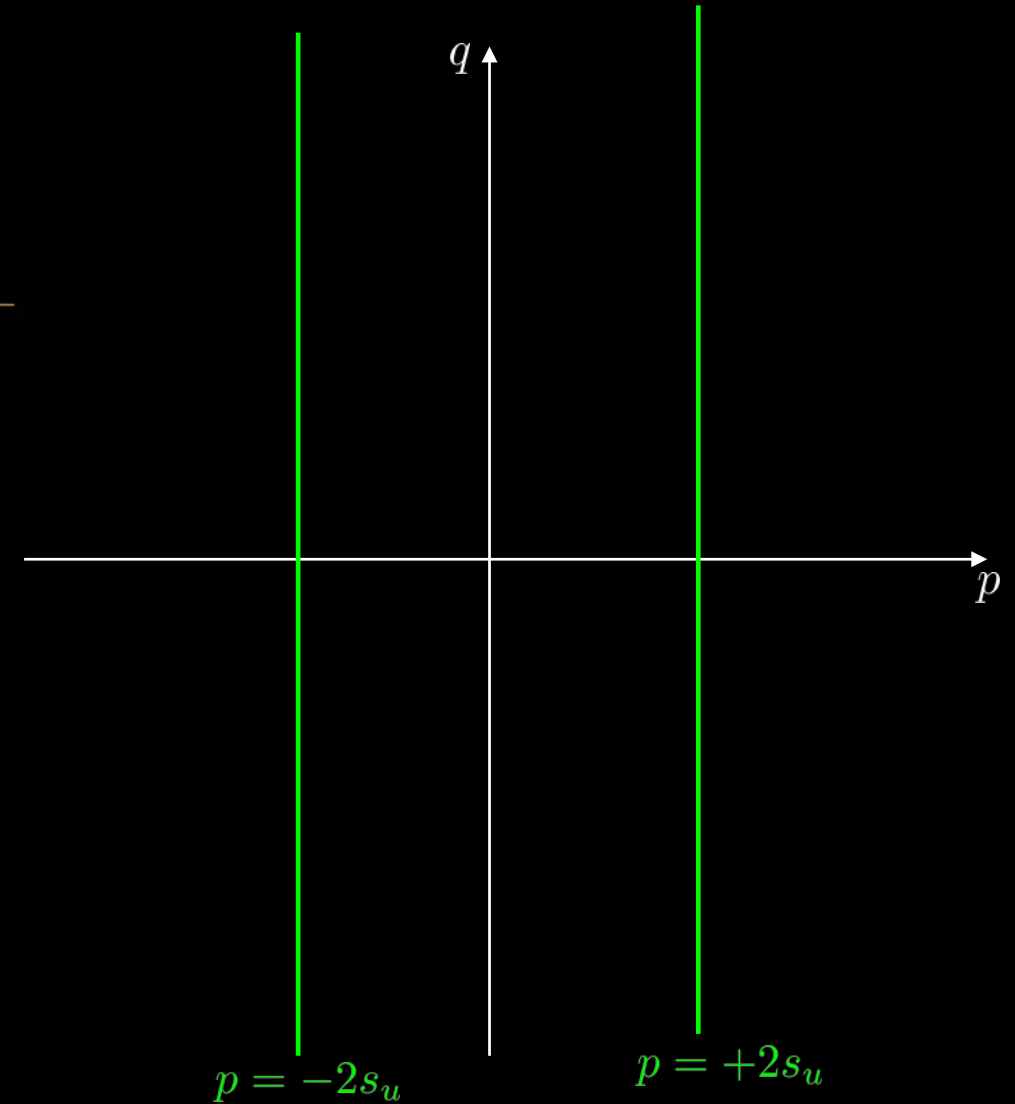


maximize  
subject to

$q$

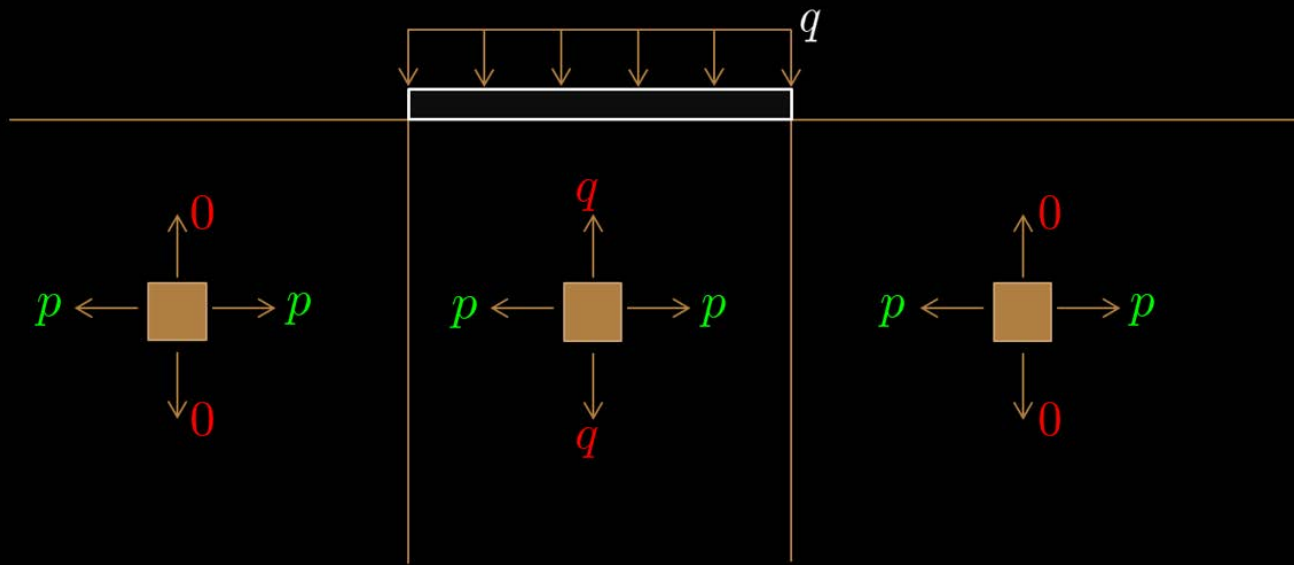
$$|p| \leq 2s_u$$

$$|q - p| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil

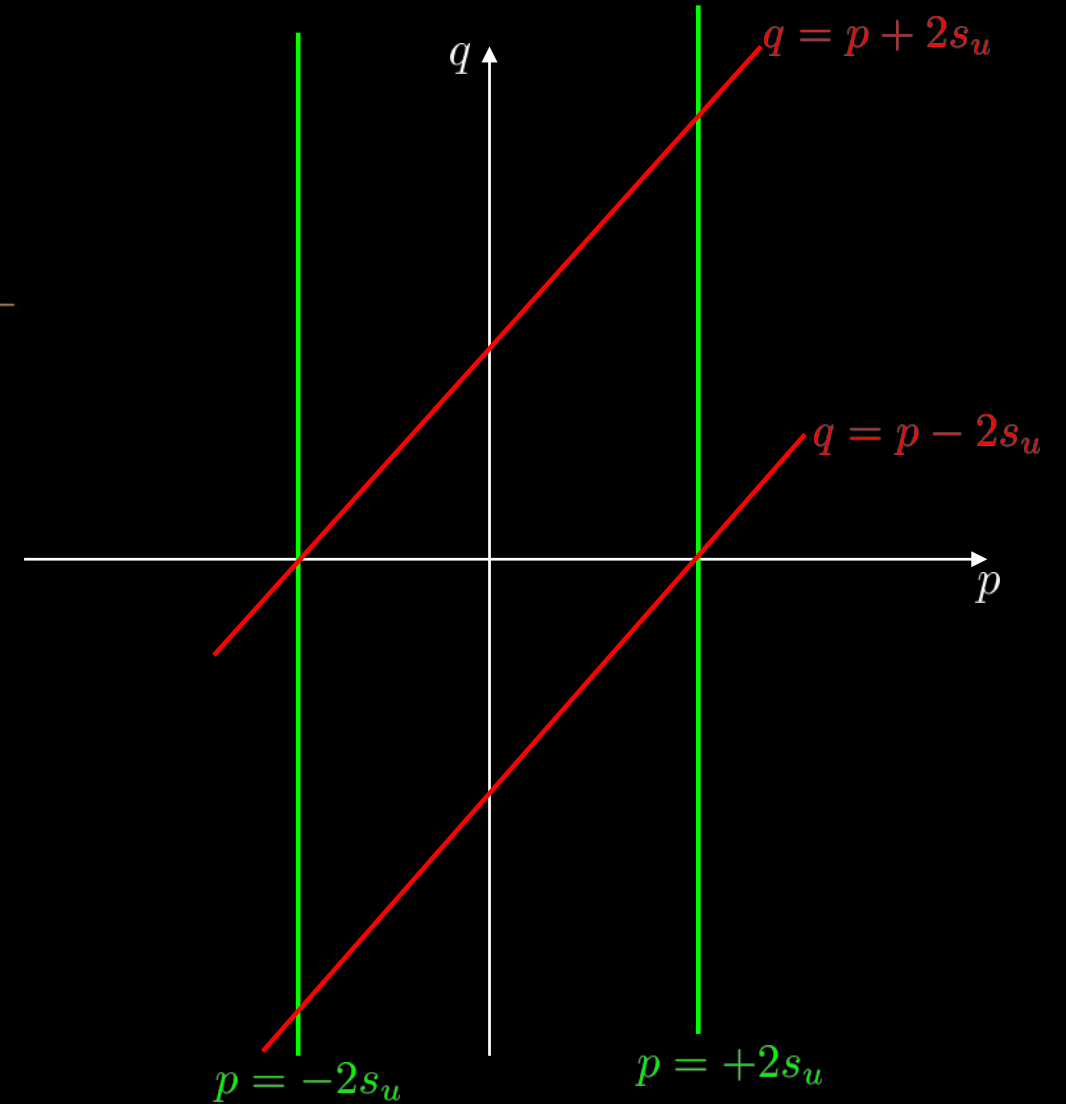


maximize  
subject to

$q$

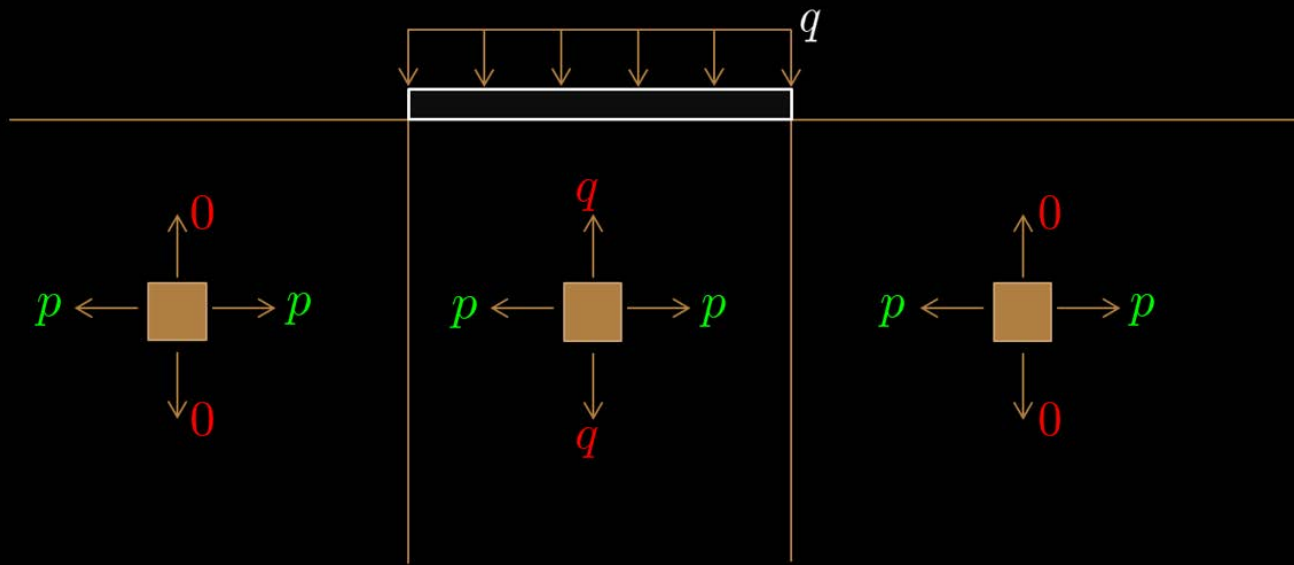
$$|p| \leq 2s_u$$

$$|q - p| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil

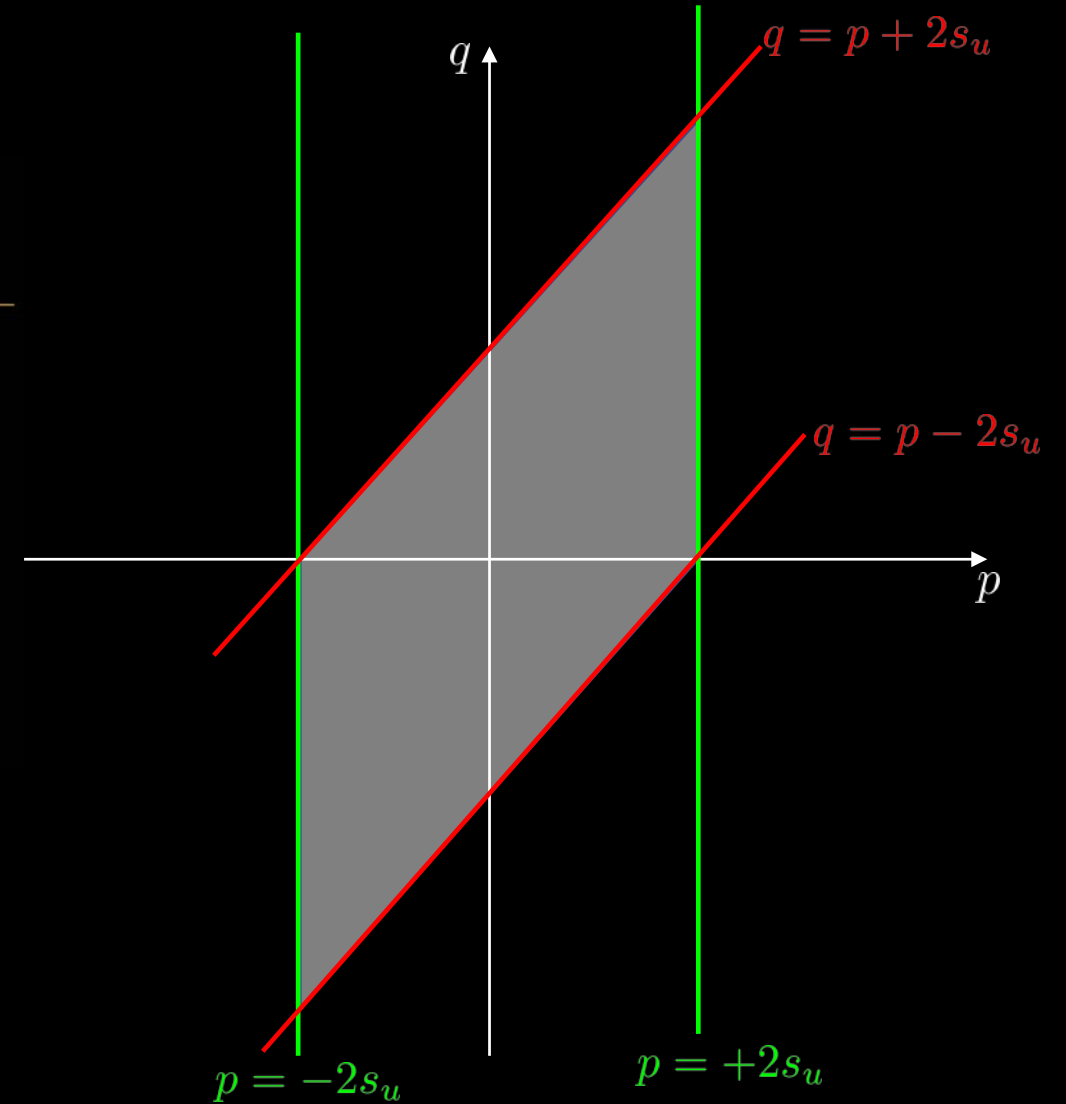


maximize  
subject to

$q$

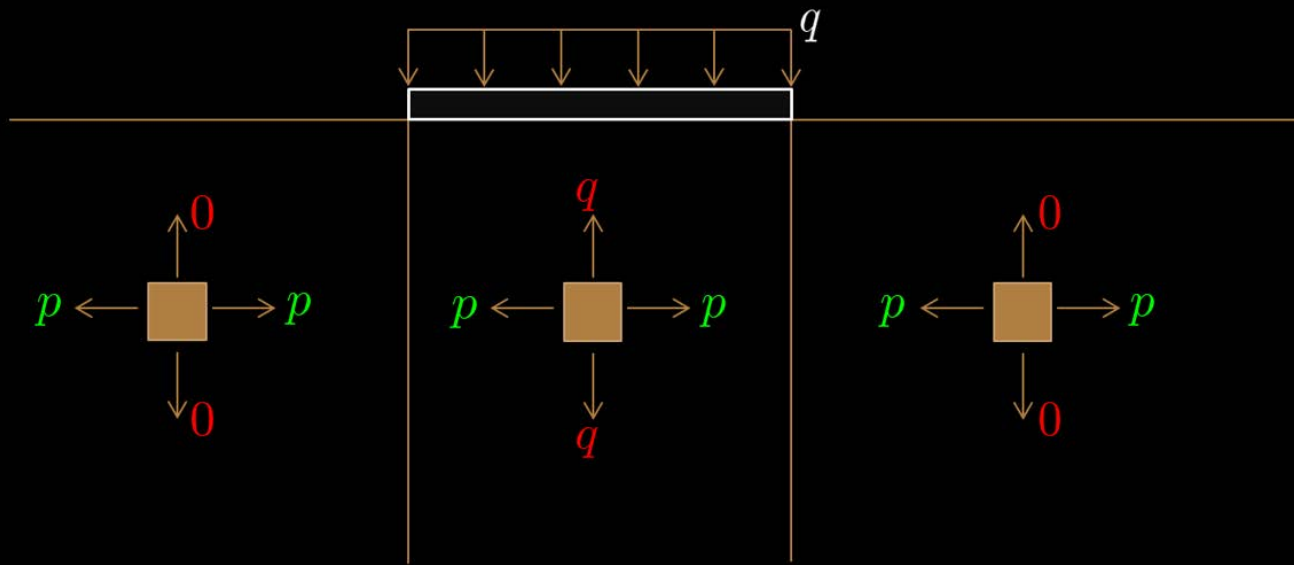
$$|p| \leq 2s_u$$

$$|q - p| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil

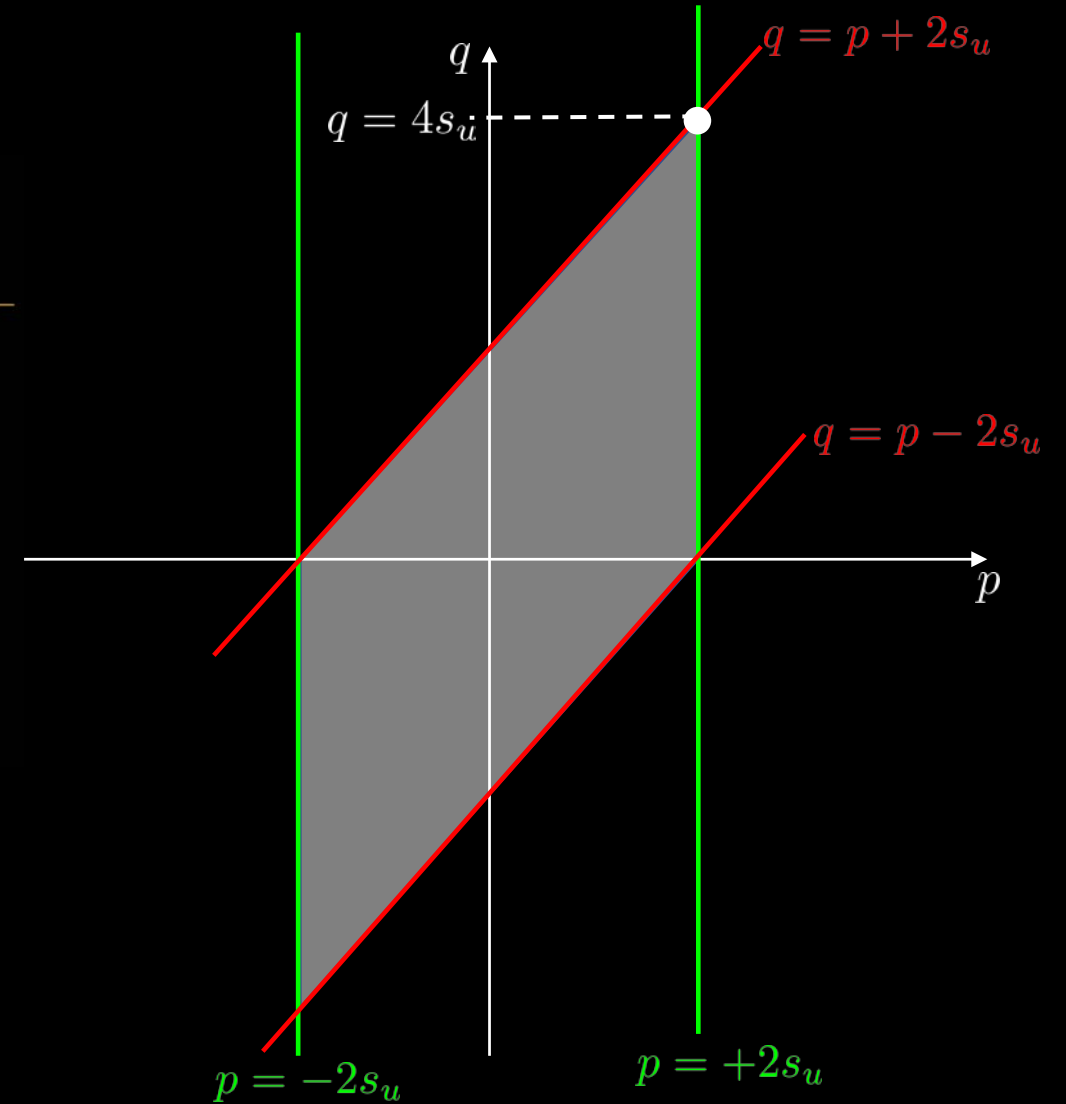


maximize  
subject to

$q$

$$|p| \leq 2s_u$$

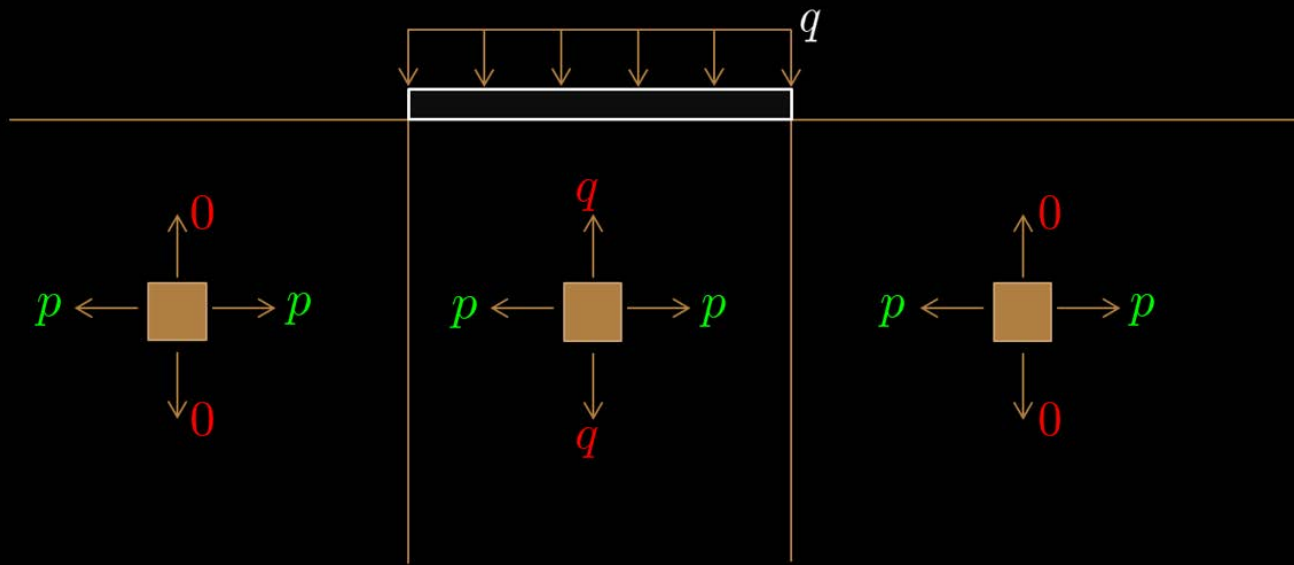
$$|q - p| \leq 2s_u$$





# The Optum approach

Example: footing on weightless Tresca soil

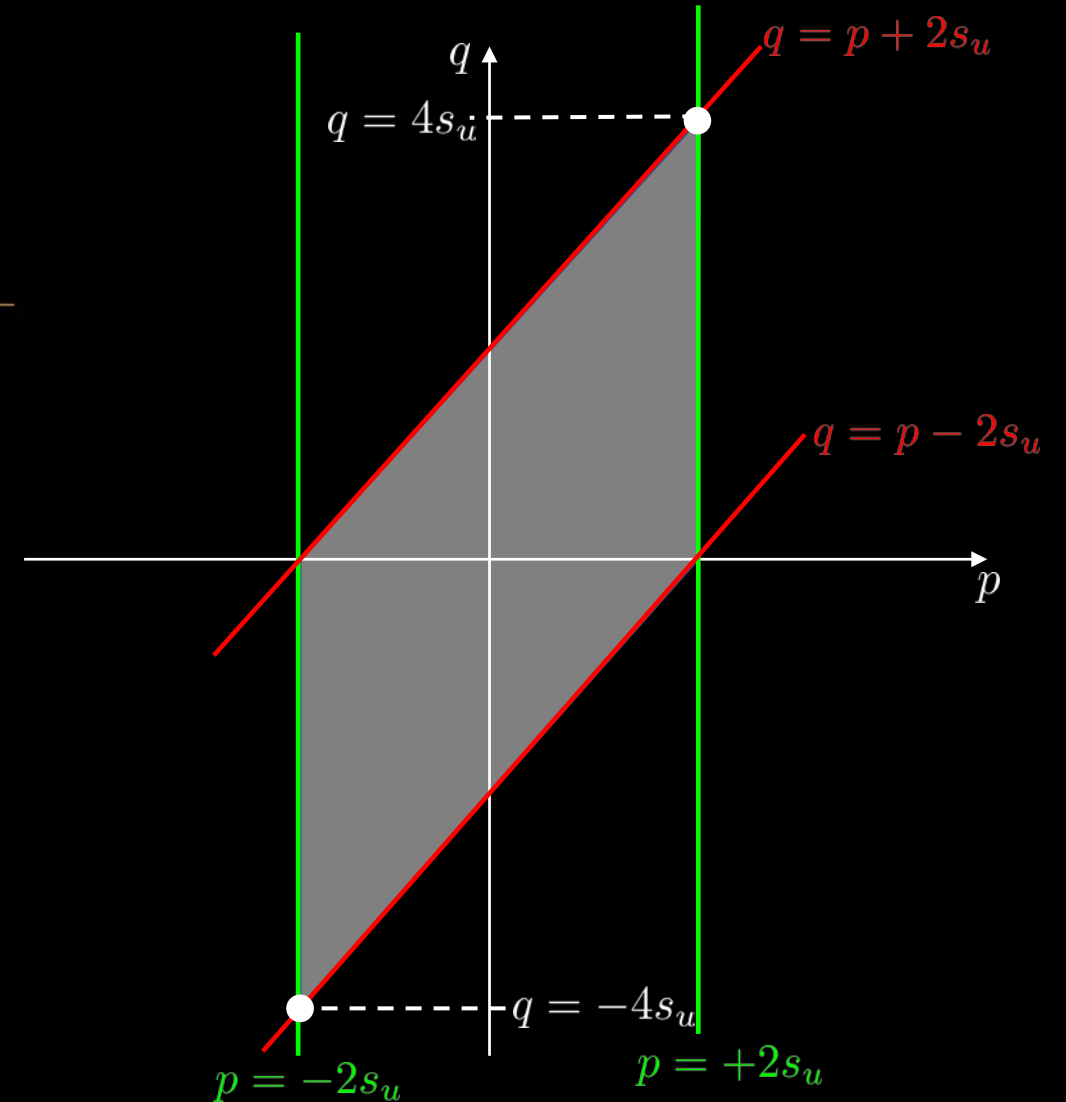


maximize  
subject to

$$q$$

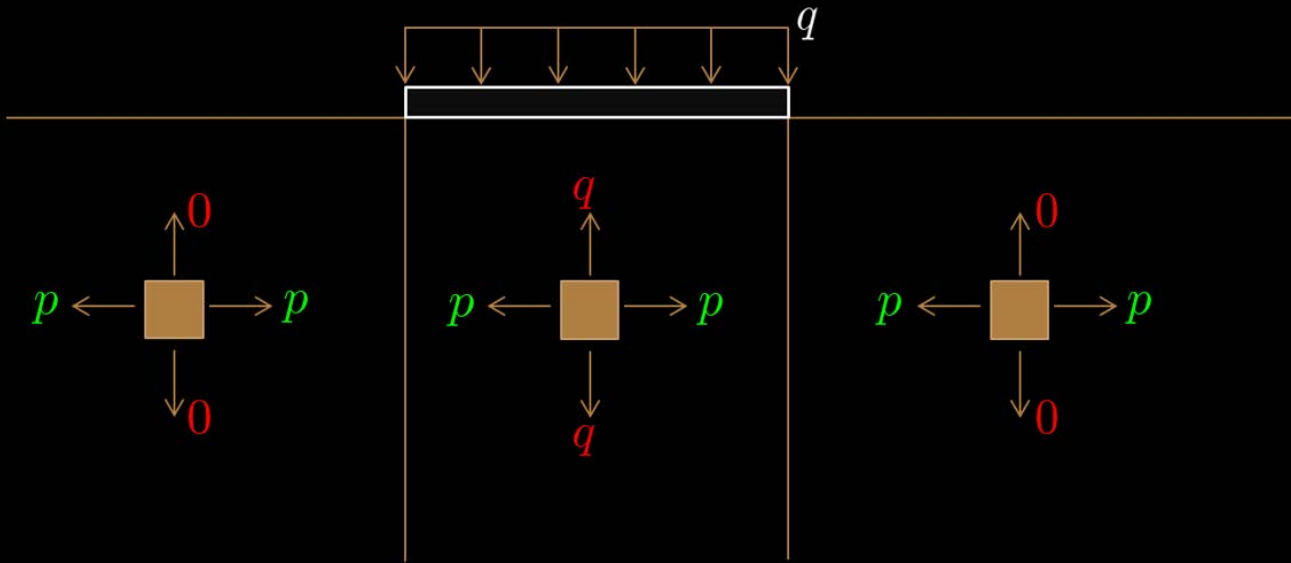
$$|p| \leq 2s_u$$

$$|q - p| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil

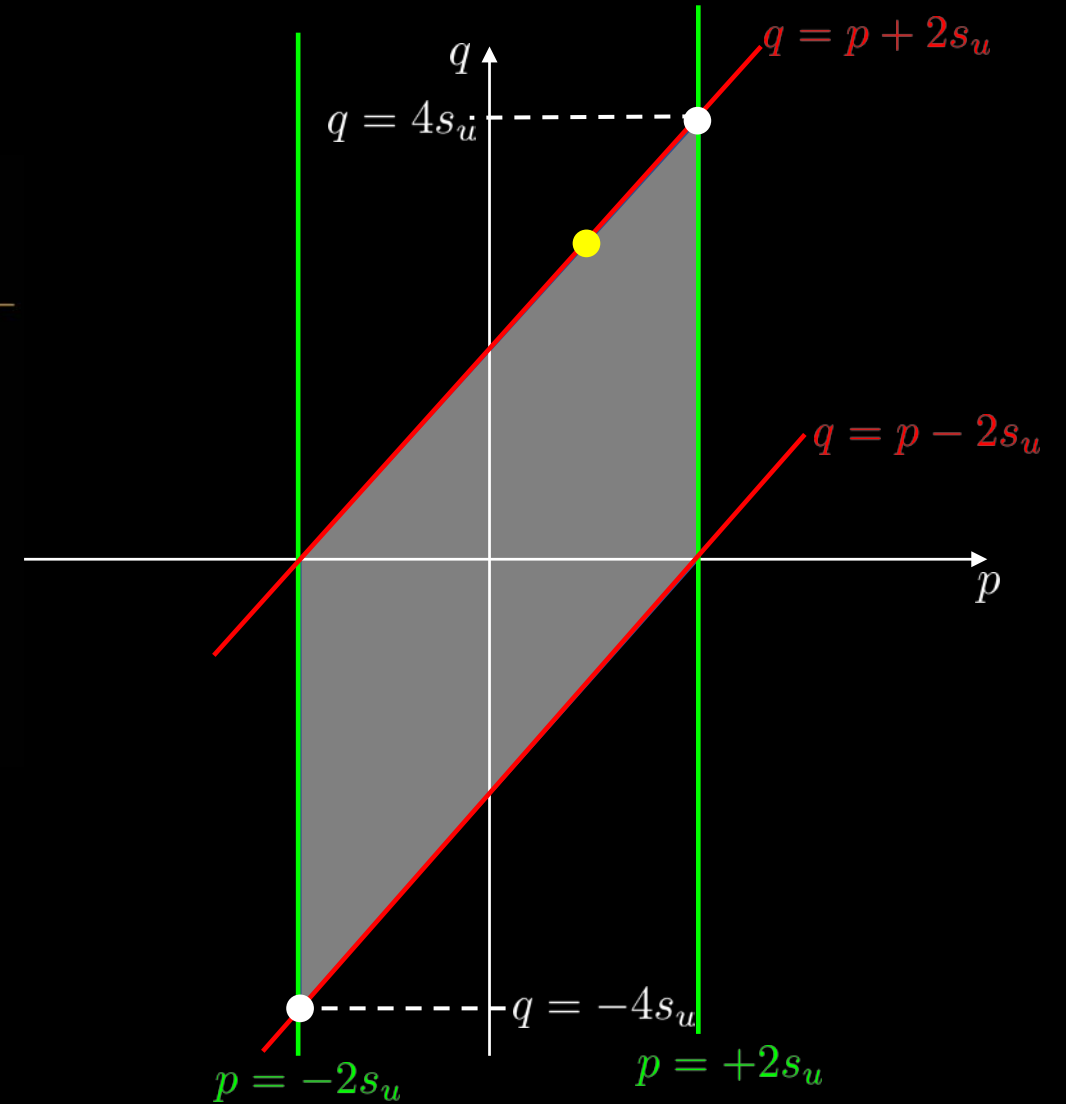


maximize  
subject to

$$q$$

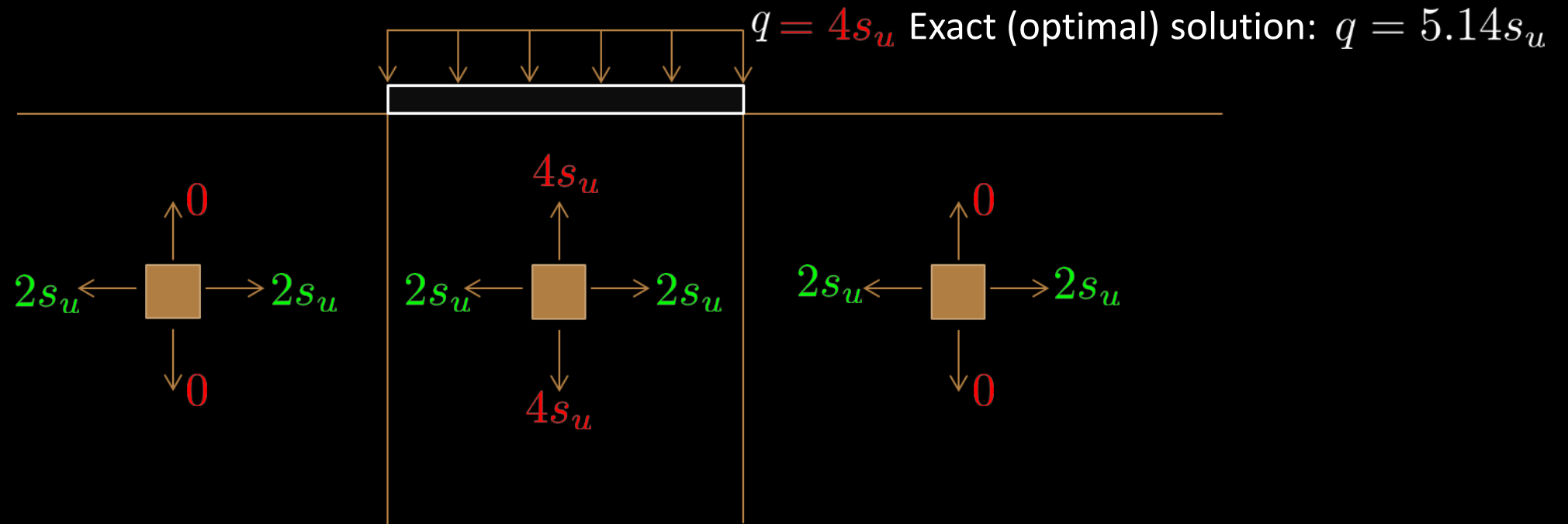
$$|p| \leq 2s_u$$

$$|q - p| \leq 2s_u$$



# The Optum approach

Example: footing on weightless Tresca soil



maximize  
subject to

$q$   
Global equilibrium (satisfied)

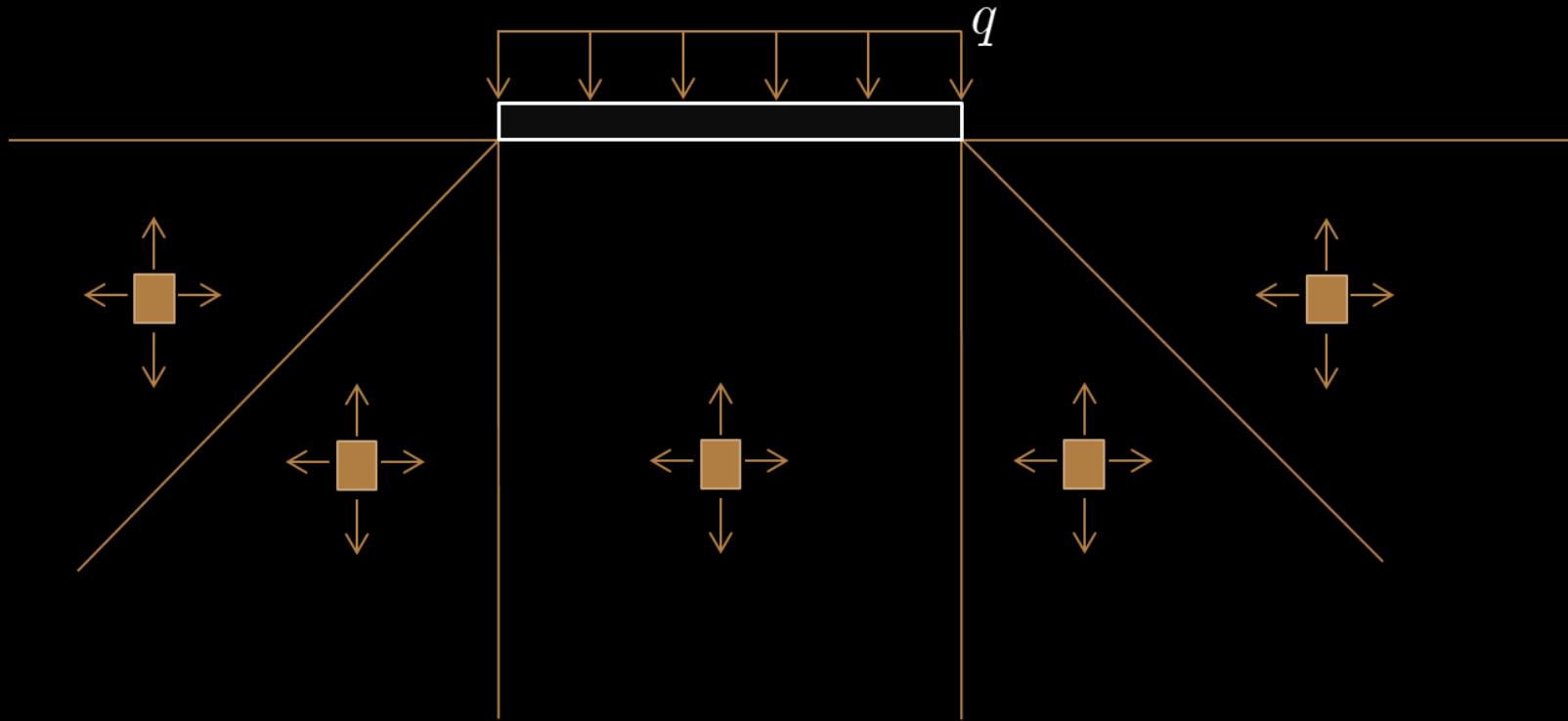
Static BCs

Interface equilibrium

$$|\sigma_1 - \sigma_3| \leq 2s_u$$

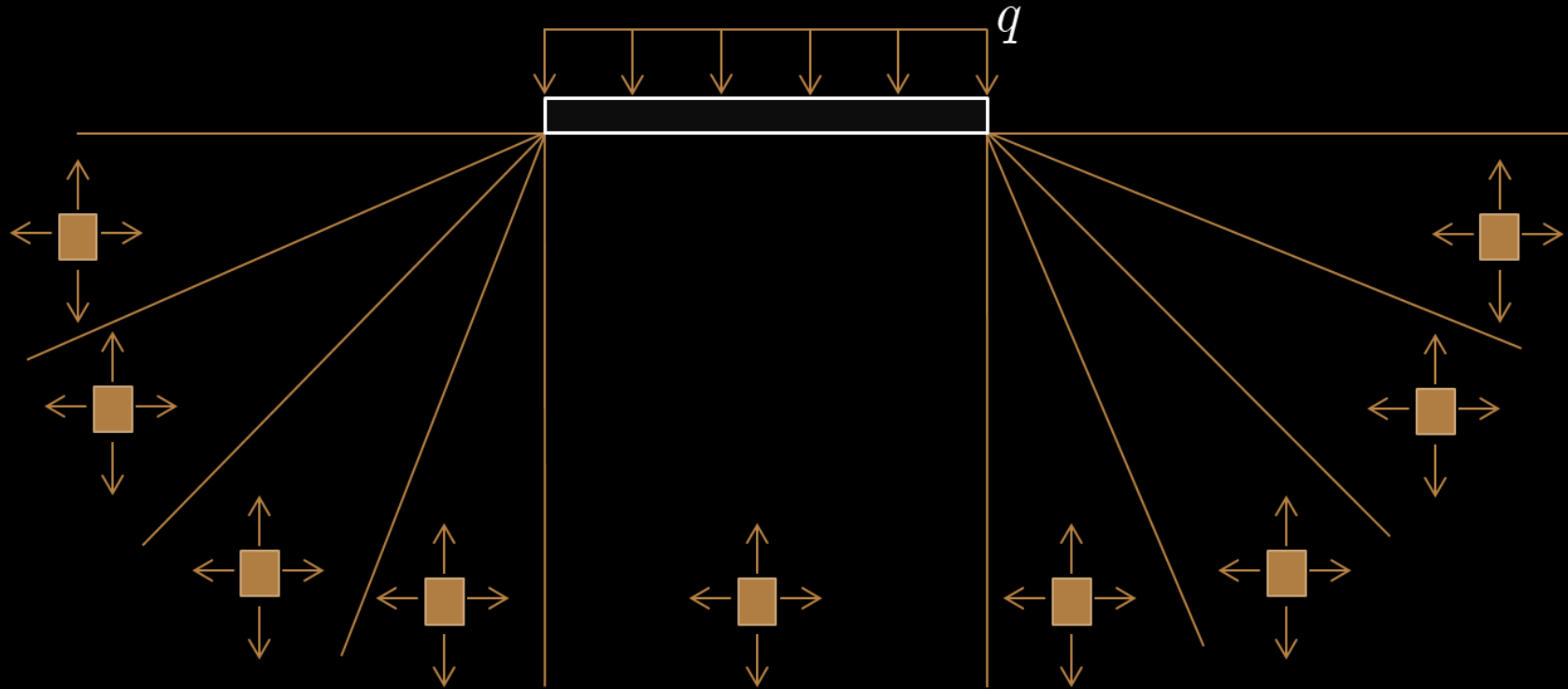
# The Optum approach

Example: footing on weightless Tresca soil



# The Optum approach

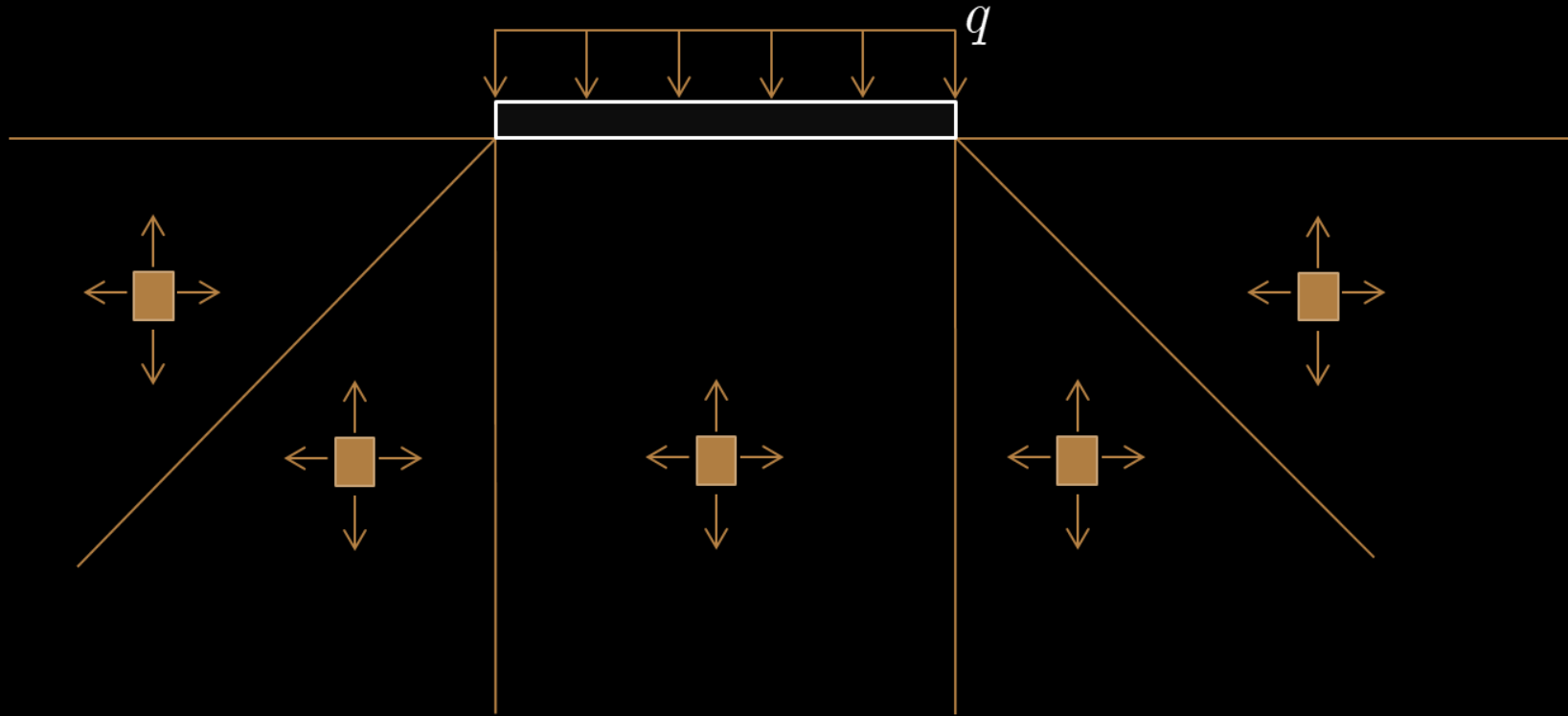
Example: footing on weightless Tresca soil





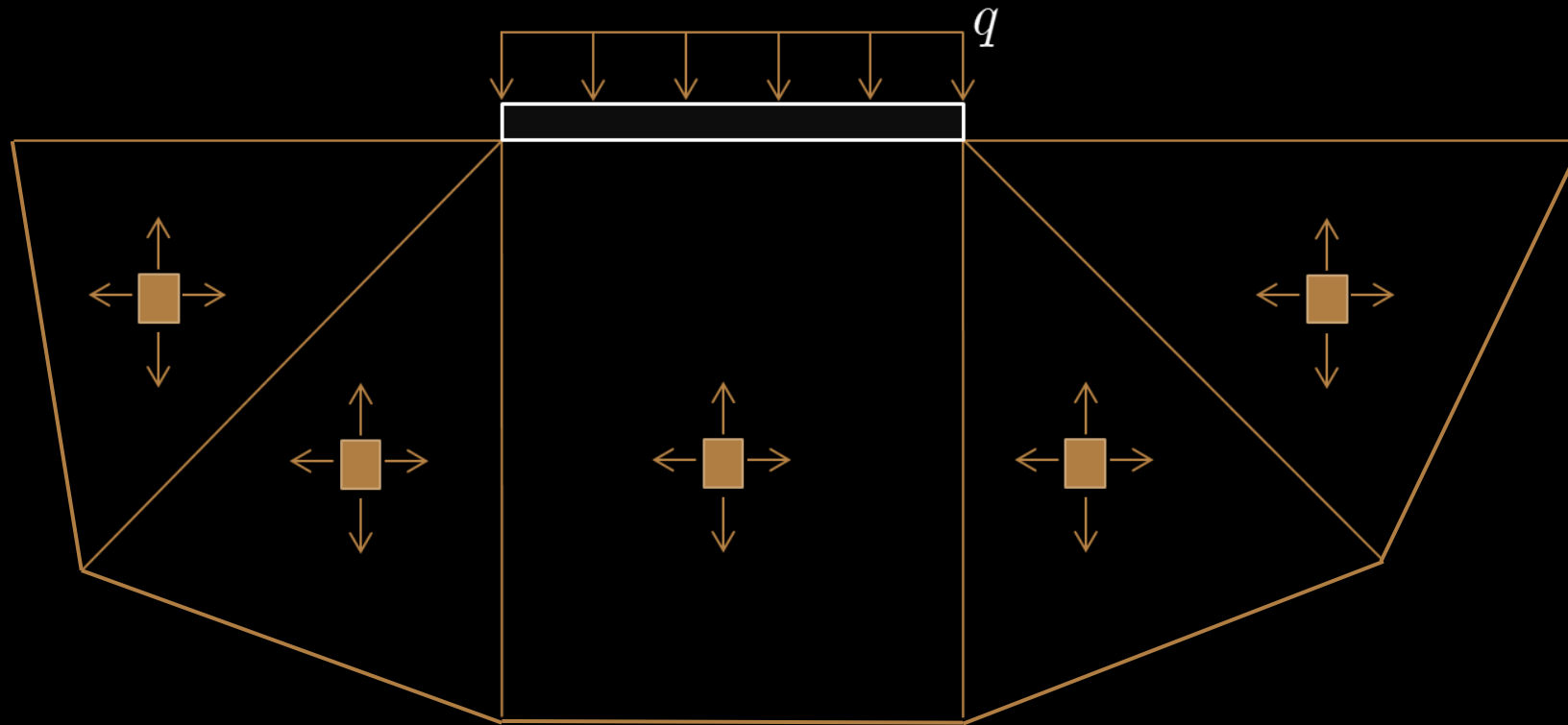
# The Optum approach

Example: footing on weightless Tresca soil



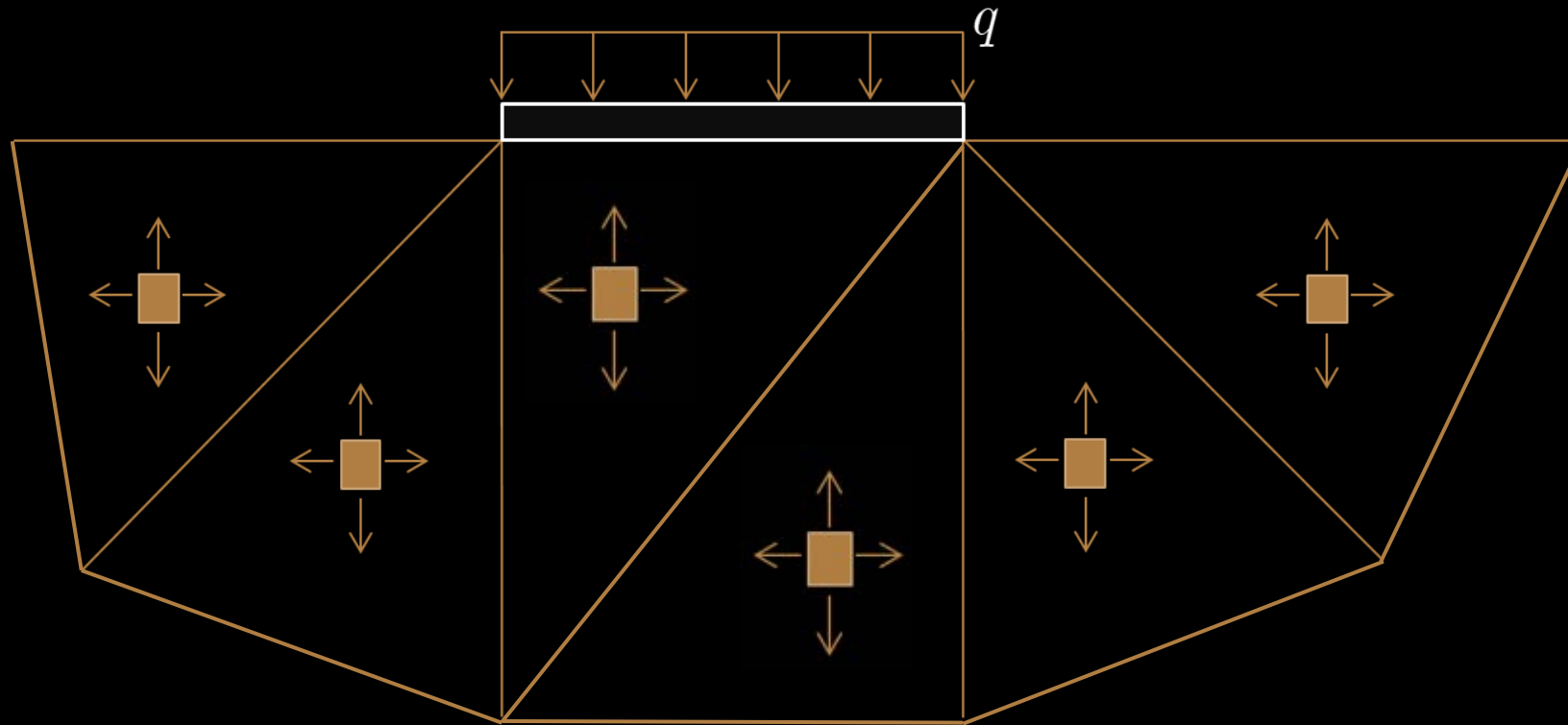
# The Optum approach

Example: footing on weightless Tresca soil



# The Optum approach

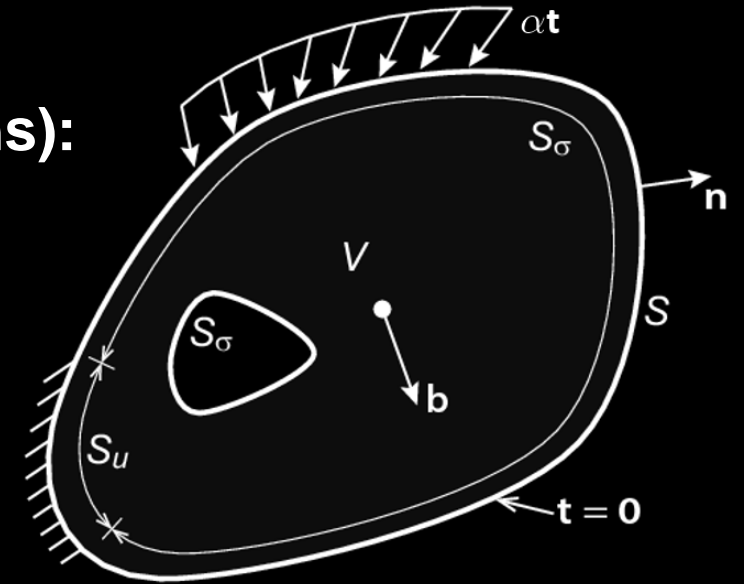
Example: footing on weightless Tresca soil



# The Optum approach

Variational principle (equivalent to governing equations):

$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & && \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$



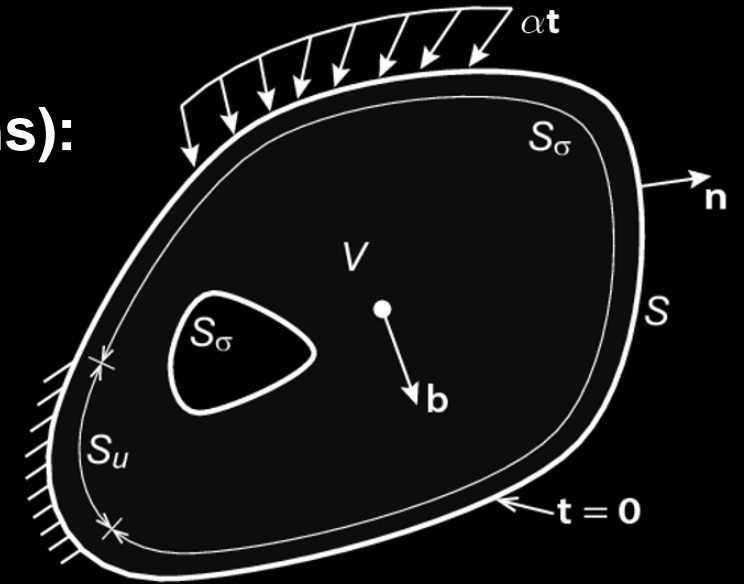
Discretize: replace continuous variables with discrete counterparts to obtain discrete optimization problem:

$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \mathbf{B}^\top \boldsymbol{\sigma} = \alpha \mathbf{f} + \mathbf{f}_0 \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$

# The Optum approach

Variational principle (equivalent to governing equations):

$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & && \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$



Discretize: replace continuous variables with discrete counterparts to obtain discrete optimization problem:

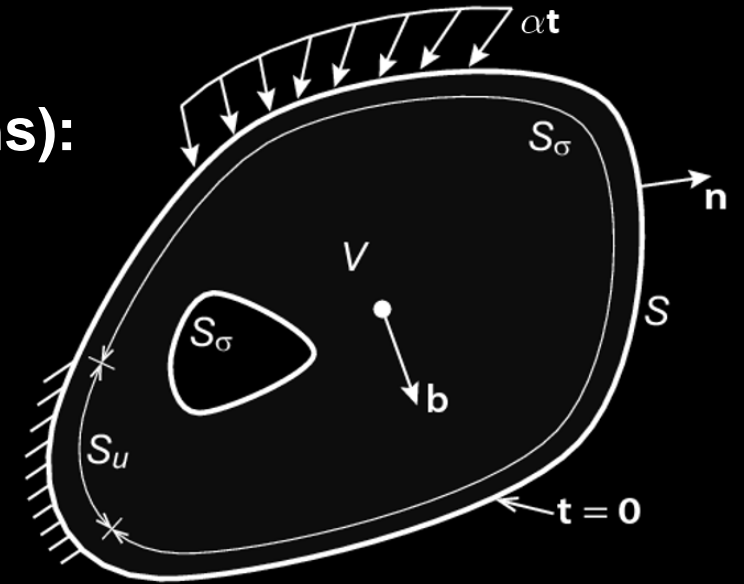
$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \mathbf{B}^\top \boldsymbol{\sigma} = \alpha \mathbf{f} + \mathbf{f}_0 \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$

Very efficient and robust algorithms now available (conic programming)

# The Optum approach

Variational principle (equivalent to governing equations):

$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & && \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$



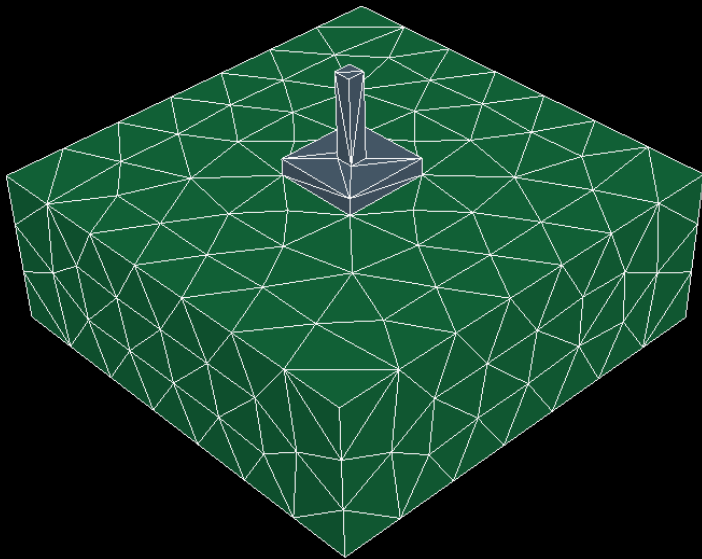
Discretize: replace continuous variables with discrete counterparts to obtain discrete optimization problem:

$$\begin{aligned} &\text{maximize} && \alpha \\ &\text{subject to} && \mathbf{B}^\top \boldsymbol{\sigma} = \alpha \mathbf{f} + \mathbf{f}_0 \\ & && F(\boldsymbol{\sigma}) \leq 0 \end{aligned}$$

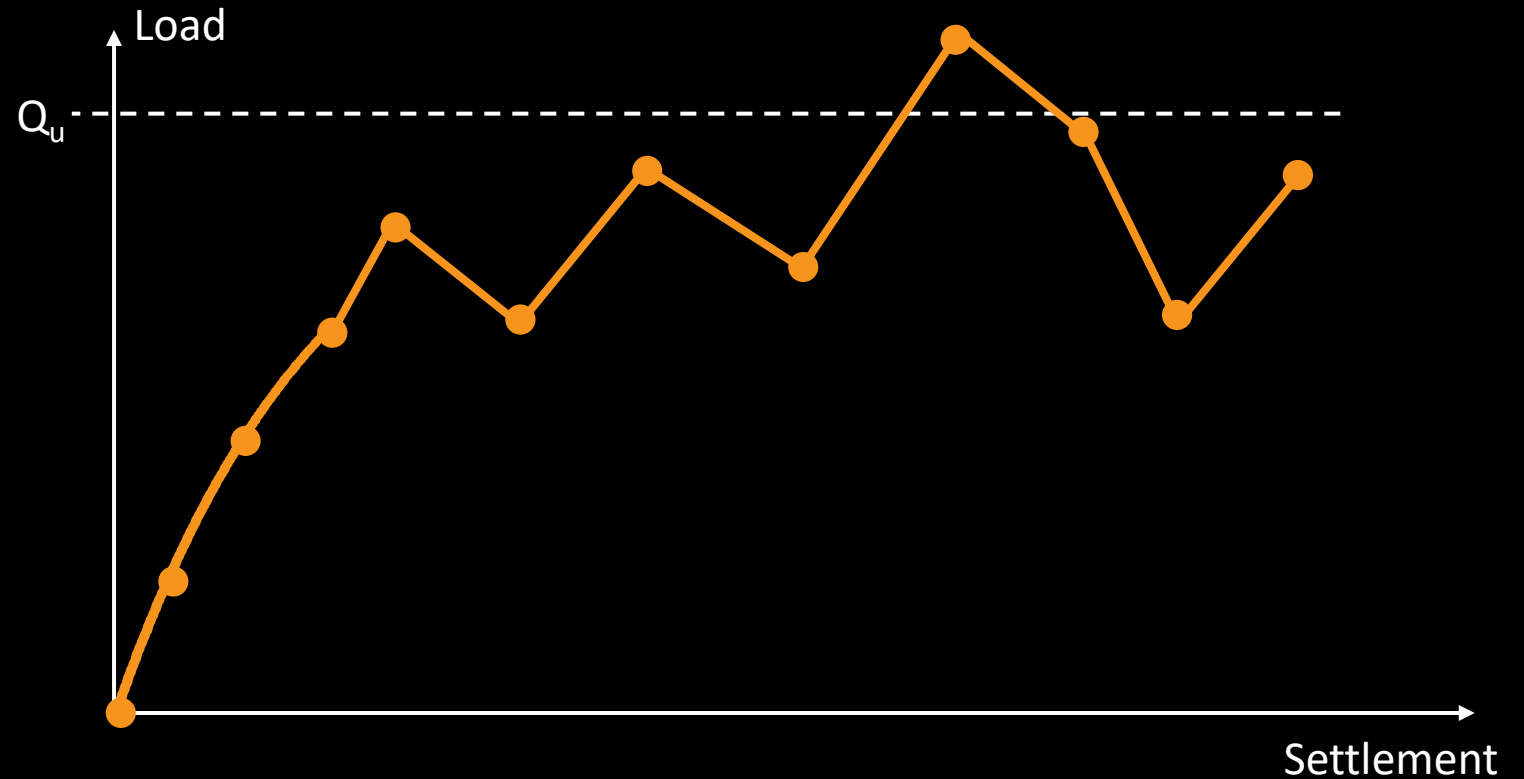
Upper bound formulation takes same form but with slightly different  $\mathbf{B}$ ,  $\mathbf{f}$ ,  $\mathbf{f}_0$



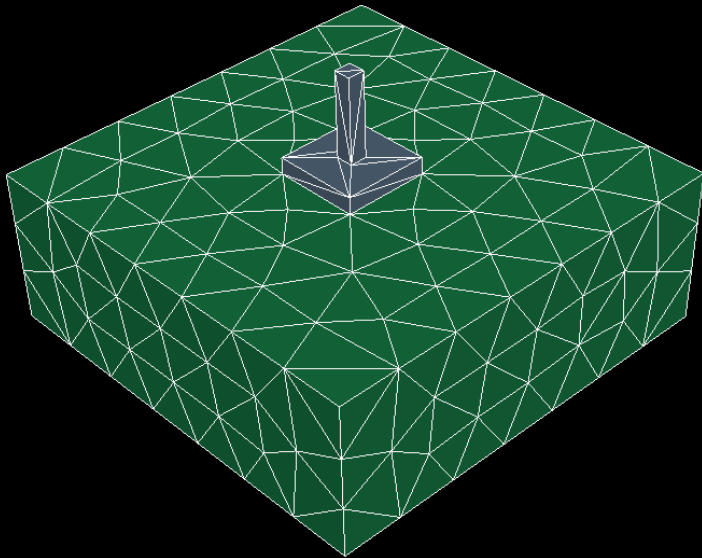
# The conventional FE approach



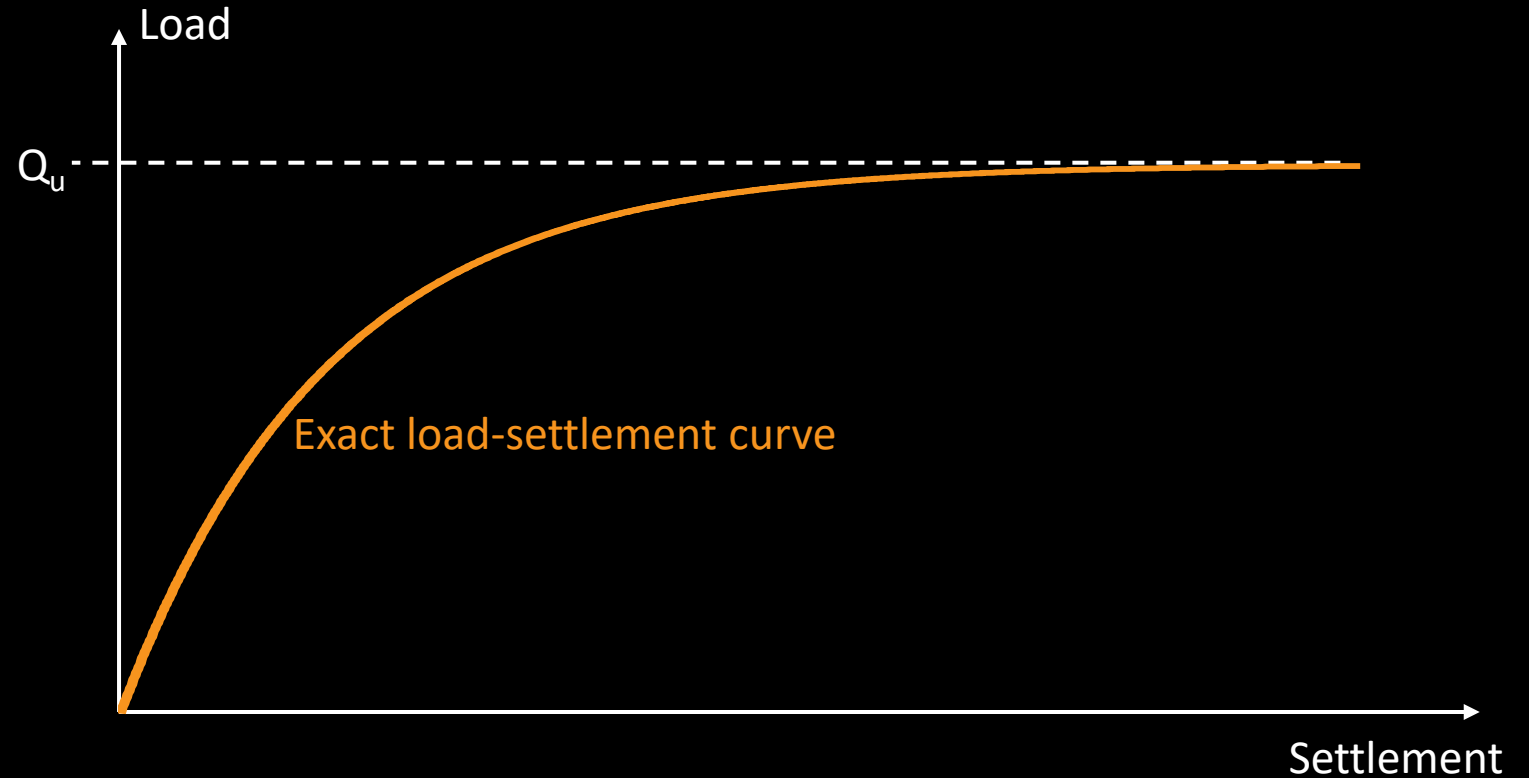
Increase load to failure:



# The Optum approach

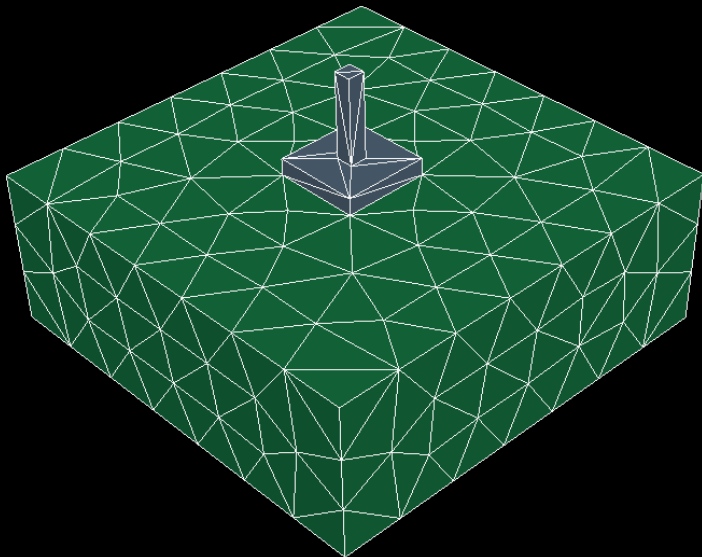


Increase load to failure:

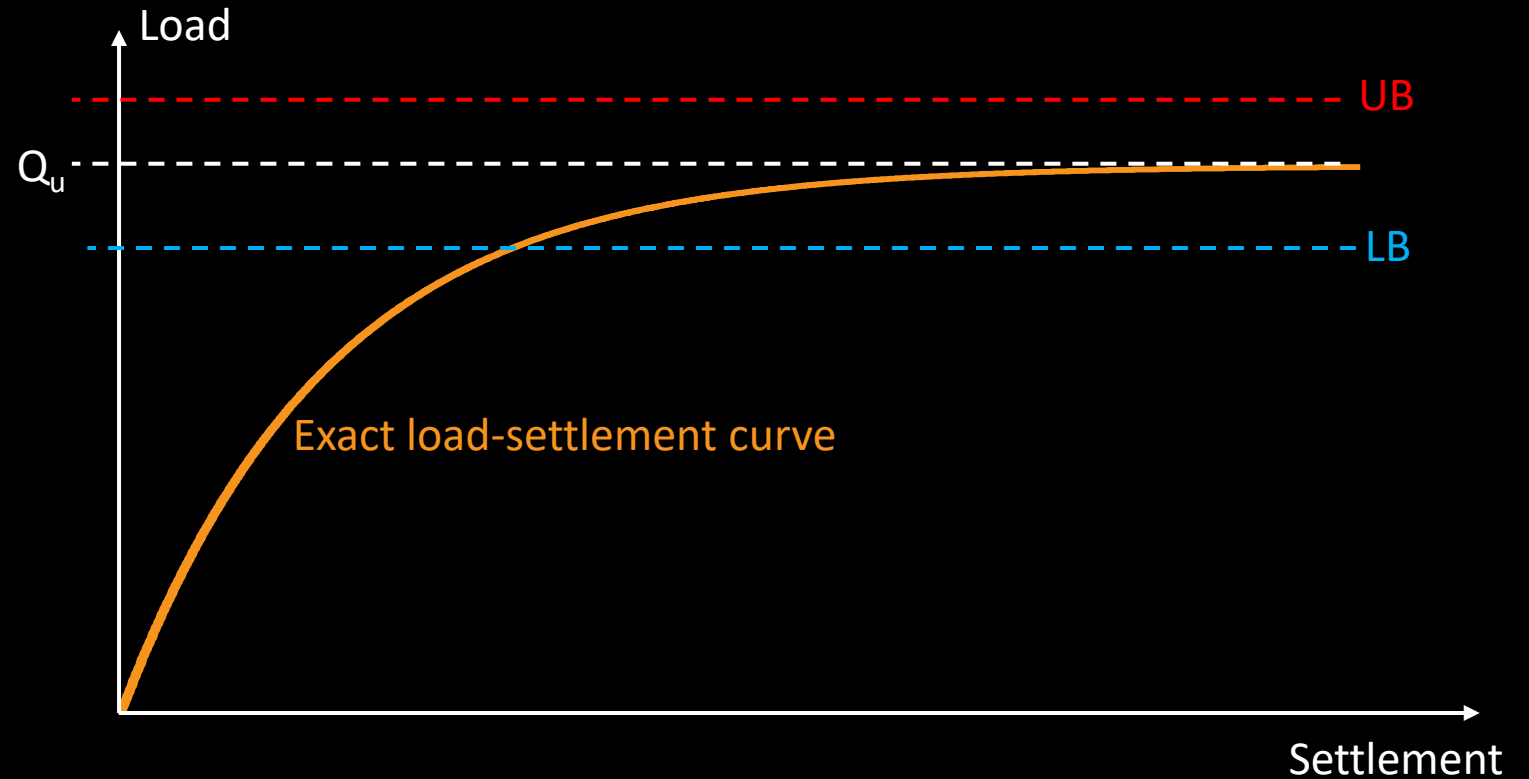


What is the limit load?

# The Optum approach

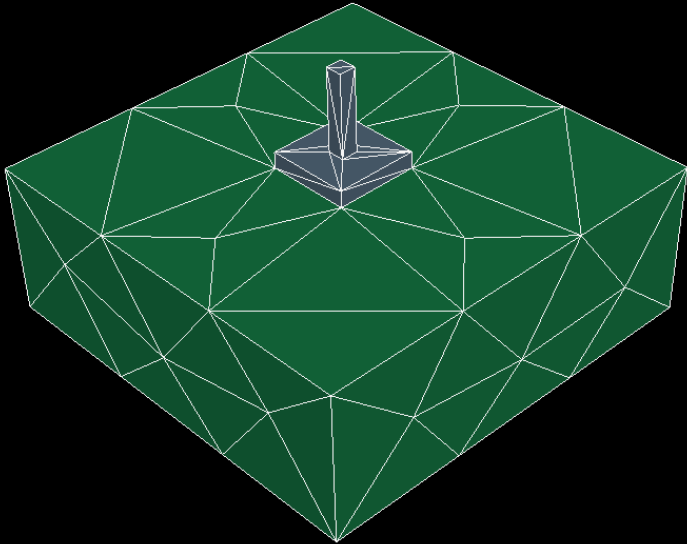


Increase load to failure:

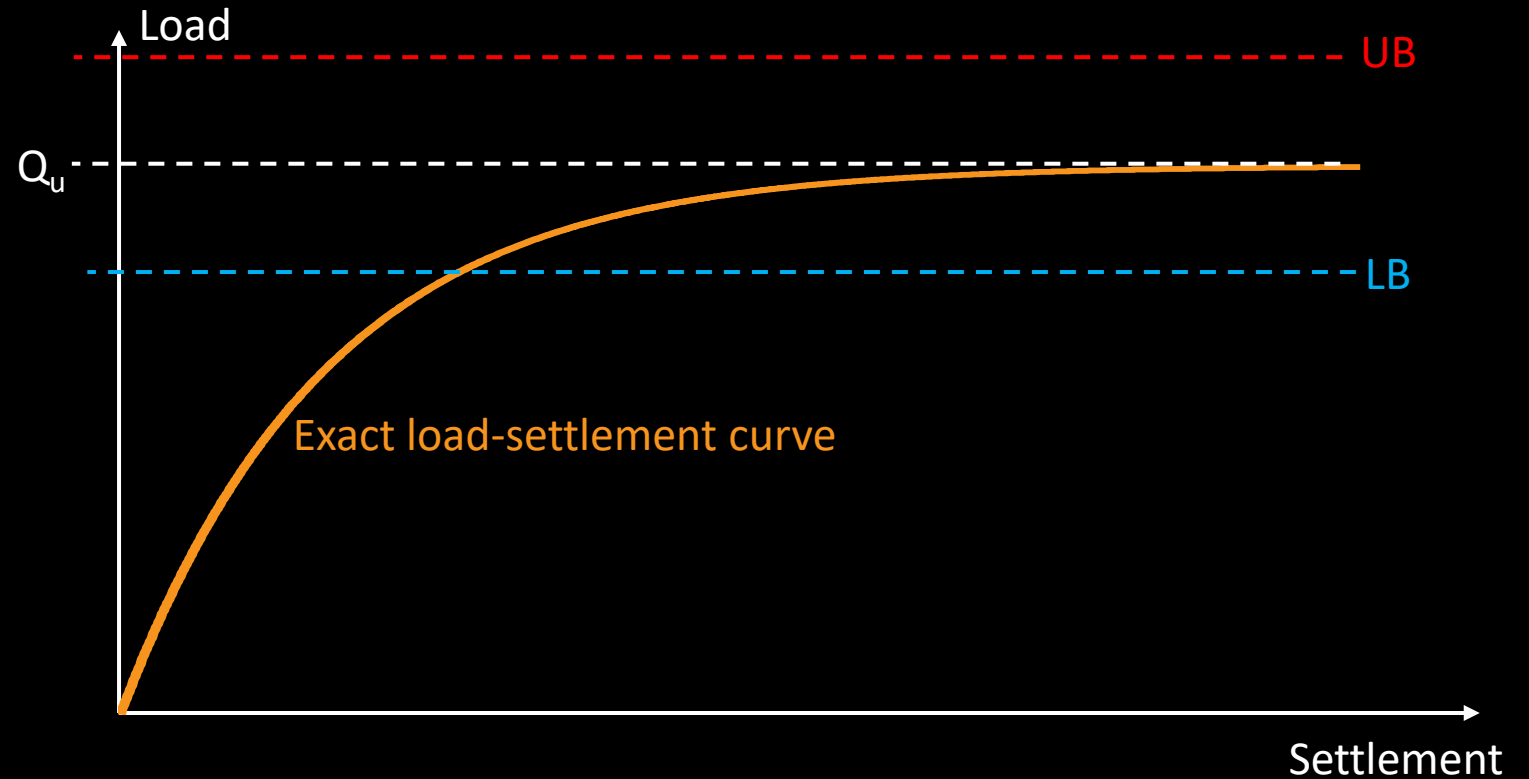


What is the limit load?

# The Optum approach



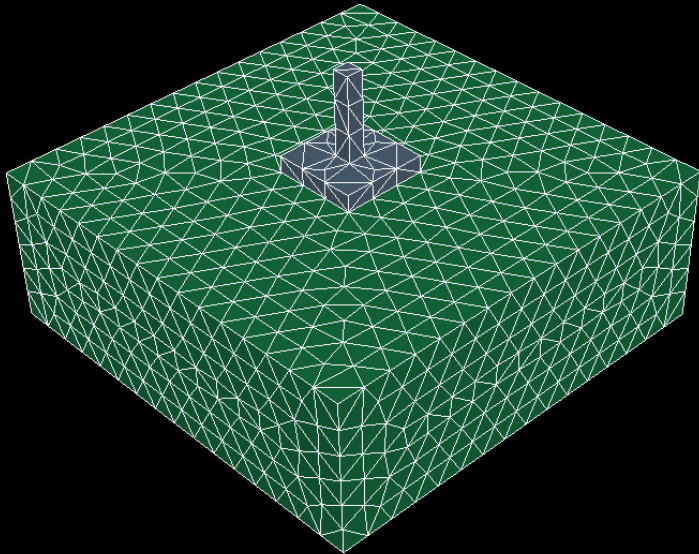
Increase load to failure:



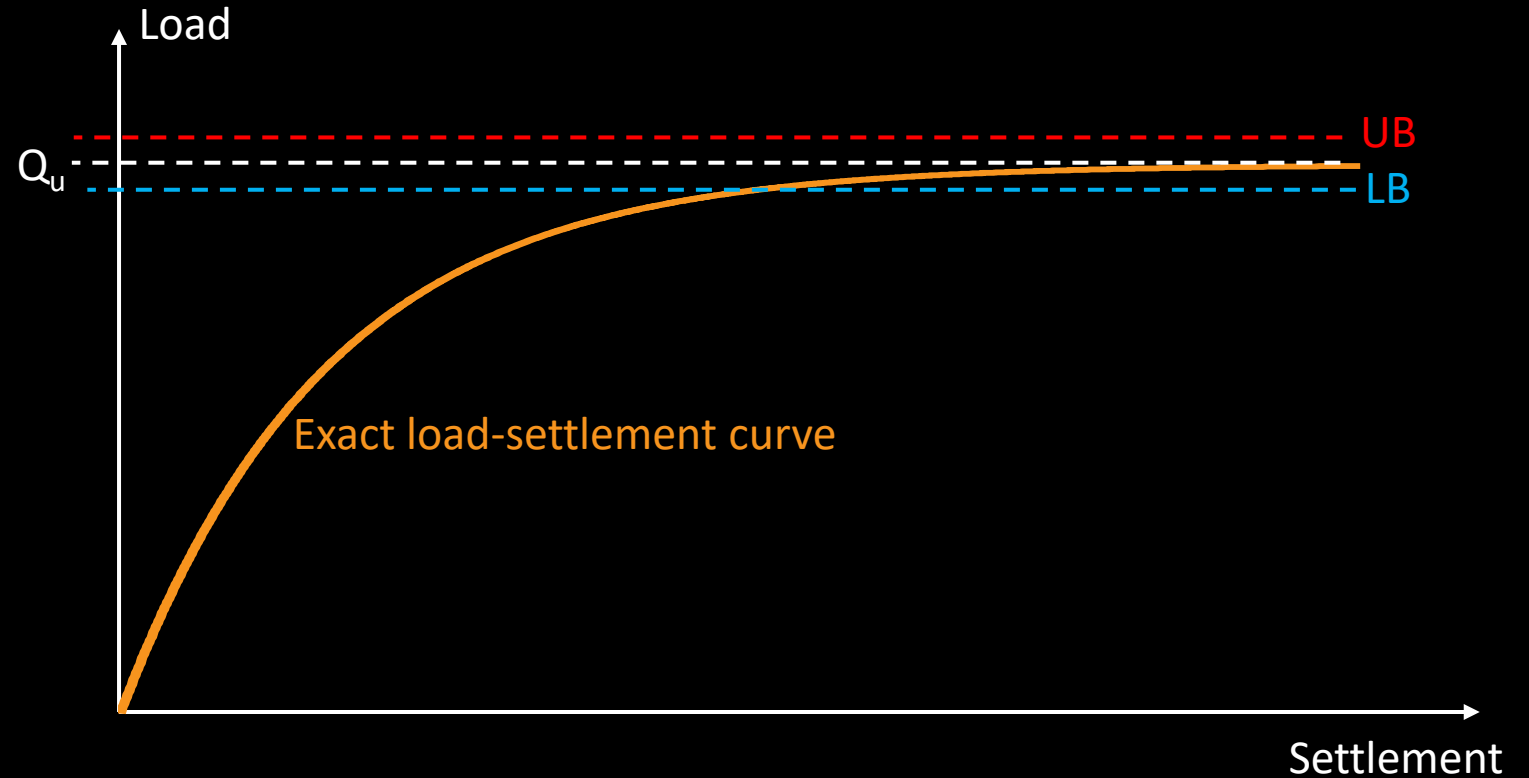
How accurate is the solution?



# The Optum approach

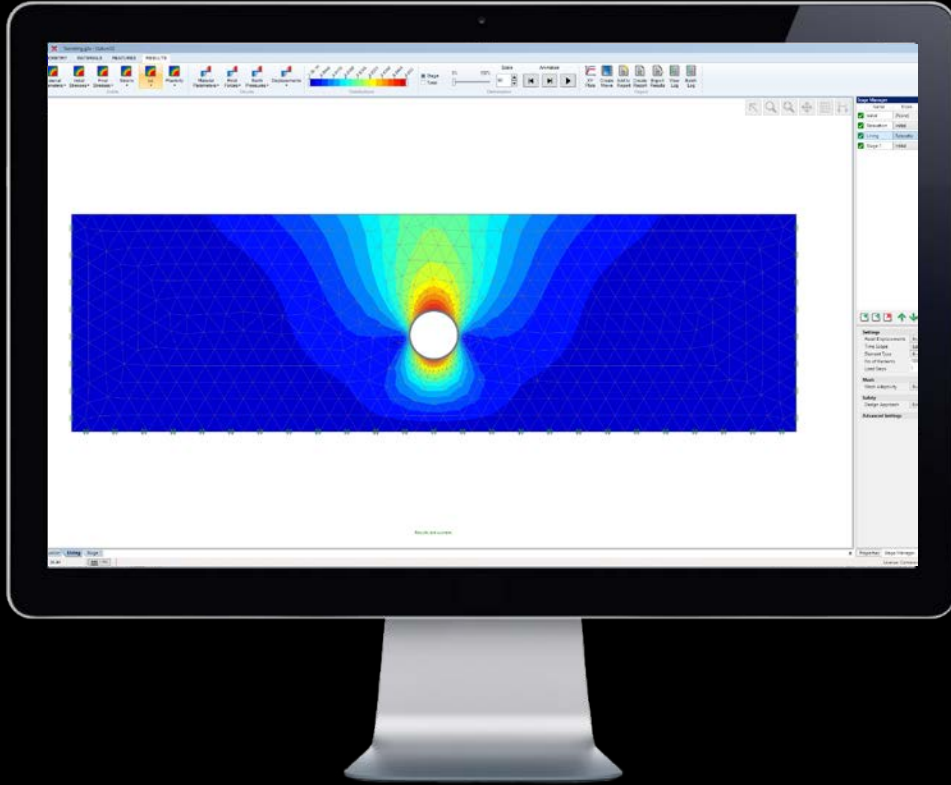


Increase load to failure:

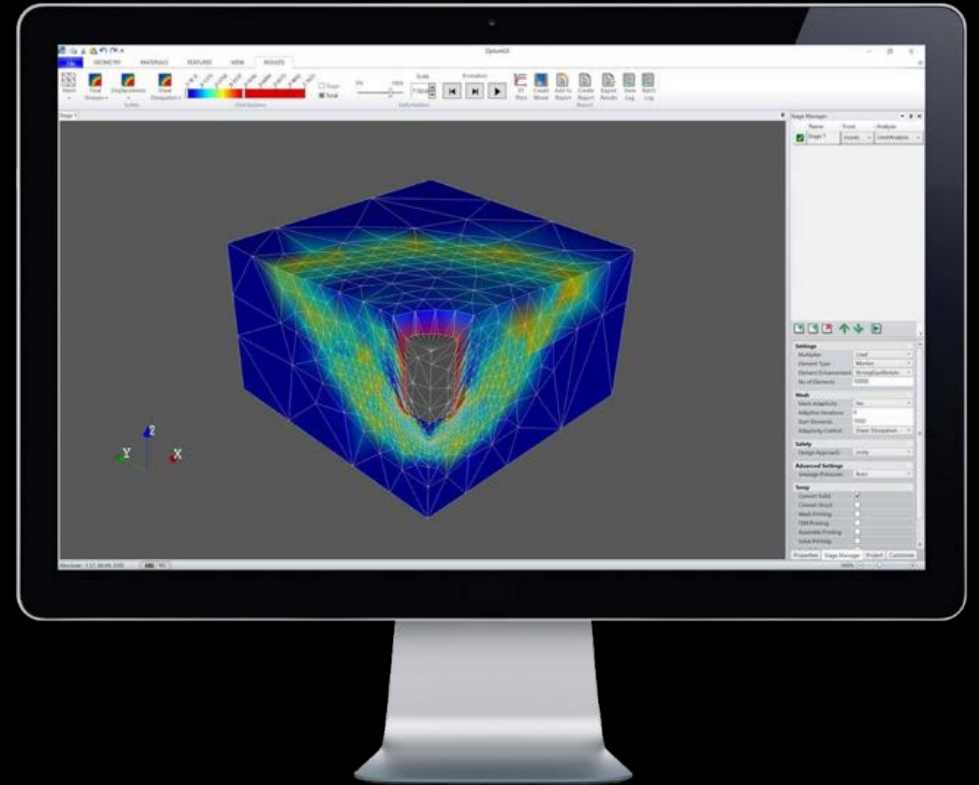


How accurate is the solution?

# Examples



OPTUM G2



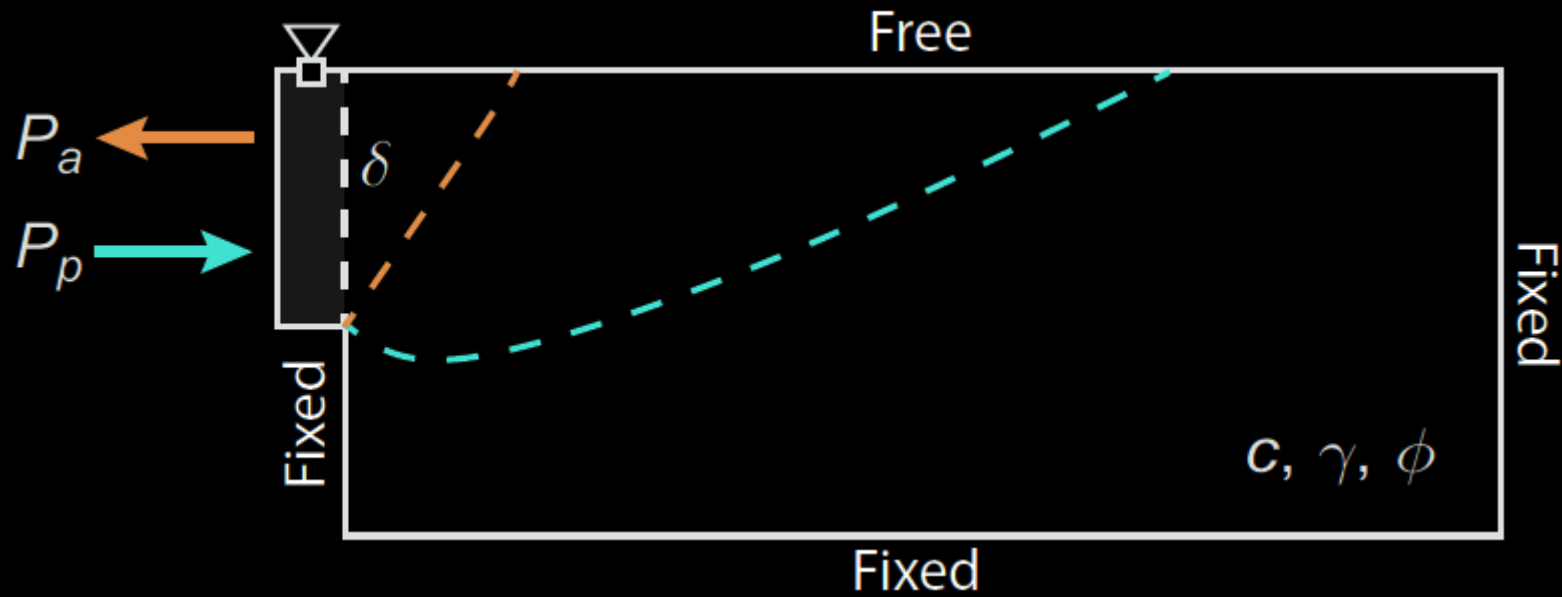
OPTUM G3

**Arbitrary problems can now be solved – to within a verified accuracy – in a reasonable amount of time**



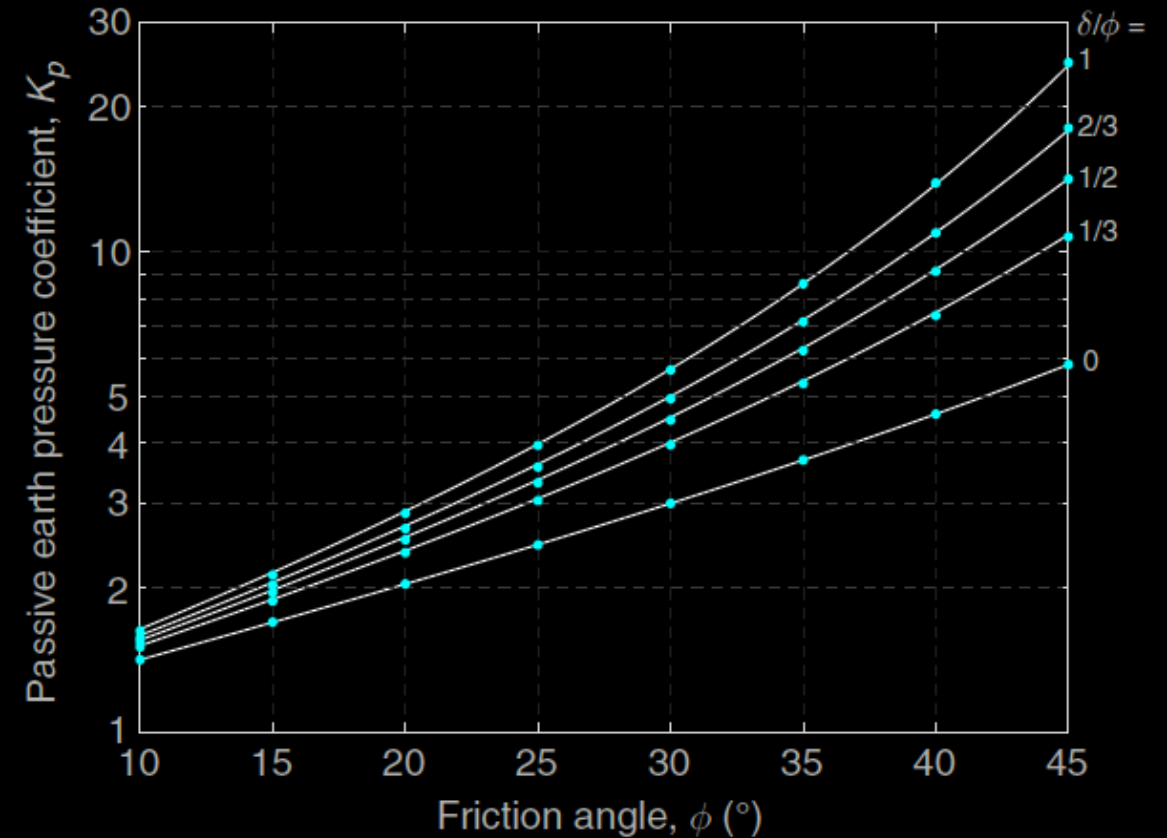
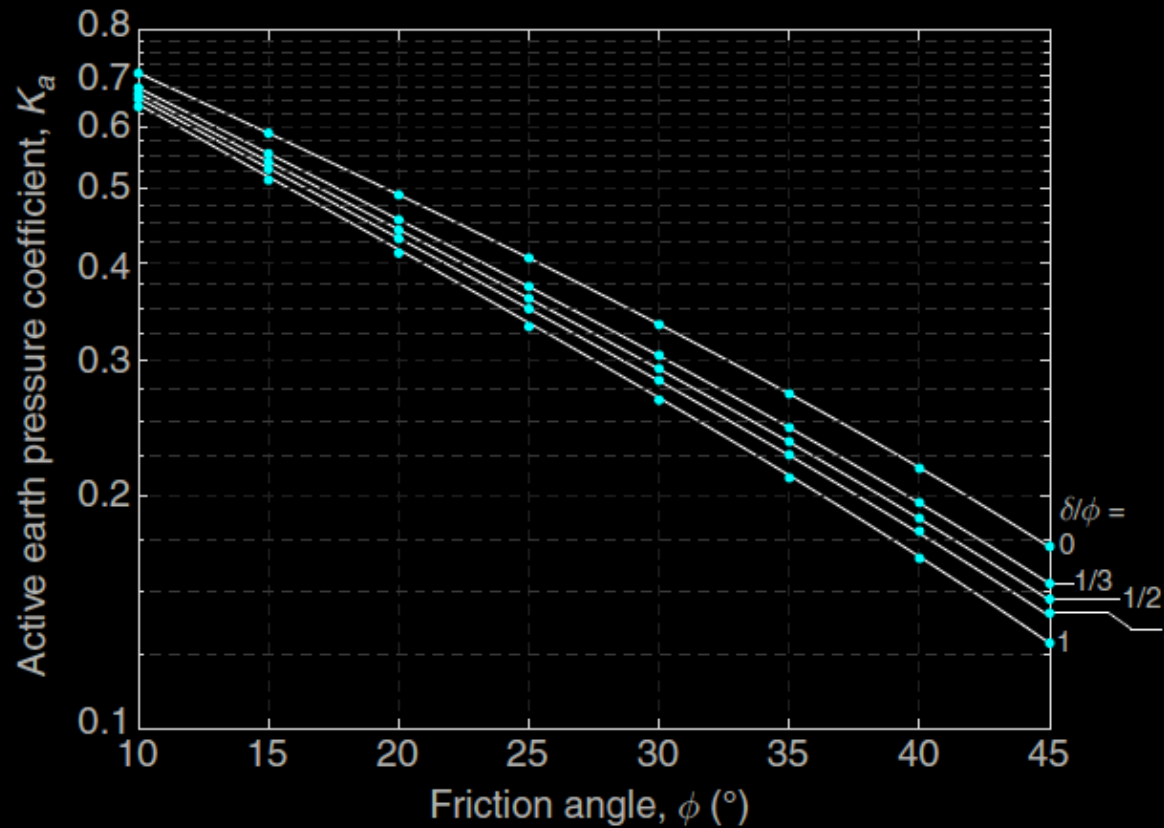
# Example

## Earth pressure coefficients



# Example

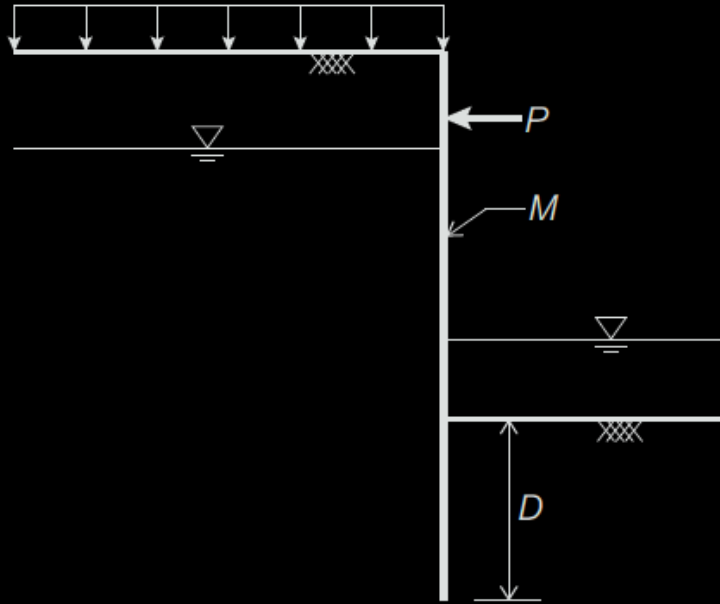
## Earth pressure coefficients



**Dots: FELA, curves: fits (see paper). Accuracy =  $\pm 1\%$**

# Example

## Embedded retaining walls

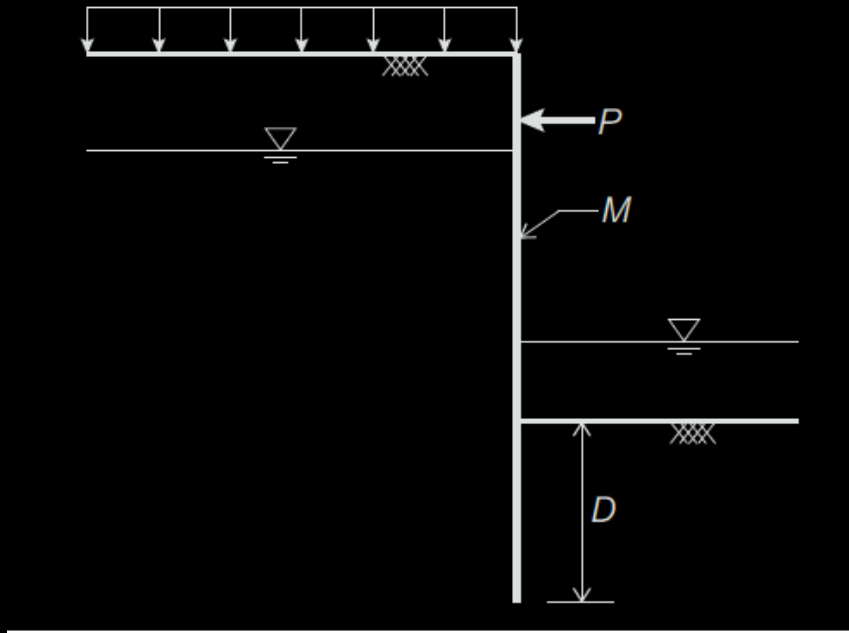


### Design variables:

- + Wall moment capacity ( $M$ )
- + Anchor capacity ( $P$ )
- + Embedment depth ( $D$ )

# Example

## Embedded retaining walls



### Design variables:

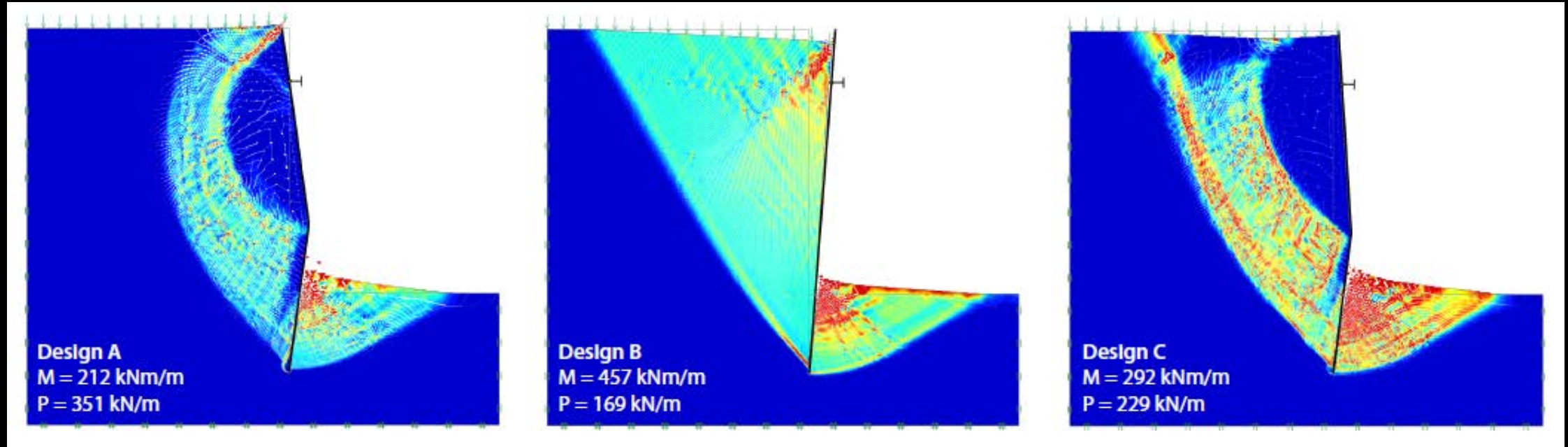
- + Wall moment capacity ( $M$ )
- + Anchor capacity ( $P$ )
- + Embedment depth ( $D$ )

### For given $D$ :

- + Minimize wall moment
- + Minimize anchor capacity
- + Minimize combination of wall moment capacity and anchor capacity

# Example

## Embedded retaining walls



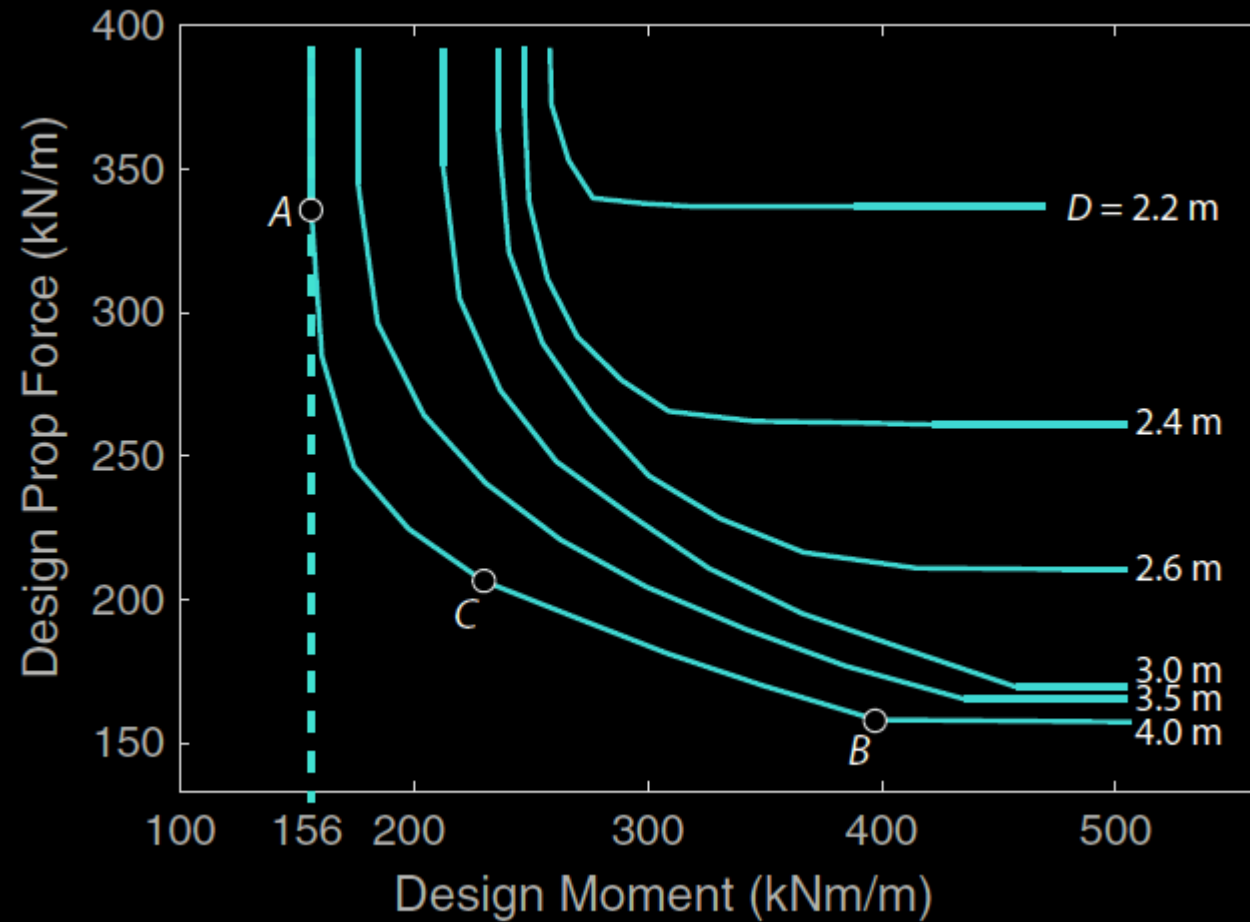
Min M (large P)

Min P (large M)

Compromise

# Example

## Embedded retaining walls





# The Optum approach

## Rigid plasticity

Equilibrium:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

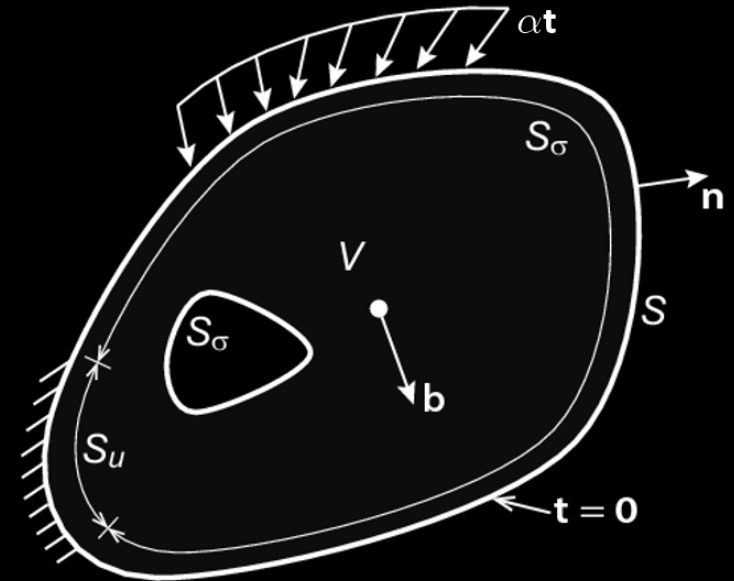
Static BC:  $\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t}$  on  $S_\sigma$

Strain-disp:  $\dot{\boldsymbol{\epsilon}}^p = \nabla \dot{\mathbf{u}}$

Yield condition:  $F(\boldsymbol{\sigma}) \leq 0$

Flow rule:  $\dot{\boldsymbol{\epsilon}}^p = \dot{\lambda} \frac{\partial F}{\partial \boldsymbol{\sigma}}$

Complementarity:  $\dot{\lambda} \geq 0, \quad \dot{\lambda} F(\boldsymbol{\sigma}) = 0$



## Variational formulation

maximize  $\alpha$

subject to  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

$\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t}$  on  $S_\sigma$

$F(\boldsymbol{\sigma}) \leq 0$

# The Optum approach

## Rigid plasticity

Equilibrium:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

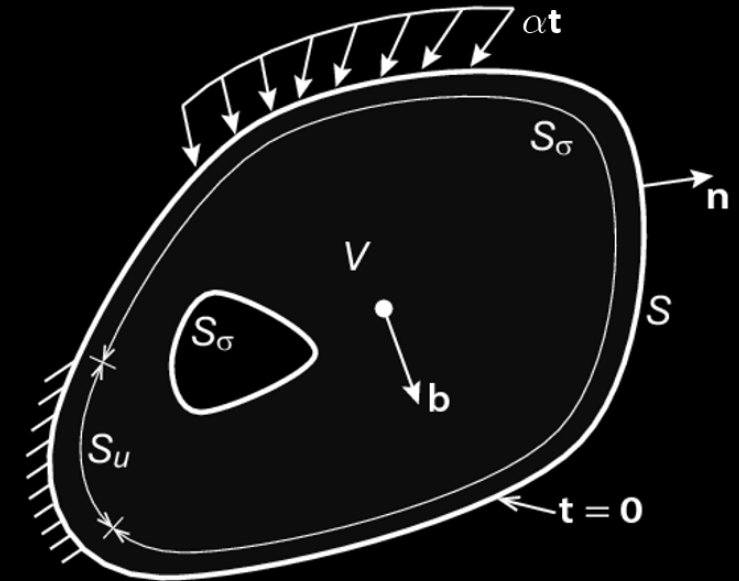
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## Variational formulation

maximize

$\alpha$

subject to

$$\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$$

$$\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \quad \text{on } S_\sigma$$

$$F(\boldsymbol{\sigma}) \leq 0$$

**What about settlements (elastoplasticity)?**

# The Optum approach

## Elastoplasticity

Equilibrium:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

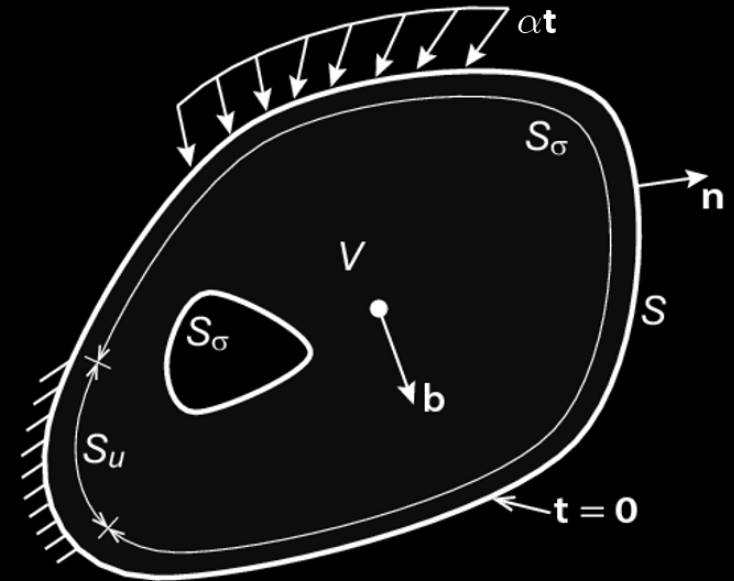
Static BC:  $\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t}$  on  $S_\sigma$

Strain-disp-Hooke:  $\nabla \dot{\mathbf{u}} = \mathbb{C} \dot{\boldsymbol{\sigma}} + \dot{\boldsymbol{\epsilon}}^p$

Yield condition:  $F(\boldsymbol{\sigma}) \leq 0$

Flow rule:  $\dot{\boldsymbol{\epsilon}}^p = \dot{\lambda} \frac{\partial F}{\partial \boldsymbol{\sigma}}$

Complementarity:  $\dot{\lambda} \geq 0, \quad \dot{\lambda} F(\boldsymbol{\sigma}) = 0$



## Variational formulation

maximize

$\alpha$

subject to

$$\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$$

$$\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \quad \text{on } S_\sigma$$

$$F(\boldsymbol{\sigma}) \leq 0$$

**What about settlements (elastoplasticity)?**

# The Optum approach

## Elastoplasticity

Equilibrium:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$

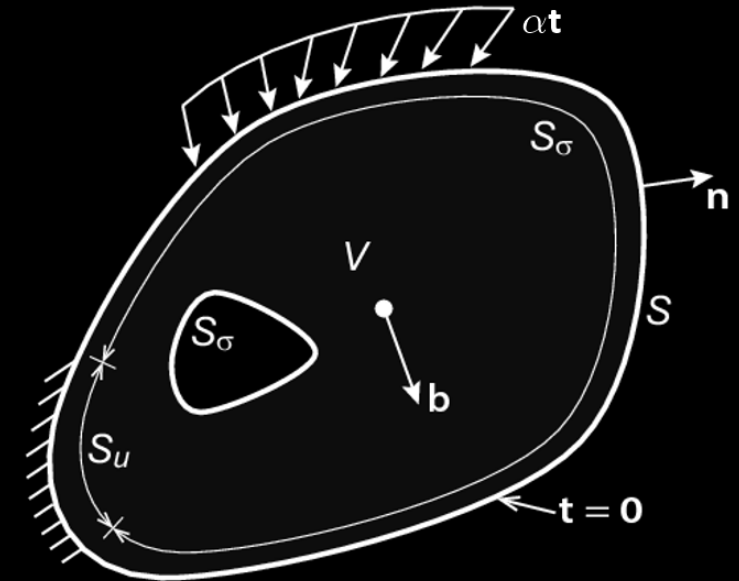
Static BC:  $\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t}$  on  $S_\sigma$

Strain-disp-Hooke:  $\nabla \dot{\mathbf{u}} = \mathbb{C} \dot{\boldsymbol{\sigma}} + \dot{\boldsymbol{\epsilon}}^p$

Yield condition:  $F(\boldsymbol{\sigma}) \leq 0$

Flow rule:  $\dot{\boldsymbol{\epsilon}}^p = \dot{\lambda} \frac{\partial F}{\partial \boldsymbol{\sigma}}$

Complementarity:  $\dot{\lambda} \geq 0, \quad \dot{\lambda} F(\boldsymbol{\sigma}) = 0$



## Variational formulation

maximize  $\alpha - \int_V \frac{1}{2} \Delta \boldsymbol{\sigma} \cdot \mathbb{C} \Delta \boldsymbol{\sigma} dV$   
subject to  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$   
 $\mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t}$  on  $S_\sigma$   
 $F(\boldsymbol{\sigma}) \leq 0$

**What about settlements (elastoplasticity)?**

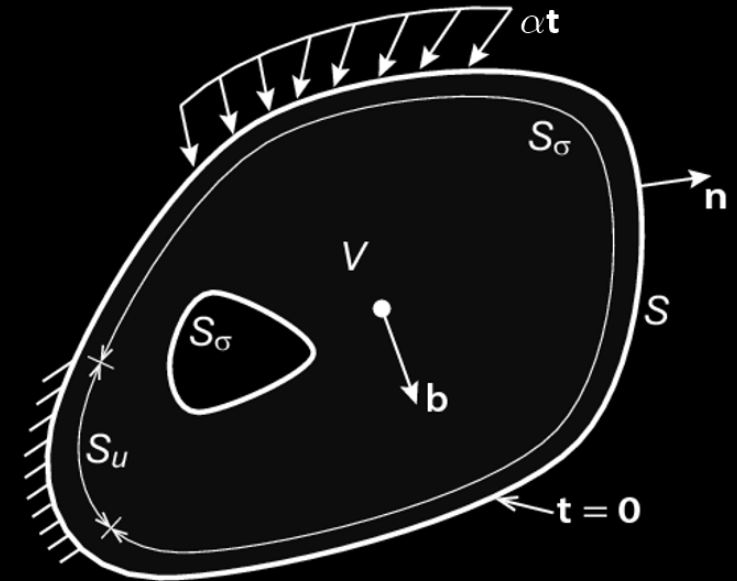
# The Optum approach

## Rigid plasticity

$$\begin{array}{ll}\text{maximize} & \alpha \\ \text{subject to} & \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & F(\boldsymbol{\sigma}) \leq 0\end{array}$$

## Elastoplasticity

$$\begin{array}{ll}\text{maximize} & \alpha - \int_V \frac{1}{2} \Delta \boldsymbol{\sigma} \cdot \mathbb{C} \Delta \boldsymbol{\sigma} \, dV \\ \text{subject to} & \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & F(\boldsymbol{\sigma}) \leq 0\end{array}$$



Similar modifications to reproduce governing equations of hardening plasticity, coupled pore pressure-deformation, dynamics, and more

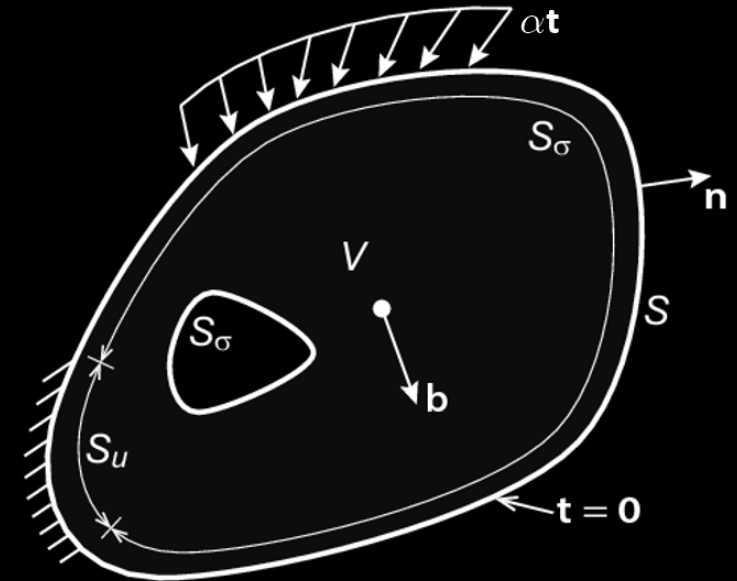
# The Optum approach

## Rigid plasticity

$$\begin{array}{ll}\text{maximize} & \alpha \\ \text{subject to} & \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & F(\boldsymbol{\sigma}) \leq 0\end{array}$$

## Elastoplasticity

$$\begin{array}{ll}\text{maximize} & \alpha - \int_V \frac{1}{2} \Delta \boldsymbol{\sigma} \cdot \mathbb{C} \Delta \boldsymbol{\sigma} \, dV \\ \text{subject to} & \nabla \cdot \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0} \\ & \mathbf{n} \cdot \boldsymbol{\sigma} = \alpha \mathbf{t} \text{ on } S_\sigma \\ & F(\boldsymbol{\sigma}) \leq 0\end{array}$$



**OPTUM is general FE – not just limit analysis – but approached from the view of Euler's maximum/minimum postulate**

# The Optum approach

Alternative narrative: limit analysis follows as a special (and useful) case of elastoplasticity:

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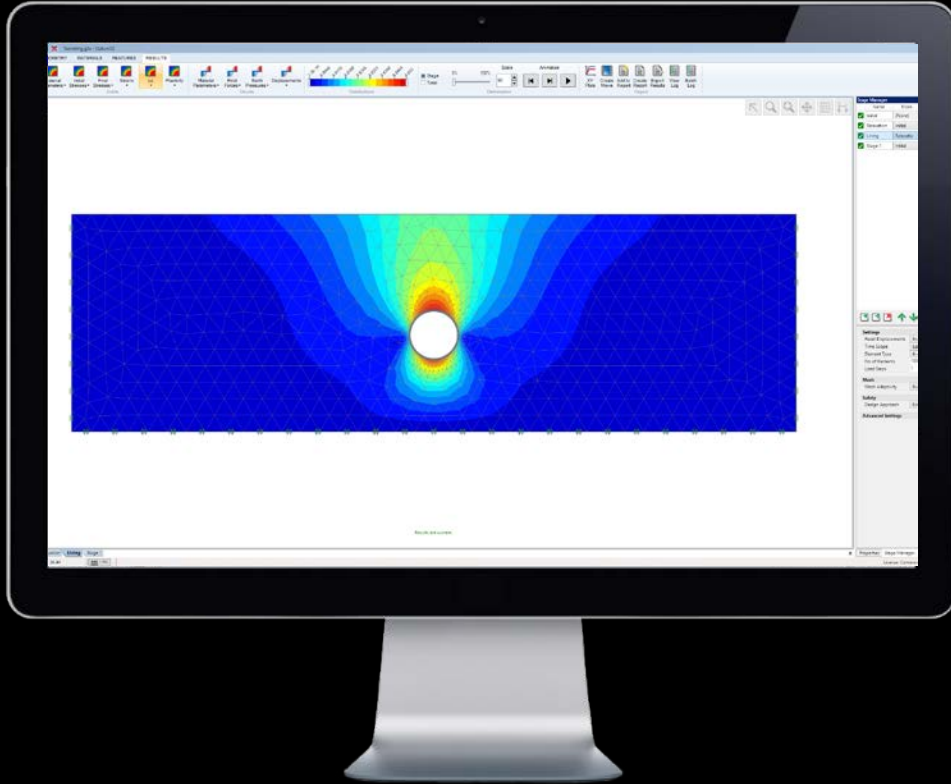
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# The Optum approach

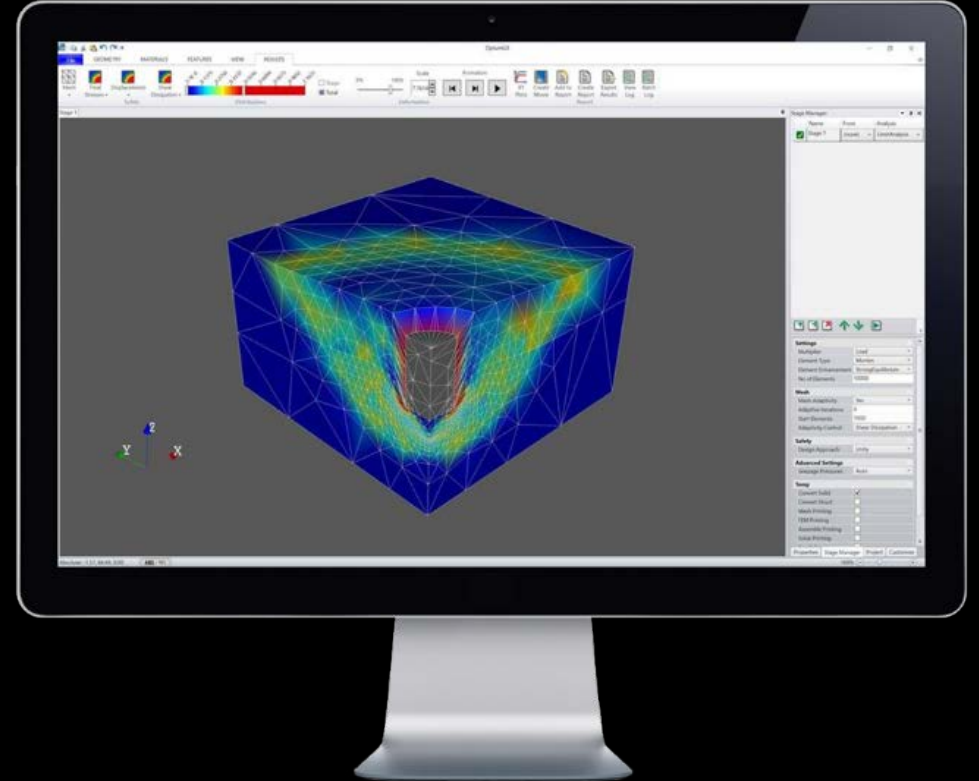
## Summary

- + Same governing equations but approached differently
- + No limitations in terms of physics that can be dealt with
- + Significant advantages in terms of computational efficiency and robustness
- + Ability to compute rigorous error estimates (upper/lower)
- + Ability to provide direct answers to direct questions, e.g. what is the limit load?
- + Ability to deal directly with engineering design, c.f. sheet pile design charts

# Future developments



OPTUM G2



OPTUM G3

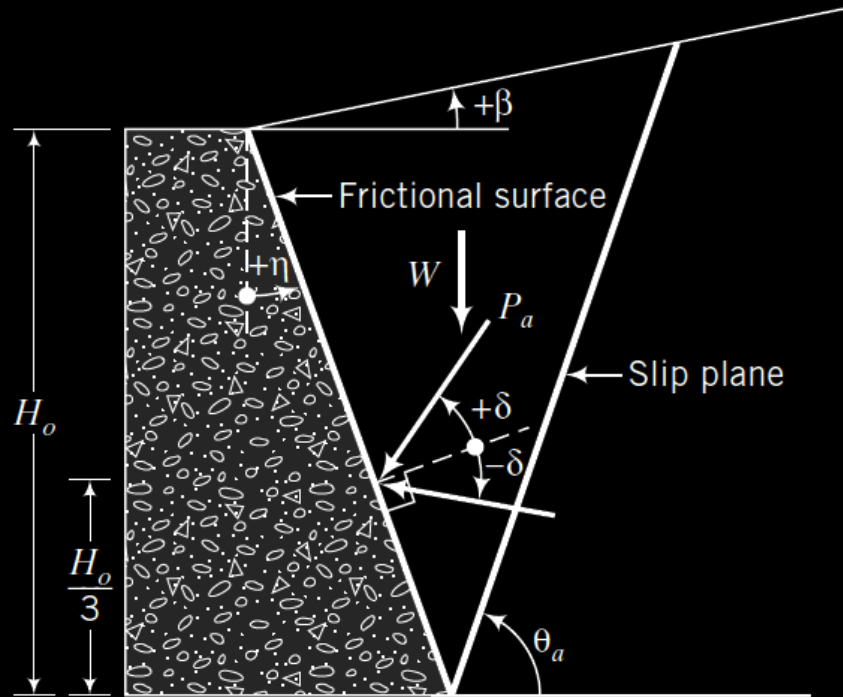
# Future developments



**Future developments**

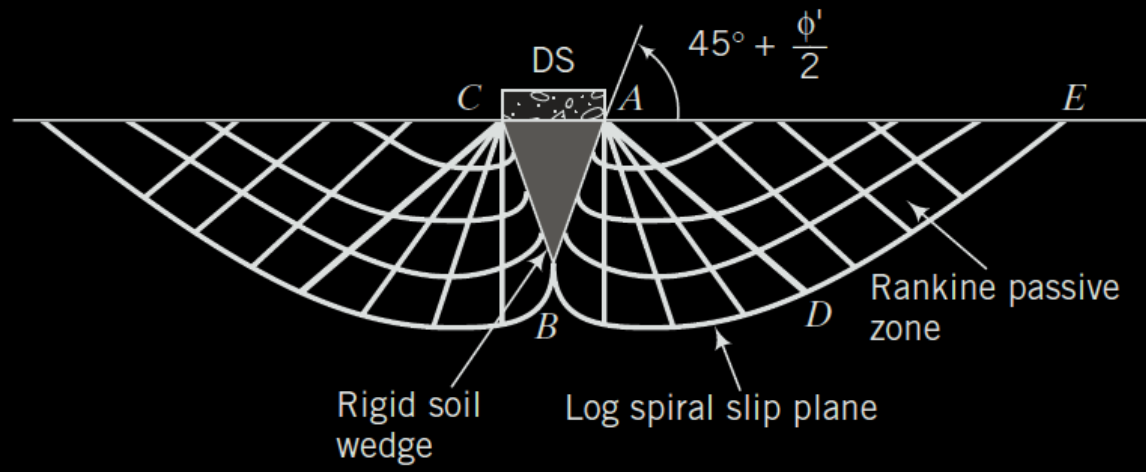
**The world is 3D –  
Why do we then use 2D?**

# Retaining walls



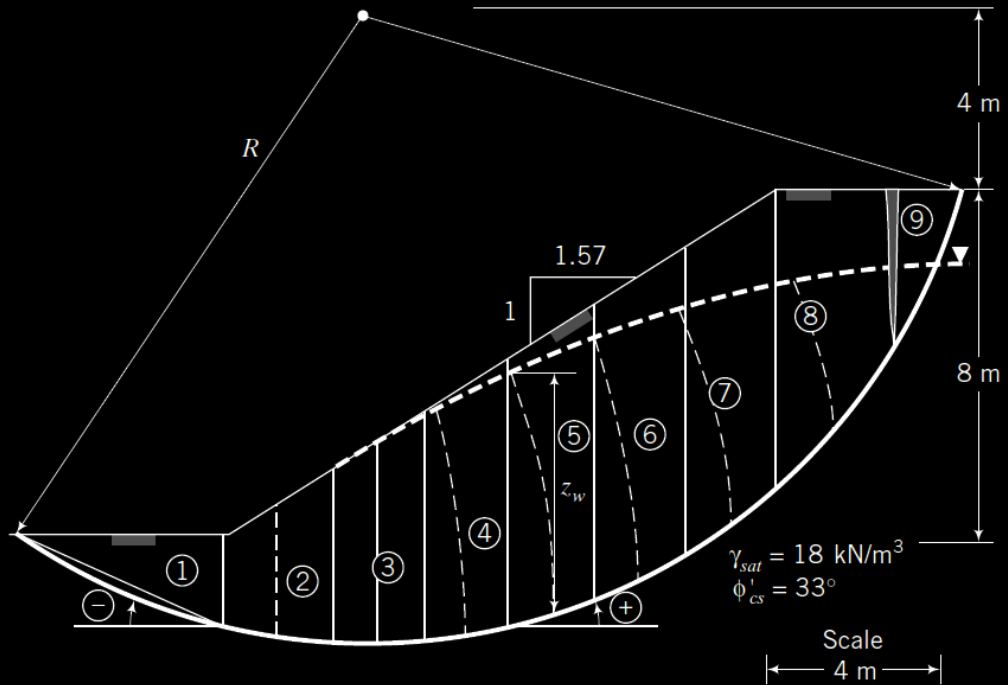


# Foundations



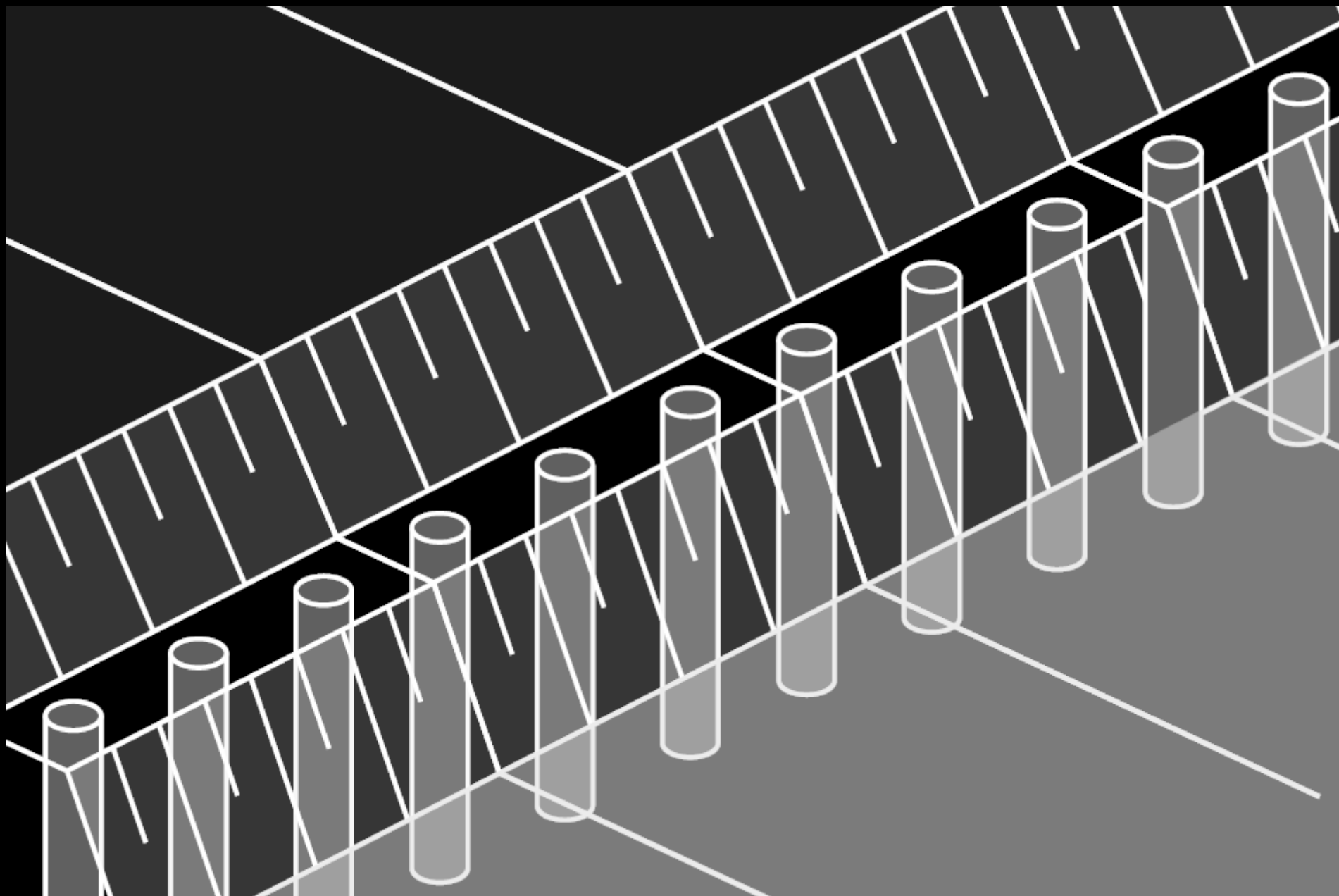


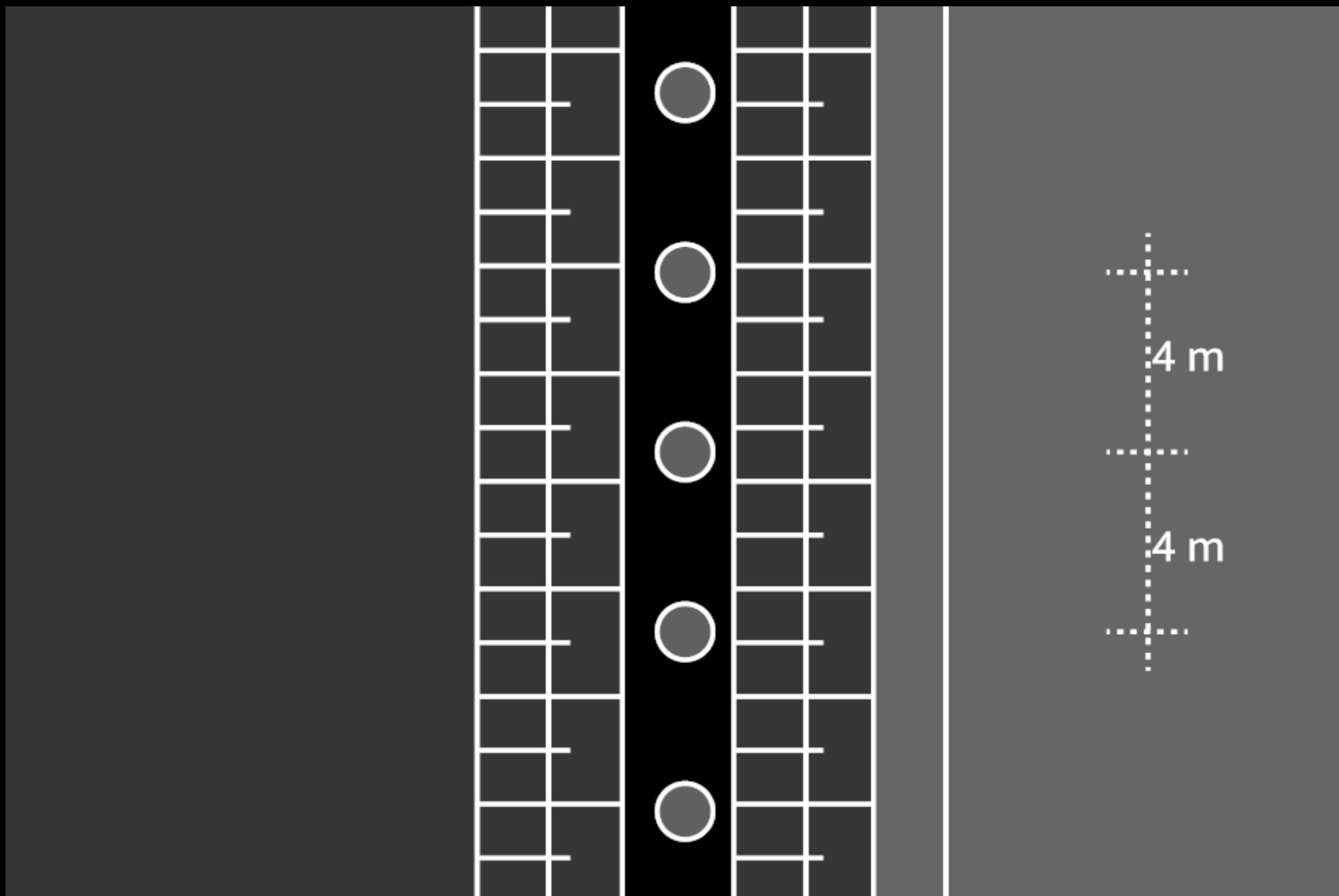
# Slopes

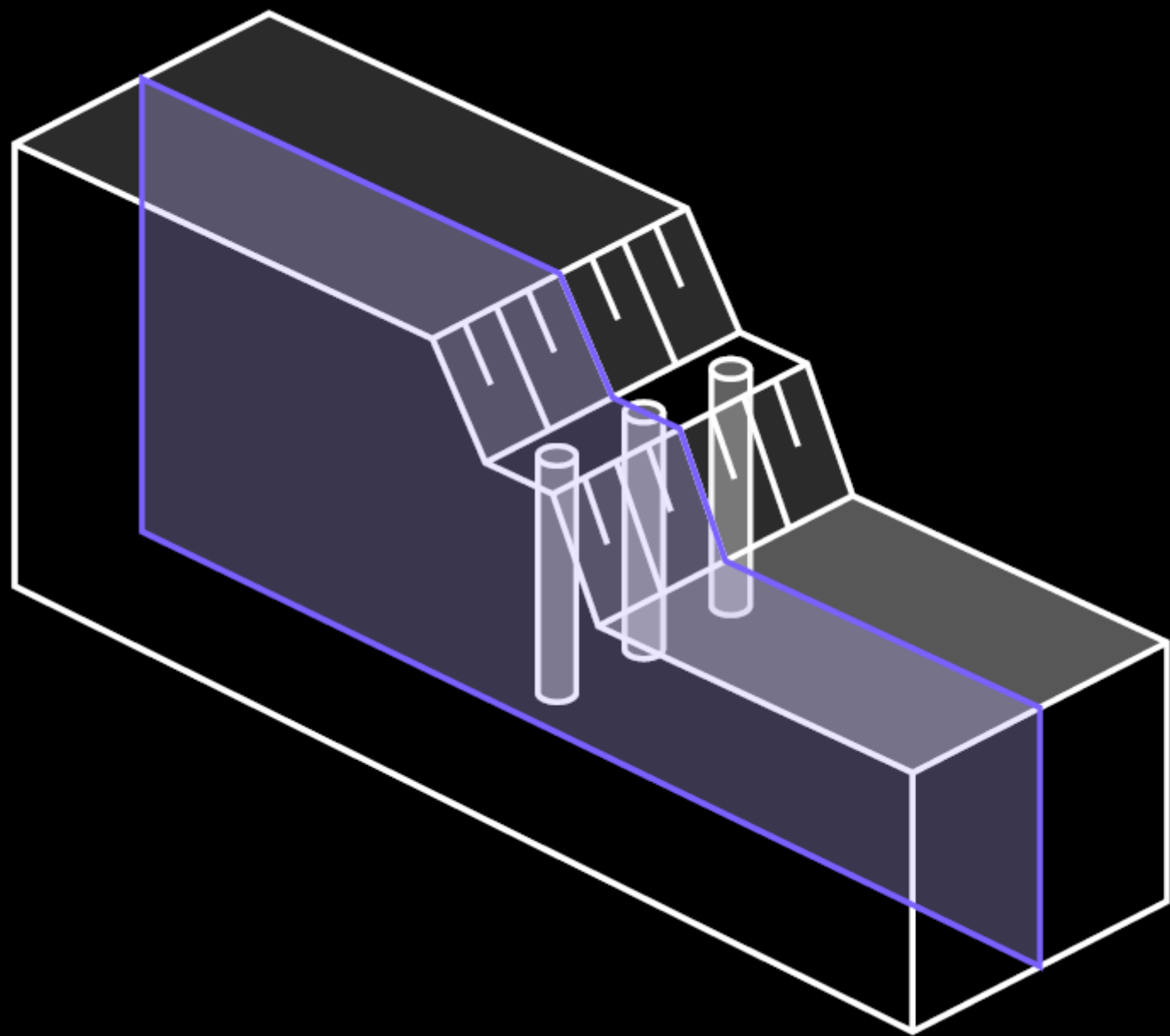


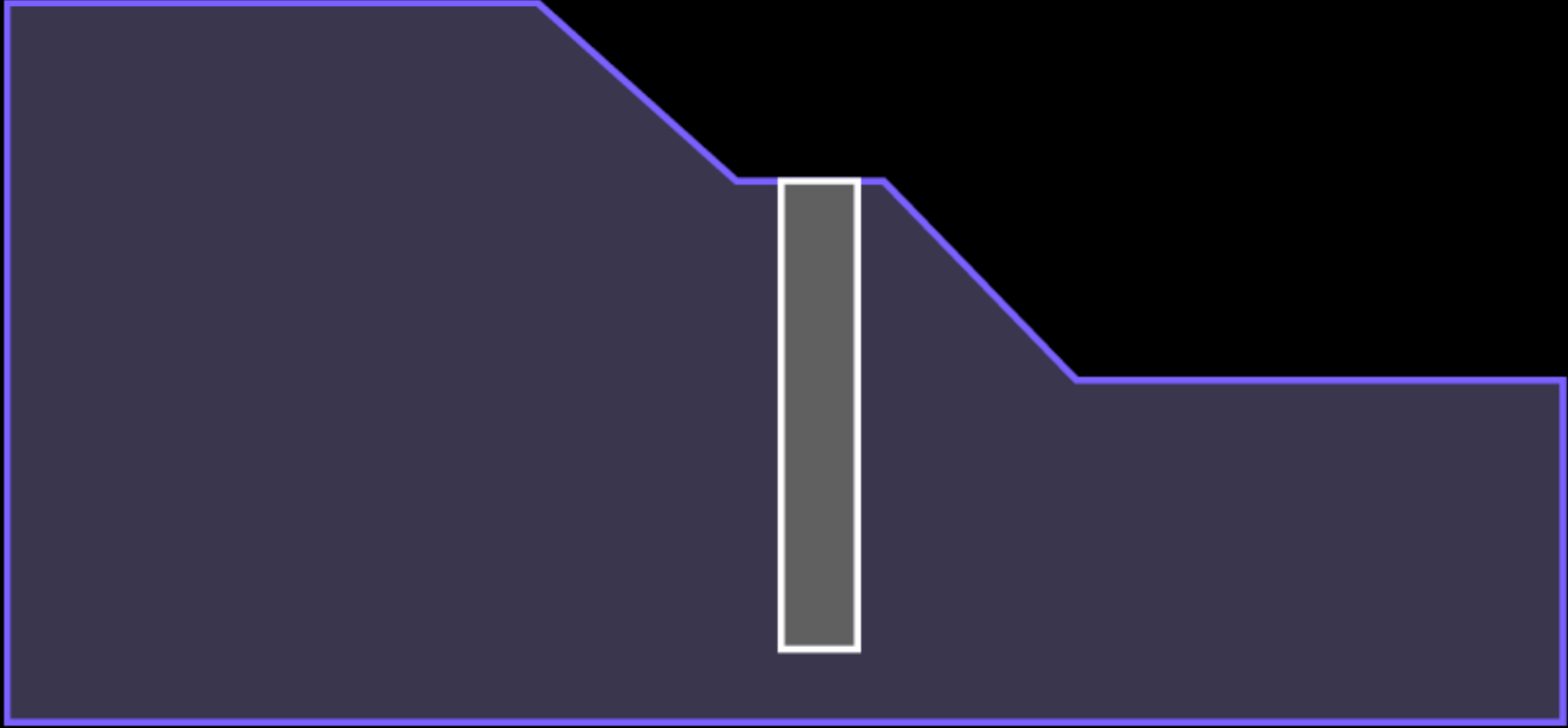
# **Example 1**

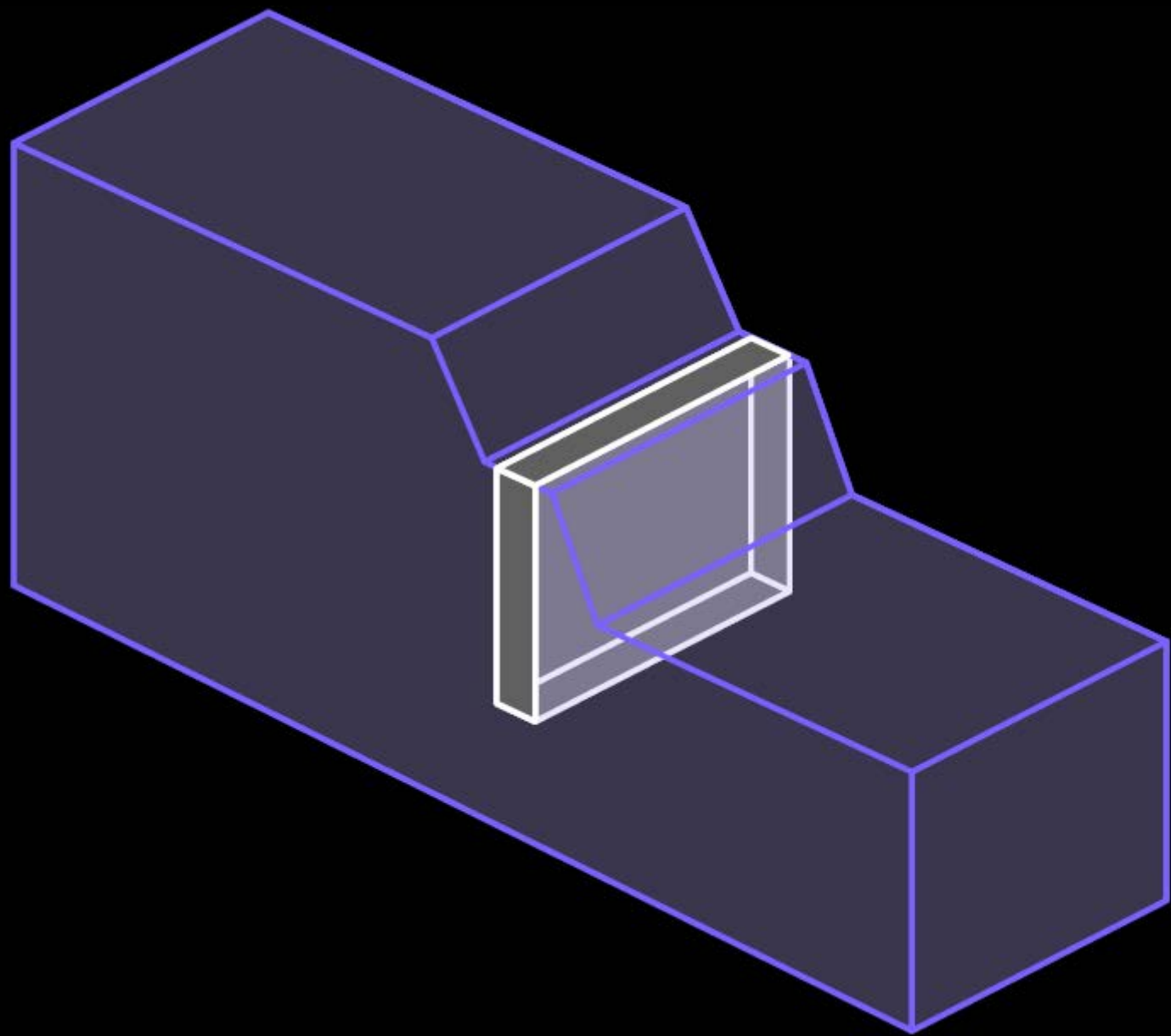
**Pile reinforced slope**







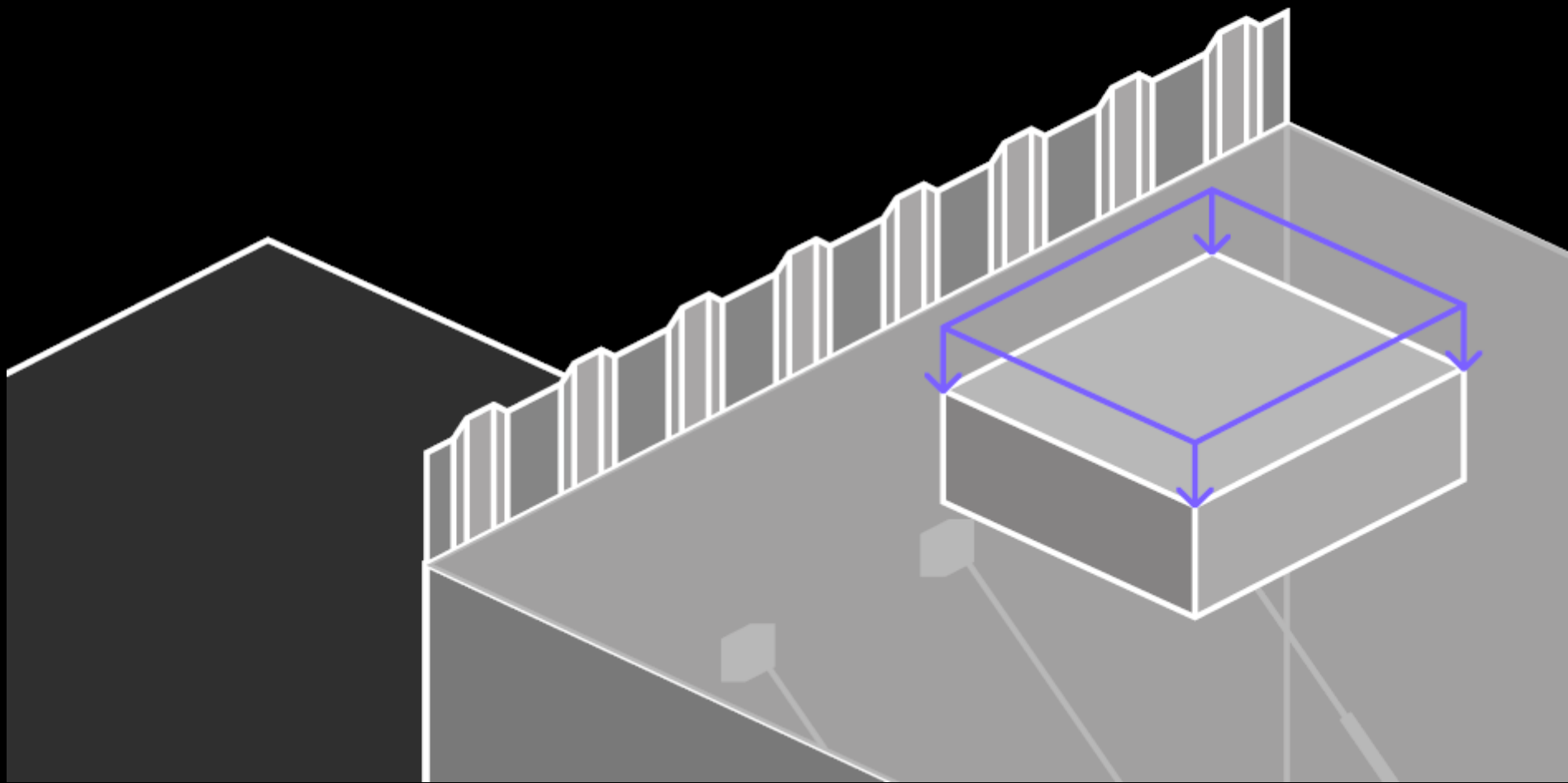


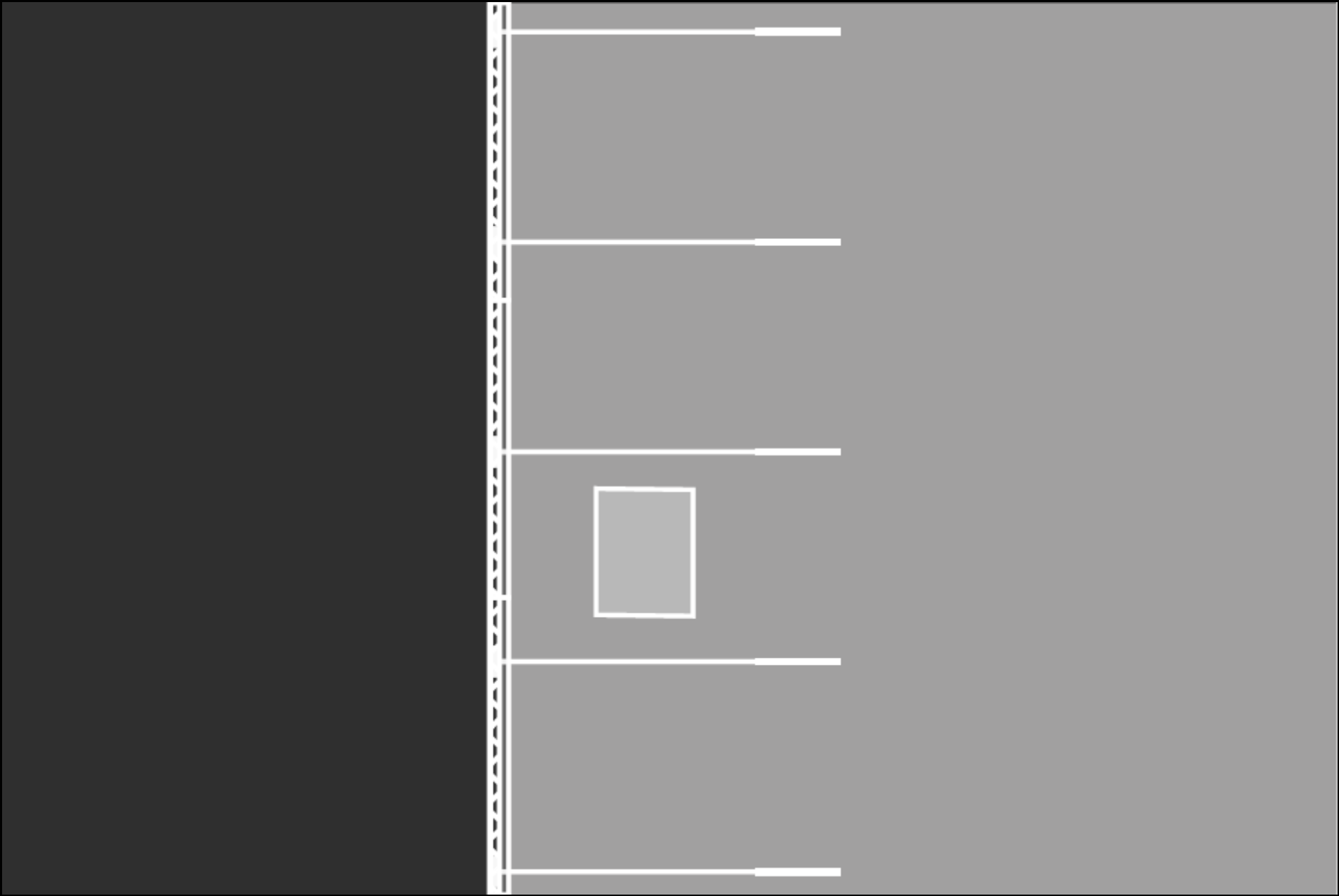


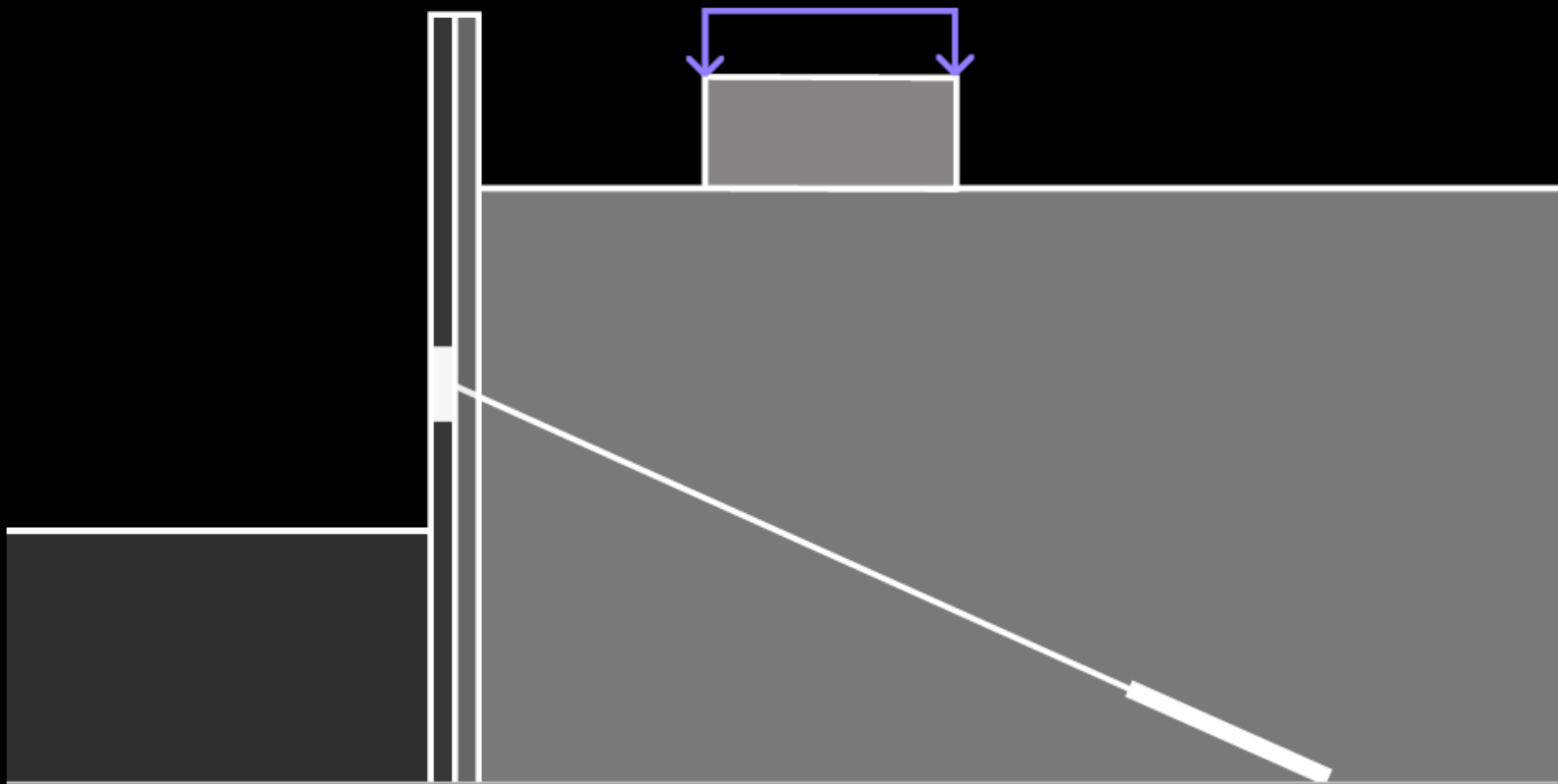


# **Example 2**

## **Foundation settlement**

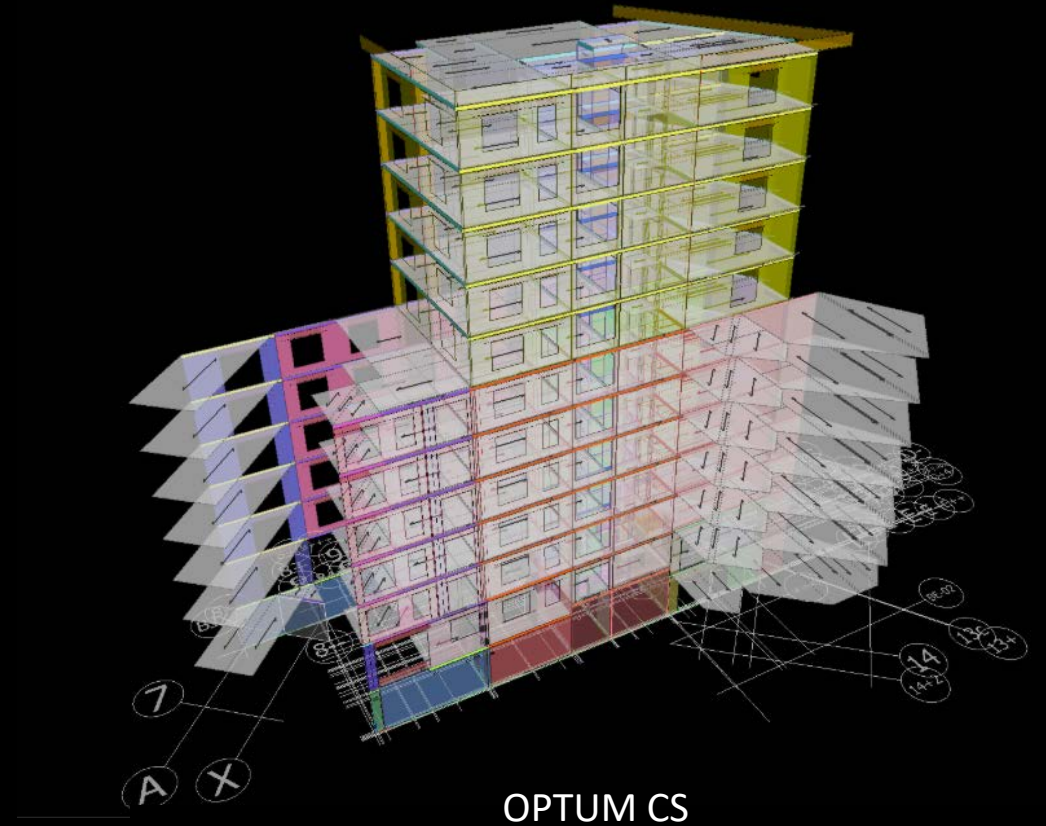






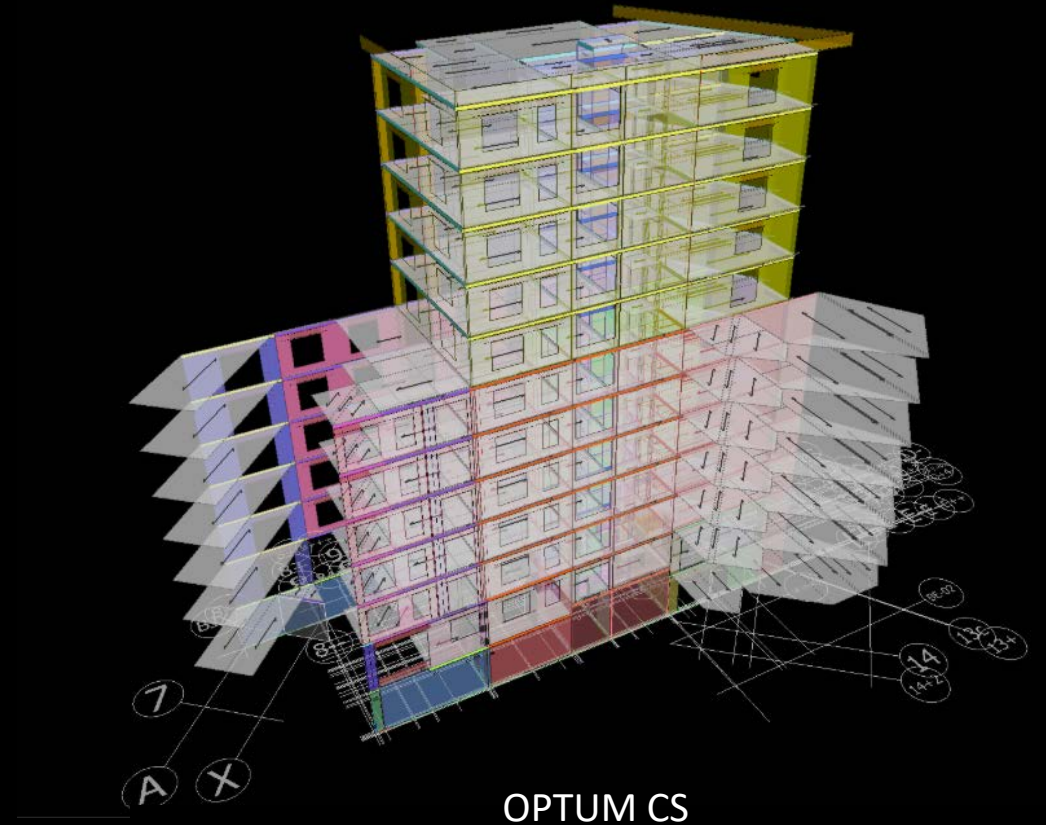
# Why 2D?

- + All other areas of engineering are in 3D by default – mechanical, aerospace, steel, concrete, etc



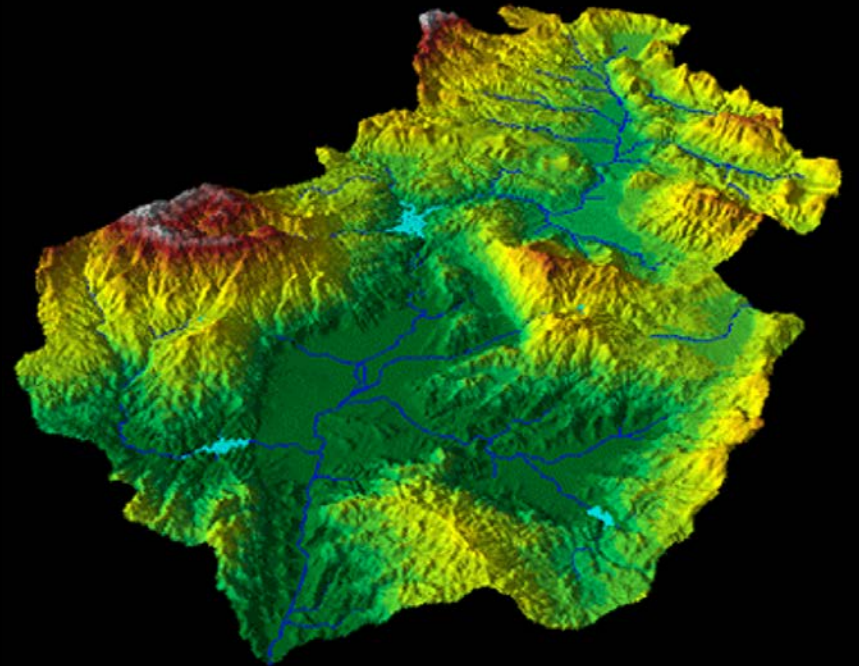
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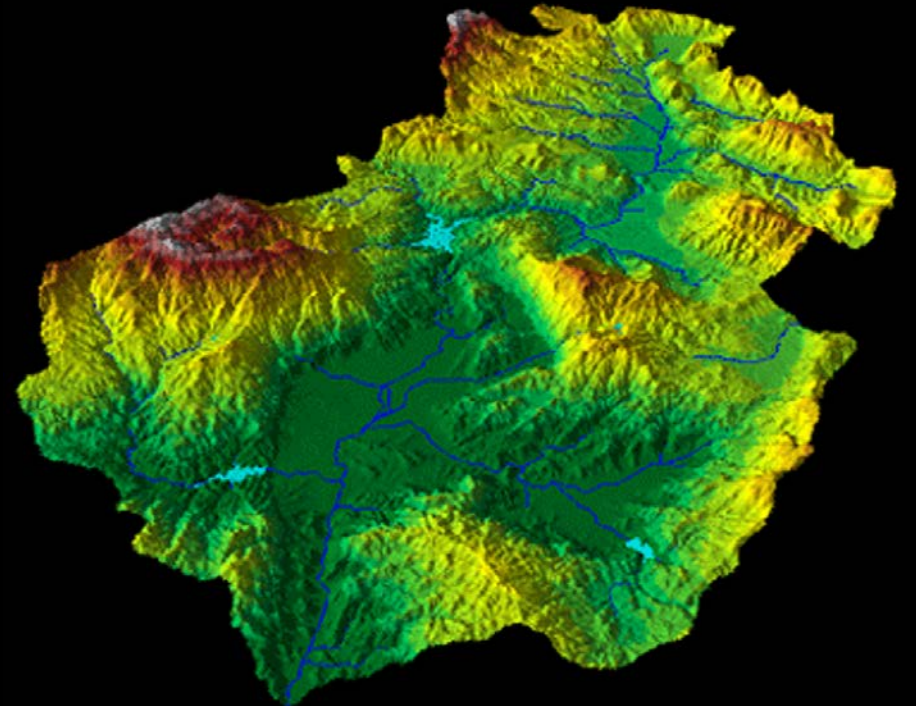
- + All other areas of engineering are in 3D by default – mechanical, aerospace, steel, concrete, etc
- + BIM is inherently 3D – whether or not the calculations are done in 3D
- + Terrain data increasingly specified in terms of Digital Elevation Models





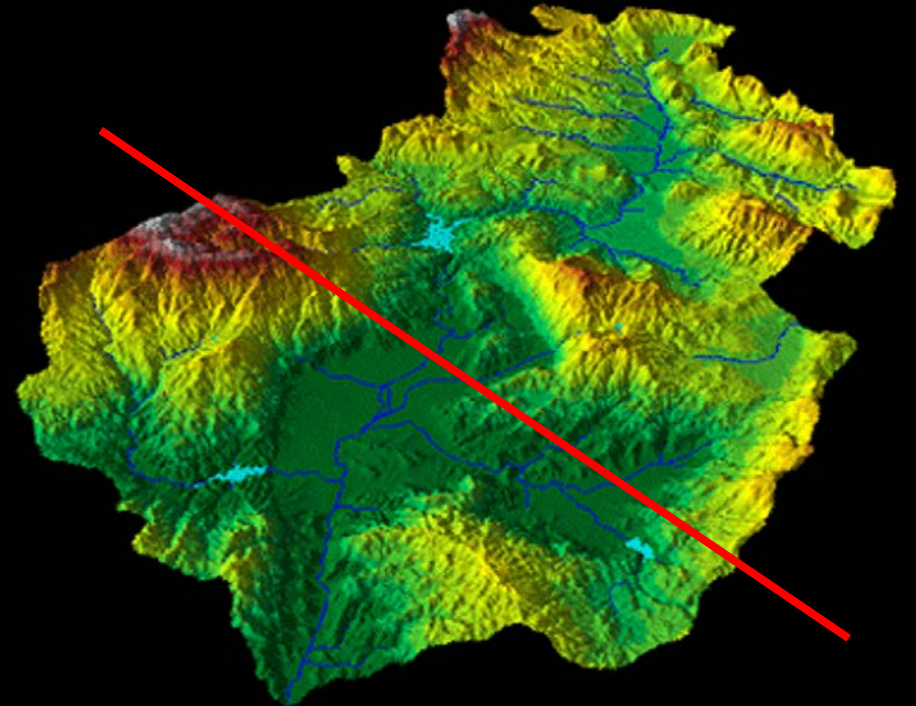
# On the other hand

- + The world is 3D *but* 2D is convenient and sometimes the only feasible approach
- + Many geotechnical problems are to a good approximation 2D
- + Common 2D/3D requirements:
  - Extrude 2D models to 3D
  - Cut through 3D models to obtain 2D sections



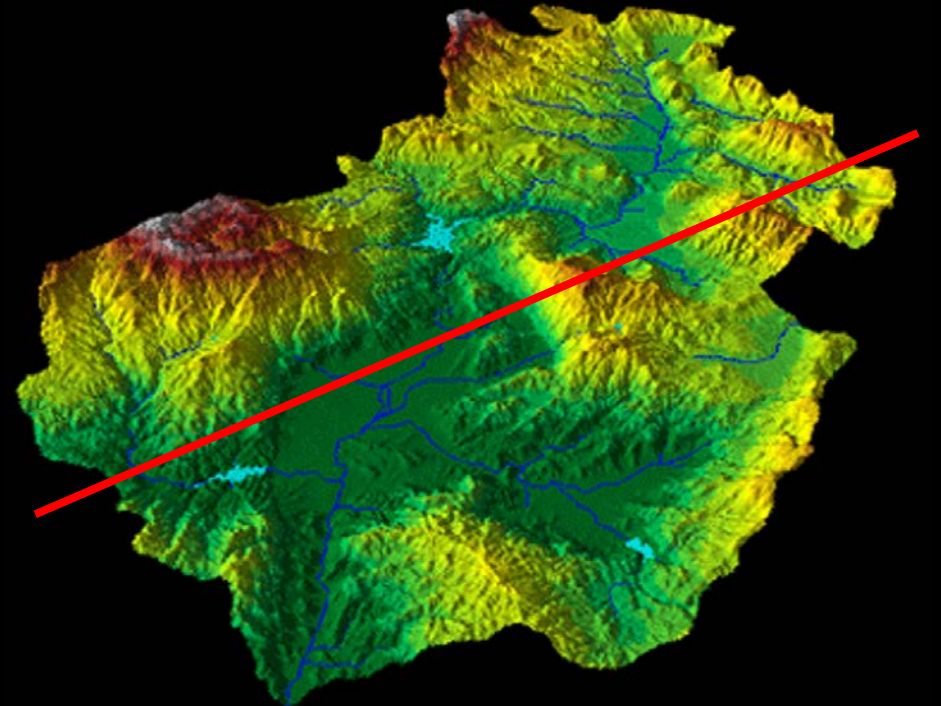
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# **Solution:**

# **Merge 2D and 3D**









Optum





**Thanks for you attention**

# Strength reduction

## Question:

How safe is the slope?



# Strength reduction

## Question:

What is the ratio between driving and resisting forces?





# Strength reduction

## Question:

By what factor should the material strength parameters be reduced to induce failure?



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By what factor should the material strength parameters be reduced to induce failure?

## Solve iteratively:

$$\begin{aligned} &\text{maximize} && 0 \\ &\text{subject to} && \mathbf{B}^T \boldsymbol{\sigma} = \mathbf{f}_0 \\ & && F(\boldsymbol{\sigma}, \text{FOS}) \leq 0 \end{aligned}$$

Feasible (stable): increase FOS

Infeasible (unstable): decrease FOS

